

A Weighted L^q -Approach to Oseen Flow Around a Rotating Body

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Abstract

We study time-periodic Oseen flows past a rotating body in \mathbb{R}^3 proving weighted *a priori* estimates in L^q -spaces using Muckenhoupt weights. After a time-dependent change of coordinates the problem is reduced to a stationary Oseen equation with the additional terms $(\omega \times x) \cdot \nabla u$ and $-\omega \wedge u$ in the equation of momentum where ω denotes the angular velocity. Due to the asymmetry of Oseen flow and to describe its wake we use anisotropic Muckenhoupt weights, a weighted theory of Littlewood-Paley decomposition and of maximal operators as well as one-sided univariate weights, one-sided maximal operators and a new version of Jones' factorization theorem.

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1 Introduction

We consider a three-dimensional rigid body $K \subset \subset \mathbb{R}^3$ rotating with angular velocity $\omega = \tilde{\omega}(0, 0, 1)^T$, $\tilde{\omega} \neq 0$, and assume that the complement $\mathbb{R}^3 \setminus K$

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is filled with a viscous incompressible fluid modelled by the Navier-Stokes equations. Then we will analyze the viscous flow either past the rotating body K with velocity $u_\infty = ke_3 \neq 0$ at infinity or around a rotating body K which is moving in the direction of its axis of rotation. Given the coefficient of viscosity $\nu > 0$ and an external force $\tilde{f} = \tilde{f}(y, t)$, we are looking for the velocity $v = v(y, t)$ and the pressure $q = q(y, t)$ solving the nonlinear system

$$\begin{aligned}
v_t - \nu \Delta v + v \cdot \nabla v + \nabla q &= \tilde{f} && \text{in } \Omega(t), t > 0 \\
\operatorname{div} v &= 0 && \text{in } \Omega(t), t > 0 \\
v(y, t) &= \omega \wedge y && \text{on } \partial\Omega(t), t > 0 \\
v(y, t) &\rightarrow u_\infty \neq 0 && \text{as } |y| \rightarrow \infty.
\end{aligned} \tag{1.1}$$

Here the time-dependent exterior domain $\Omega(t)$ is given - due to the rotation with angular velocity ω - by

$$\Omega(t) = O_\omega(t)\Omega$$

where $\Omega \subset \mathbb{R}^3$ is a fixed exterior domain and $O_\omega(t)$ denotes the orthogonal matrix

$$O_\omega(t) = \begin{pmatrix} \cos \tilde{\omega}t & -\sin \tilde{\omega}t & 0 \\ \sin \tilde{\omega}t & \cos \tilde{\omega}t & 0 \\ 0 & 0 & 1 \end{pmatrix}. \tag{1.2}$$

Introducing the change of variables and the new functions

$$x = O_\omega(t)^T y \quad \text{and} \quad u(x, t) = O_{\omega(t)}^T (v(y, t) - u_\infty), \quad p(x, t) = q(y, t), \tag{1.3}$$

respectively, as well as the force term $f(x, t) = O(t)^T \tilde{f}(y, t)$ we arrive at the modified Navier-Stokes system

$$\begin{aligned}
u_t - \nu \Delta u + u \cdot \nabla u + k \partial_3 u \\
-(\omega \wedge x) \cdot \nabla u + \omega \wedge u + \nabla p &= f && \text{in } \Omega \times (0, \infty) \\
\operatorname{div} u &= 0 && \text{in } \Omega \times (0, \infty) \\
u(x, t) &\rightarrow 0 && \text{as } |x| \rightarrow \infty
\end{aligned} \tag{1.4}$$

with boundary condition $u(x, t) = \omega \wedge x - u_\infty$ on $\partial\Omega$ in the exterior time-independent domain Ω .

Due to the new coordinate system attached to the rotating body the nonlinear system (1.4) contains two new linear terms, the classical Coriolis

force term $\omega \wedge u$ (up to a multiplicative constant) and the term $(\omega \wedge x) \cdot \nabla u$ which is *not* subordinate to the Laplacian in unbounded domains. Linearizing (1.4) in u at $u \equiv 0$ and considering only the stationary problem we arrive at the modified Oseen system

$$\begin{aligned} -\nu \Delta u + k \partial_3 u - (\omega \wedge x) \cdot \nabla u + \omega \wedge u + \nabla p &= f & \text{in } \Omega \\ \operatorname{div} u &= 0 & \text{in } \Omega \\ u &\rightarrow 0 & \text{at } \infty \end{aligned} \quad (1.5)$$

together with the boundary condition $u(x, t) = \omega \wedge x - u_\infty$ on $\partial\Omega$. Note that there is no boundary condition in the case $\Omega = \mathbb{R}^3$.

The linear system (1.5) has been analyzed in classical L^q -spaces, $1 < q < \infty$, for the whole space case in [3], [4] proving the *a priori*-estimate

$$\begin{aligned} \|\nu \nabla^2 u\|_q + \|\nabla p\|_q &\leq c \|f\|_q, \\ \|k \partial_3 u\|_q + \|(\omega \wedge x) \cdot \nabla u + \omega \wedge u\|_q &\leq c \left(1 + \frac{k^4}{\nu^2 |\omega|^2}\right) \|f\|_q \end{aligned} \quad (1.6)$$

with a constant $c > 0$ independent of ν , k and ω . For a discussion of weak solutions we refer to [14], [15]; the spectrum of the linear operator defined by (1.5) is considered in [8]. The corresponding case when $u_\infty = 0$ has recently been analyzed in [5]–[7], [11], [12], [19]–[21]. For a more comprehensive introduction including physical considerations and non-Newtonian fluids we refer to [9].

The aim of this paper is to generalize the *a priori*-estimate (1.6) to weighted L^q -spaces for the whole space \mathbb{R}^3 . For this reason we introduce the weighted Lebesgue space

$$L_w^q(\mathbb{R}^3) = L_w^q = \left\{ u \in L_{\text{loc}}^1(\mathbb{R}^3) : \|u\|_{q,w} = \left(\int_{\mathbb{R}^n} |u(x)|^q w(x) dx \right)^{1/q} < \infty \right\},$$

where $w \in L_{\text{loc}}^1$ is a nonnegative weight function and should reflect the anisotropy of the flow and the existence of a wake region in the downstream direction $x_3 > 0$. Our tools will include Littlewood-Paley theory, singular integral operators, multiplier operators and maximal operators in weighted spaces so that we need weight functions satisfying Muckenhoupt type conditions. For a totally different approach using variational methods see [13].

Definition 1.1. Let \mathcal{R} be a collection of bounded sets R in \mathbb{R}^n , each of positive Lebesgue measure $|R|$. A weight function $0 \leq w \in L_{\text{loc}}^1$ belongs to

the *Muckenhoupt class* $A_q(\mathcal{R}) = A_q(\mathbb{R}^n, \mathcal{R})$, $1 \leq q < \infty$, if there exists a constant $C > 0$ such that

$$\sup_R \left(\frac{1}{|R|} \int_R w(x) dx \right) \left(\frac{1}{|R|} \int_R w^{-1/(q-1)} dx \right)^{q-1} \leq C \quad \text{for any } R \in \mathcal{R}$$

if $1 < q < \infty$, and

$$\sup_{R \in \mathcal{R}, R \ni x_0} \frac{1}{|R|} \int_R w(x) dx \leq Cw(x_0) \quad \text{for a.a. } x_0 \in \mathbb{R}^n,$$

if $q = 1$, respectively.

Due to the anisotropic nature of our problem we shall need a variant of the classical Muckenhoupt class $A_q(\mathcal{C}) = A_q(\mathbb{R}^3, \mathcal{C})$, where \mathcal{C} is the set of all cubes $Q \subset \mathbb{R}^3$ with edges parallel to the coordinate axes. Namely, \mathcal{C} is replaced by \mathcal{J} , the set of all bounded intervals (rectangles) in \mathbb{R}^3 , leading to the class $A_q(\mathcal{J}) = A_q(\mathbb{R}^3, \mathcal{J})$. Obviously, $A_q(\mathbb{R}^3, \mathcal{J}) \subsetneq A_q(\mathbb{R}^3, \mathcal{C})$.

Moreover, to describe the anisotropy of the wake region more precisely by weights we have to introduce in addition to the weights on \mathbb{R}^n *one-sided Muckenhoupt weights* and *one-sided maximal operators* on the real line, see Definition 1.2, Theorem 2.3 and Lemma 2.4 below.

Definition 1.2. (i) For every locally integrable function u on the real line let M^+u be defined by

$$M^+u(x) = \sup_{h>0} \frac{1}{h} \int_x^{x+h} |u(t)| dt.$$

Analogously,

$$M^-u(x) = \sup_{h>0} \frac{1}{h} \int_{x-h}^x |u(t)| dt.$$

(ii) A weight function $0 \leq w \in L_{\text{loc}}^1(\mathbb{R})$ lies in the *weight class* A_1^- if there exists a constant $c > 0$ such that $M^+w(x) \leq cw(x)$ for almost all $x \in \mathbb{R}$. Analogously, $w \in A_1^+$ if and only if $M^-w(x) \leq cw(x)$ for almost all $x \in \mathbb{R}$. The smallest constant $c \geq 0$ satisfying $M^\pm w(x) \leq cw(x)$ for almost all $x \in \mathbb{R}$ is called the A_1^\mp -*constant* of w .

(iii) A weight function $0 \leq w \in L_{\text{loc}}^1$ belongs to the *one-sided Muckenhoupt class* A_q^+ , $1 < q < \infty$, if there exists a constant $C > 0$ such that for all $x \in \mathbb{R}$

$$\sup_{h>0} \left(\frac{1}{h} \int_{x-h}^x w(t) dt \right) \left(\frac{1}{h} \int_x^{x+h} w(t)^{-1/(q-1)} dt \right)^{q-1} \leq C.$$

The smallest constant $C \geq 0$ satisfying this estimate is called the A_q^+ -constant of w . By analogy, we define the set of weights A_q^- and the A_q^- -constant of a weight in A_q^- .

Now we are in a position to describe the most general weights considered in this paper. Note that these weights are independent of the angular variable θ in the cylindrical coordinate system $(r, \theta, x_3) \in [0, \infty) \times [0, 2\pi] \times \mathbb{R}$ attached to the axis of revolution $e_3 = (0, 0, 1)^T$. Hence we will write $w(x) = w(x_1, x_2, x_3) = w_r(x_3)$ for $r = |(x_1, x_2)|$, $x = (x_1, x_2, x_3)$.

Definition 1.3. For $1 \leq q < \infty$ let

$$\begin{aligned} \tilde{A}_q^- = \tilde{A}_q^-(\mathbb{R}^3) &= \{w \in A_q(\mathbb{R}^3) : w \text{ is } \theta\text{-independent for a.a. } r > 0, \\ &w(x_1, x_2, \cdot) = w_r(\cdot) \in A_q^-(\mathbb{R}) \\ &\text{with } A_q^-(\mathbb{R})\text{-constant essentially bounded in } r\}. \end{aligned} \quad (1.7)$$

Theorem 1.4. Let the weight function $0 \leq w \in L_{\text{loc}}^1(\mathbb{R}^3)$ be independent of the angular variable θ and satisfy the following condition depending on $q \in (1, \infty)$:

$$\begin{aligned} 2 \leq q < \infty : \quad w^\tau &\in \tilde{A}_{\tau q/2}^- \quad \text{for some } \tau \in [1, \infty) \\ 1 < q < 2 : \quad w^\tau &\in \tilde{A}_{\tau q/2}^- \quad \text{for some } \tau \in \left(\frac{2}{q}, \frac{2}{2-q}\right]. \end{aligned} \quad (1.8)$$

(i) Given $f \in L_w^q(\mathbb{R}^3)^3$ there exists a solution $(u, p) \in L_{\text{loc}}^1(\mathbb{R}^3)^3 \times L_{\text{loc}}^1(\mathbb{R}^3)$ of (1.5) satisfying the estimate

$$\|\nu \nabla^2 u\|_{q,w} + \|\nabla p\|_{q,w} \leq c \|f\|_{q,w}, \quad (1.9)$$

with a constant $c = c(q, w) > 0$ independent of ν , k and ω .

(ii) Let $f \in L_{w_1}^{q_1}(\mathbb{R}^3)^3 \cap L_{w_2}^{q_2}(\mathbb{R}^3)^3$ such that both (q_1, w_1) and (q_2, w_2) satisfy the conditions (1.8), and let $u_1, u_2 \in L_{\text{loc}}^1(\mathbb{R}^3)^3$ together with corresponding pressure functions $p_1, p_2 \in L_{\text{loc}}^1(\mathbb{R}^3)$ be solutions of (1.5) satisfying (1.9) for (q_1, w_1) and (q_2, w_2) , respectively. Then there are $\alpha, \beta \in \mathbb{R}$ such that u_1 coincides with u_2 up to an affine linear field $\alpha e_3 + \beta \omega \wedge x$, $\alpha, \beta \in \mathbb{R}$.

Corollary 1.5. Let the weight function $0 \leq w \in L_{\text{loc}}^1(\mathbb{R}^3)$ be independent of the angular variable θ . Moreover, let w satisfy the following condition depending on $q \in (1, \infty)$:

$$\begin{aligned} 2 \leq q < \infty : \quad w^\tau &\in \tilde{A}_{\tau q/2}^-(\mathcal{J}) \quad \text{for some } \tau \in [1, \infty) \\ 1 < q < 2 : \quad w^\tau &\in \tilde{A}_{\tau q/2}^-(\mathcal{J}) \quad \text{for some } \tau \in \left(\frac{2}{q}, \frac{2}{2-q}\right] \end{aligned} \quad (1.10)$$

where the weight class $\tilde{A}_\tau^-(\mathcal{J})$, $1 \leq \tau < \infty$, is defined by

$$\tilde{A}_\tau^-(\mathcal{J}) = \tilde{A}_\tau^-(\mathbb{R}^3) \cap A_\tau(\mathcal{J}).$$

Given $f \in L_w^q(\mathbb{R}^3)^3$ there exists a solution $(u, p) \in L_{\text{loc}}^1(\mathbb{R}^3)^3 \times L_{\text{loc}}^1(\mathbb{R}^3)$ of (1.5) satisfying the estimate

$$\|k\partial_3 u\|_{q,w} + \|(\omega \wedge x) \cdot u - \omega \wedge u\|_{q,w} \leq c \left(1 + \frac{k^5}{\nu^{5/2}|\omega|^{5/2}} \right) \|f\|_{q,w} \quad (1.11)$$

with a constant $c = c(q, w) > 0$ independent of ν , k and ω .

We remark that the ω -dependent term $1 + \frac{k^5}{\nu^{5/2}|\omega|^{5/2}}$ in (1.11) cannot be avoided in general; see [4] for an example in the space $L^2(\mathbb{R}^3)$.

As an example of anisotropic weight functions we consider

$$w(x) = \eta_\beta^\alpha(x) = (1 + |x|)^\alpha (1 + s(x))^\beta, \quad s(x) = |(x_1, x_2, x_3)| - x_3, \quad (1.12)$$

introduced in [2] to analyze the Oseen equations; see also [13]–[14].

Corollary 1.6. *The a priori estimate (1.9) holds for the anisotropic weights $w = \eta_\beta^\alpha$, see (1.12), provided that*

$$\begin{aligned} 2 \leq q < \infty & : -\frac{q}{2} < \alpha < \frac{q}{2}, \quad 0 \leq \beta < \frac{q}{2} \quad \text{and} \quad \alpha + \beta > -1 \\ 1 < q < 2 & : -\frac{q}{2} < \alpha < q - 1, \quad 0 \leq \beta < q - 1 \quad \text{and} \quad \alpha + \beta > -\frac{q}{2}. \end{aligned}$$

Note that the condition $\beta \geq 0$ will reflect the existence of a wake region in the downstream direction $x_3 > 0$ where the solution of the original nonlinear problem (1.1) will decay slower than in the upstream direction $x_3 < 0$.

2 Preliminaries

To prove Theorem 1.4 we need several properties of Muckenhoupt weights and of maximal operators. Recall that \mathcal{J} stands for the set of all nondegenerate rectangles in \mathbb{R}^n with edges parallel to the coordinate axes.

Proposition 2.1. (1) *Let μ be a nonnegative regular Borel measure such that the strong centered Hardy-Littlewood maximal operator*

$$\mathcal{M}_{\mathcal{J}}\mu(x) = \sup_{R \in \mathcal{J}, R \ni x} \frac{1}{|R|} \int_R d\mu$$

is finite for almost all $x \in \mathbb{R}^n$; here R runs through the collection \mathcal{J} of rectangles containing additionally the point x , and $|R|$ denotes the Lebesgue measure of R . Then $(\mathcal{M}_{\mathcal{J}}\mu)^\gamma \in A_1(\mathcal{J})$ for all $\gamma \in [0, 1)$.

(2) For all $1 < q < \tau$ we have $A_1(\mathcal{J}) \subset A_q(\mathcal{J}) \subset A_\tau(\mathcal{J})$.

(3) Let $1 < q < \infty$ and $w \in A_q(\mathcal{J})$. Then there are $w_1, w_2 \in A_1(\mathcal{J})$ such that

$$w = \frac{w_1}{w_2^{q-1}}.$$

Conversely, given $w_1, w_2 \in A_1(\mathcal{J})$, the weight $w = w_1 w_2^{1-q}$ belongs to $A_q(\mathcal{J})$.

For the proofs see [10, Chapter IV, §6]. The claim (3) is a variant of Jones' factorization theorem, see [10, Chapter IV, Theorem 6.8].

For a rapidly decreasing function $u \in \mathcal{S}(\mathbb{R}^n)$ let

$$\mathcal{F}u(\xi) = \hat{u}(\xi) = \frac{1}{(2\pi)^{n/2}} \int_{\mathbb{R}^n} e^{-ix \cdot \xi} u(x) dx, \quad \xi \in \mathbb{R}^n,$$

be the Fourier transform of u . Its inverse will be denoted by \mathcal{F}^{-1} . Moreover, we define the centered Hardy-Littlewood maximal operator

$$\mathcal{M}u(x) = \sup_{Q \ni x} \frac{1}{|Q|} \int_Q |u(y)| dy, \quad x \in \mathbb{R}^n,$$

for $u \in L^1_{\text{loc}}(\mathbb{R}^n)$ where Q runs through the set of all closed cubes centered at x .

Theorem 2.2. *Let $1 < q < \infty$ and $w \in A_q$.*

(i) *The operator \mathcal{M} , defined e.g. on $\mathcal{S}(\mathbb{R}^n)$, is a bounded operator from L^q_w to L^q_w .*

(ii) *Let $m \in C^n(\mathbb{R}^n \setminus \{0\})$ satisfy the pointwise Hörmander-Mikhlin multiplier condition*

$$|\xi^{|\alpha|} |D^\alpha m(\xi)| \leq c_\alpha \quad \text{for all } \xi \in \mathbb{R}^n \setminus \{0\}$$

and all multiindices $\alpha \in \mathbb{N}_0^n$ with $|\alpha| \leq n_1 \in \mathbb{N}$, where $n_1 \geq n/2$. Then the multiplier operator $u \mapsto \mathcal{F}^{-1}(m\hat{u})$, $u \in \mathcal{S}(\mathbb{R}^n)$, can be extended to a bounded linear operator from L^q_w to L^q_w .

(iii) *Let m be of class C^n in each "quadrant" of \mathbb{R}^n and let a constant $B \geq 0$ exist such that $\|m\|_\infty \leq B$,*

$$\sup_{x_{k+1}, \dots, x_n} \int_{\mathcal{I}} \left| \frac{\partial^k m(x)}{\partial x_1 \cdots \partial x_k} \right| dx_1 \cdots dx_k \leq B$$

for any dyadic interval \mathcal{I} in \mathbb{R}^k , $1 \leq k \leq n$, and also for any permutation of the variables x_1, \dots, x_k within x_1, \dots, x_n . If $1 < p < \infty$ and $w \in A_p(\mathbb{R}^n, \mathcal{J})$, then m defines a bounded multiplier operator from $L_w^p(\mathbb{R}^n)$ to $L_w^p(\mathbb{R}^n)$.

Proof. (i) See [10, Theorem IV 2.8], [18, Theorem 9]. (ii) See [10, Theorem IV 3.9] or [17, Theorem 4]. Note that the pointwise condition on m implies the integral condition in [10], [17]. For the proof of (iii) see [17]. \blacksquare

Concerning *one-sided weights* and *one-sided maximal operators* on the real line, see Definition 1.2, we first recall the following duality property: $w \in A_q^+$ if and only if $w^{-q'/q} = w^{-1/(q-1)} \in A_q^-$. Moreover we will need the following results:

Theorem 2.3 (Theorem 1 of [23]). *Let $1 < p < \infty$ and $p' = \frac{p}{p-1}$.*

(i) *Let $w_1 \in A_1^+$, $w_2 \in A_1^-$. Then $\frac{w_1}{w_2^{p-1}} \in A_p^+$. Conversely, given $w \in A_p^+$ there exist $w_1 \in A_1^+$, $w_2 \in A_1^-$ such that $w = \frac{w_1}{w_2^{p-1}}$.*

(ii) *The operator M^+ is continuous from $L_w^p(\mathbb{R})$ to itself if and only if $w \in A_p^+$. Analogously, $M^- : L_w^p(\mathbb{R}) \rightarrow L_w^p(\mathbb{R})$ if and only if $w \in A_p^-$.*

Obviously, $A_p \subset A_p^\pm$ where A_p denotes the usual Muckenhoupt class on the real line. Hence $|x|^\alpha, (1 + |x|)^\alpha \in A_p^\pm$ if $-1 < \alpha < p - 1$, $1 < p < \infty$. However, in view of the anisotropic weight $w = \eta_\beta^\alpha$ on \mathbb{R}^3 , see (1.12), we have to consider also one-dimensional anisotropic weight functions such as

$$\tilde{w}_{\alpha,\beta}(x) = \tilde{w}_{\alpha,\beta}(x; r) = (r^2 + x^2)^{\alpha/2} (\sqrt{r^2 + x^2} - x)^\beta, \quad x \in \mathbb{R}, r > 0. \quad (2.1)$$

Lemma 2.4. (i) *For every $r > 0$ the univariate weight $\tilde{w}_{\alpha,\beta}(x; r)$ lies in A_1^- if and only if $\beta \geq 0$, $\alpha \leq \beta$ and $\alpha + \beta > -1$. Moreover, the A_1^- -constant of $\tilde{w}_{\alpha,\beta}$ is uniformly bounded in r .*

(ii) *For every $r > 0$ the univariate weight*

$$w_{\alpha,\beta}(x) = w_{\alpha,\beta}(x; r) = (1 + r^2 + x^2)^{\alpha/2} (1 + \sqrt{r^2 + x^2} - x)^\beta$$

lies in A_1^- with an A_1^- -constant independent of $r > 0$ if and only if

$$\alpha \leq 0 \leq \beta \text{ and } \alpha + \beta > -1. \quad (2.2)$$

(iii) *Let $1 < p < \infty$. Then for every $r > 0$*

$$\begin{aligned} w_{\alpha,\beta}(\cdot; r) &\in A_p^+ \quad \text{for } \alpha > -1, \quad \beta \leq 0, \quad \alpha + \beta < p - 1 \\ w_{\alpha,\beta}(\cdot; r) &\in A_p^- \quad \text{for } \alpha < p - 1, \quad \beta \geq 0, \quad \alpha + \beta > -1. \end{aligned} \quad (2.3)$$

Moreover, the A_p^\pm -constant is uniformly bounded in $r > 0$.

Proof. (i) A simple scaling argument shows that it suffices to look at the weight $\tilde{w} = \tilde{w}_{\alpha,\beta}$ in (2.1) for $r = 1$ only and that the A_1^- -constant is independent of $r > 0$. We will consider three cases.

Case 1: $x > 0$. Then $\tilde{w}(x) \sim (1 + |x|)^{\alpha-\beta}$, i.e., there exists a constant $c > 0$ independent of $x > 0$ such that $\frac{1}{c}(1 + |x|)^{\alpha-\beta} \leq \tilde{w}(x) \leq c(1 + |x|)^{\alpha-\beta}$ for all $x > 0$. Hence for all $h > 0$

$$\frac{1}{h} \int_x^{x+h} \tilde{w}(t) dt \sim \frac{1}{h} \int_x^{x+h} (1+t)^{\alpha-\beta} dt.$$

If $\alpha - \beta > 0$, then the term on the right hand-side is strictly increasing to $+\infty$ as $h \rightarrow \infty$. Thus we are led to the condition $\alpha \leq \beta$.

Now let $\alpha \leq \beta$. Then for all $h > 0$

$$\frac{1}{h} \int_x^{x+h} (1+t)^{\alpha-\beta} dt \leq \frac{1}{h} \int_x^{x+h} (1+x)^{\alpha-\beta} dt = (1+|x|)^{\alpha-\beta} \sim \tilde{w}(x).$$

Case 2: $x < 0$ and $0 < h < |x|$. Then $\tilde{w}(t) \sim (1+|t|)^{\alpha+\beta}$ for all $t \in (x, x+h)$. Assume that $\alpha + \beta = -1$ and let $h = |x|$. Then

$$\frac{1}{|x|} \int_x^0 (1+|t|)^{-1} dt = \frac{\log(1+|x|)}{|x|}$$

is not bounded by $c\tilde{w}(x) = c/|x|$ uniformly in $x < 0$ for any constant $c > 0$. Analogously, if $\alpha + \beta < -1$, then for $h = |x|$ we see that $\frac{1}{|x|} \int_x^0 (1+|t|)^{\alpha+\beta} dt \sim \frac{1}{|x|}$ is not bounded by $c\tilde{w}(x) = c(1+|x|)^{\alpha+\beta}$ uniformly in $x < 0$. Hence in the following we have to assume that $\alpha + \beta > -1$. We shall consider two subcases: $h > 0$ small with respect to $|x|$ and h comparable with $|x|$. If $0 < h < \frac{|x|}{2}$, then

$$\frac{1}{h} \int_x^{x+h} (1+|t|)^{\alpha+\beta} dt \sim \frac{1}{h} \int_x^{x+h} (1+|x|)^{\alpha+\beta} dt = (1+|x|)^{\alpha+\beta} \sim \tilde{w}(x).$$

For the second subcase assume that $\frac{|x|}{2} < h < |x|$. Then we are led to the integral

$$\begin{aligned} & \frac{1}{|x|} \int_x^{x+h} (1+|t|)^{\alpha+\beta} dt \\ & \leq \frac{1}{|x|} \int_x^0 (1+|t|)^{\alpha+\beta} dt \sim \begin{cases} \frac{(1+|x|)^{\alpha+\beta+1}}{|x|}, & |x| > 1 \\ 1, & |x| < 1 \end{cases} \sim \tilde{w}(x). \end{aligned}$$

Case 3: $x < 0$ and $h > |x|$. In this case we have to consider the sum

$$\frac{1}{h} \int_x^0 \tilde{w} dt + \frac{1}{h} \int_0^{x+h} \tilde{w} dt \leq \frac{1}{|x|} \int_x^0 \tilde{w} dt + \frac{c}{h} \int_0^{x+h} (1+t)^{\alpha-\beta} dt =: I_1 + I_2,$$

where the first integral I_1 is bounded by $c\tilde{w}(x)$ uniformly in $x < 0$, see *Case 2*, and where for $|x| < 1$ the second integral I_2 is bounded by $c \sim \tilde{w}(x)$. Therefore, let $|x| > 1$ in the following. If $\alpha - \beta \leq -1$, then the condition $\alpha + \beta > -1$ implies that $\beta > 0$; moreover, I_2 is easily shown to be bounded by $c\tilde{w}(x) \sim (1+|x|)^{\alpha+\beta}$ uniformly in $x < 0$ and $h > |x|$.

Now consider the case $\alpha - \beta > -1$. We shall investigate three possibilities of the position of h with respect to $|x|$. If $h = 2|x|$, then

$$\frac{1}{|x|} \int_0^{|x|} (1+t)^{\alpha-\beta} dt = \frac{c}{|x|} ((1+|x|)^{\alpha-\beta+1} - 1).$$

Since $\frac{1}{|x|} = o(|x|^{\alpha+\beta}) = o(\tilde{w}(x))$ by the condition that $\alpha + \beta > -1$, the assertion $I_2 \leq c\tilde{w}(x) \sim |x|^{\alpha+\beta}$ necessarily implies that $|x|^{\alpha-\beta} \leq c|x|^{\alpha+\beta}$ for $|x| > 1$. Thus β must be nonnegative.

Next, if $|x| < h < 2|x|$, then, since $\alpha - \beta \leq \alpha + \beta$ and $\alpha + \beta > -1$,

$$I_2 \leq \frac{c}{|x|} \int_0^{|x|} (1+t)^{\alpha-\beta} dt \leq c|x|^{\alpha+\beta} \sim \tilde{w}(x).$$

Finally, if $h > 2|x| > 2$, then

$$I_2 \leq \frac{c}{h} (1+x+h)^{\alpha-\beta+1} \leq ch^{\alpha-\beta} \leq c|x|^{\alpha+\beta} \sim \tilde{w}(x)$$

since $\alpha \leq \beta$ (see *Case 1*). Summarizing the previous cases and estimates we have proved that there exists $c > 0$ such that $M^+\tilde{w}(x) \leq c\tilde{w}(x)$ for a.a. $x \in \mathbb{R}$, and that this results holds if and only if $\beta \geq 0$, $\alpha \leq \beta$, and $\alpha + \beta > -1$.

(ii) To verify the necessity of (2.2) let $r = 1$ and $w = w_{\alpha,\beta}$. For $x > 0$ when $(1 + \sqrt{r^2 + x^2} - x)^\beta \sim 1$, we have to estimate

$$\frac{1}{h} \int_x^{x+h} w(t) dt \sim \frac{1}{h} \int_x^{x+h} (1+t)^\alpha dt$$

by $cw(x) \sim (1+x)^\alpha$. As in *Case 1* of Part (i) (with $\beta = 0$) we get the necessary condition $\alpha \leq 0$.

Let $x < 0$. Again we shall distinguish according to the size of h with respect to $|x|$. If $0 < h < |x|$, then $w(t) \sim (1 + |t|)^{\alpha+\beta}$ for all $t \in (x, x+h)$, and

$$\frac{1}{h} \int_x^{x+h} w(t) dt \sim \frac{1}{h} \int_x^{x+h} (1 + |t|)^{\alpha+\beta} dt$$

is bounded by $cw(x) \sim (1 + |x|)^{\alpha+\beta}$ only when $\alpha + \beta > -1$; cf. *Case 2* of Part (i). Finally, when $x < 0$ and $h > |x|$, say $h = 2|x| > 2$, and when $\alpha > -1$, then

$$\frac{1}{h} \int_x^{x+h} w(t) dt \sim \frac{1}{h} \int_x^0 (1 + |t|)^{\alpha+\beta} dt + \frac{1}{h} \int_0^{x+h} (1 + t)^\alpha dt \leq cw(x) + c|x|^\alpha,$$

which is bounded by $cw(x) \sim (1 + |x|)^{\alpha+\beta}$ only if $\beta \geq 0$. However, if $\alpha \leq -1$, then the condition $\alpha + \beta > -1$ implies that even $\beta > 0$. Hence the conditions (2.2) are necessary to prove that $w \in A_1^-$.

We shall prove that conditions (2.2) are sufficient for $w_{\alpha,\beta}(x;r) \in A_1^-$ with an A_1^- -constant independent of $r > 0$. Let us assume that (2.2) holds and let first $0 < r < 1$. Then

$$\begin{aligned} w(t) &\sim (1 + |t|)^\alpha \cdot \begin{cases} 1, & t > 0 \\ (1 + |t|)^\beta, & t < 0 \end{cases} \\ &\sim (1 + |t|)^{\alpha+\beta/2} \cdot \begin{cases} (1 + |t|)^{-\beta/2}, & t > 0 \\ (1 + |t|)^{\beta/2}, & t < 0 \end{cases} \sim \tilde{w}_{\alpha',\beta'}(t;r) \end{aligned}$$

where $\alpha' = \alpha + \beta/2$, $\beta' = \beta/2$. Since the assumptions (2.2) on α, β imply that α', β' satisfy the assumptions in (i), $w \in A_1^-$ with an A_1^- -constant independent of $0 < r < 1$.

Next let $r \geq 1$. An elementary calculation shows that

$$w(t) \sim \begin{cases} \tilde{w}_{\alpha,\beta}(t;r), & t < r^2 \\ \tilde{w}_{\alpha,0}(t;r), & t > r^2 \end{cases}.$$

Then we will consider three cases.

Case 1: $x < r^2$ and $x+h < r^2$. In this case, by Part (i),

$$\frac{1}{h} \int_x^{x+h} w(t) dt \sim \frac{1}{h} \int_x^{x+h} \tilde{w}_{\alpha,\beta}(t;r) dt \leq c\tilde{w}_{\alpha,\beta}(x;r) \sim cw(x)$$

with $c > 0$ independent of $r > 1$.

Case 2: $x > r^2$ and $x + h > r^2$. Now

$$\frac{1}{h} \int_x^{x+h} w(t) dt \sim \frac{1}{h} \int_x^{x+h} \tilde{w}_{\alpha,0}(t; r) dt \leq c\tilde{w}_{\alpha,0}(x; r) \sim cw(x)$$

due to *Case 1* in Part (i).

Case 3: $x < r^2$ but $x + h > r^2$. Then

$$\frac{1}{h} \int_x^{x+h} w(t) dt \sim \frac{1}{h} \int_x^{r^2} \tilde{w}_{\alpha,\beta}(t; r) dt + \frac{1}{h} \int_{r^2}^{x+h} \tilde{w}_{\alpha,0}(t; r) dt$$

By Part (i), the first integral on the right hand side is bounded by $\frac{r^2-x}{h} \tilde{w}_{\alpha,\beta}(x; r) \leq \tilde{w}_{\alpha,\beta}(x; r) \leq cw(x)$. Hence it suffices to prove that

$$\frac{1}{h} \int_{r^2}^{x+h} \tilde{w}_{\alpha,0}(t; r) dt \leq cw(x).$$

If $|x| \leq r^2$, then Part (i) implies that

$$\frac{1}{h} \int_{r^2}^{x+h} \tilde{w}_{\alpha,0}(t; r) dt \leq \frac{x+h-r^2}{h} \tilde{w}_{\alpha,0}(r^2; r) \leq \tilde{w}_{\alpha,0}(r^2; r) \leq cr^{2\alpha}$$

where $r^{2\alpha} \leq (r+|x|)^\alpha \leq cw(x)$ since $\alpha \leq 0 \leq \beta$.

If $x < -r^2$, then $w(x) \sim |x|^{\alpha+\beta}$, and a simple scaling argument and the condition $\beta \geq 0$ allow to reduce the problem to the case $r = 1$. Actually it suffices to show the existence of $c > 0$ such that

$$J := \int_1^{x+h} t^\alpha dt \leq ch|x|^{\alpha+\beta} \quad \text{when } x \leq -1, x+h \geq 1.$$

If $\alpha < -1$, then J is bounded by $\frac{1}{|\alpha+1|} \leq c|x|^{\alpha+\beta+1} \leq ch|x|^{\alpha+\beta}$, since $\alpha + \beta > -1$ and $h > |x| > 1$. In the case $\alpha = -1$ the integral J equals

$$\log(x+h) \sim \log h + \frac{x}{h} \leq c(1 + h^{\min(\beta,1)}) \leq ch|x|^{\beta-1},$$

since $\beta > -1 - \alpha = 0$. Finally, for $\alpha > -1$, we may bound J by $c(x+h)^{\alpha+1}$. If $1 < |x| < h < 2|x|$, this term is bounded by $c|x| \leq ch|x|^\alpha \leq ch|x|^{\alpha+\beta}$. In the remaining case when $h > 2|x|$, we get that $(x+h)^{\alpha+1} \leq ch^{\alpha+1} \leq ch|x|^{\alpha+\beta}$, since $\alpha \leq 0 \leq \beta$.

Now (ii) is completely proved.

(iii) By Theorem 2.3 (i) and Part (ii) of this Lemma

$$w(x) = \frac{(1+r^2+x^2)^{\alpha_1/2}}{(1+r^2+x^2)^{\alpha_2(p-1)/2}(1+\sqrt{r^2+x^2}-x)^{\beta_2(p-1)}} \in A_p^+$$

for all $\alpha_1, \alpha_2, \beta_2$ satisfying $-1 < \alpha_1 \leq 0$, $\alpha_2 \leq 0 \leq \beta_2$ and $\alpha_2 + \beta_2 > -1$. Hence, with $\alpha = \alpha_1 - \alpha_2(p-1)$, $\beta = -\beta_2(p-1)$, we get that $w = w_{\alpha, \beta}(\cdot; r) \in A_p^+$ for all α, β satisfying $\alpha > -1$, $\beta \leq 0$, and $\alpha + \beta < p-1$. By analogy,

$$w(x) = \frac{(1+r^2+x^2)^{\alpha_1/2}(1+\sqrt{r^2+x^2}-x)^{\beta_1}}{(1+r^2+x^2)^{\alpha_2(p-1)/2}} \in A_p^-$$

for all $\alpha_1, \alpha_2, \beta_1$ satisfying $\alpha_1 \leq 0 \leq \beta_1$, $\alpha_1 + \beta_1 > -1$, $-1 < \alpha_2 \leq 0$. Hence $w = w_{\alpha, \beta}(\cdot; r) \in A_p^-$ for all α, β such that $\beta \geq 0$, $\alpha < p-1$ and $\alpha + \beta > -1$. Moreover, in both cases the A_p^\pm -constant of the weight is uniformly bounded in $r > 0$. \blacksquare

Note that the univariate weights $\tilde{w}_{\alpha, \beta}$ and $w_{\alpha, \beta}$ mainly differ for large $x > 0$. While $\tilde{w}_{0, \beta}$ decays as $(\frac{1}{x})^\beta$ as $x \rightarrow \infty$ for every fixed $r > 0$, the weight $w_{0, \beta}$ is bounded below by 1 as $x \rightarrow \infty$. The reason to consider the weights $w_{\alpha, \beta}$ rather than $\tilde{w}_{\alpha, \beta}$ is based on the use of the anisotropic weights η_β^α on \mathbb{R}^3 , see Corollary 1.5, when fixing $r = |(x_1, x_2)|$, $x_1, x_2 \in \mathbb{R}$, so that $\eta_\beta^\alpha(x_1, x_2, x_3) = w_{\alpha, \beta}(x_3; r)$.

Due to the geometry of the problem we introduce cylindrical coordinates $(r, x_3, \theta) \in (0, \infty) \times \mathbb{R} \times [0, 2\pi)$ and write $u(x_1, x_2, x_3) = u(r, x_3, \theta)$. Then the term $(e_3 \wedge x) \cdot \nabla u = -x_2 \partial_1 u + x_1 \partial_2 u$ may be rewritten in the form $(e_3 \wedge x) \cdot \nabla u = \partial_\theta u$ using the angular derivative ∂_θ applied to $u(r, x_3, \theta)$. Working first of all formally or in the space $\mathcal{S}'(\mathbb{R}^3)$ of tempered distributions we apply the Fourier transform $\mathcal{F} = \widehat{\cdot}$ to (1.5). With the Fourier variable $\xi = (\xi_1, \xi_2, \xi_3) \in \mathbb{R}^3$ and $s = |\xi|$ we get from (1.5)

$$(\nu s^2 + ik\xi_3)\widehat{u} - \tilde{\omega}(\partial_\varphi \widehat{u} - e_3 \wedge \widehat{u}) + i\xi \widehat{p} = \widehat{f}, \quad i\xi \cdot \widehat{u} = 0. \quad (2.4)$$

Here $(e_3 \wedge \xi) \cdot \nabla_\xi = -\xi_2 \partial / \partial \xi_1 + \xi_1 \partial / \partial \xi_2 = \partial_\varphi$ is the angular derivative in Fourier space when using cylindrical coordinates $(s, \xi_3, \phi, \cdot) \in \mathbb{R}_+ \times \mathbb{R} \times [0, 2\pi)$. Since $i\xi \cdot \widehat{u} = 0$ implies $i\xi \cdot (\partial_\varphi \widehat{u} - \omega \times \widehat{u}) = 0$, the unknown pressure p is given by $-|\xi|^2 \widehat{p} = i\xi \cdot \widehat{f}$, i.e.,

$$\widehat{\nabla p}(\xi) = i\xi \cdot \widehat{p} = \frac{(\xi \cdot \widehat{f})\widehat{f}}{|\xi|^2}.$$

Then the Hörmander-Mikhlin multiplier theorem on weighted L^q -spaces (Theorem 2.2 (ii)) yields for every weight $w \in A_q(\mathbb{R}^3, \mathcal{C})$ the estimate

$$\|\nabla p\|_{q,w} \leq c\|f\|_{q,w} \quad (2.5)$$

where $c = c(q, w) > 0$; in particular $\nabla p \in L_w^q$.

Hence u may be considered as a (solenoidal) solution of the reduced problem

$$-\nu\Delta u + k\partial_3 u - \tilde{\omega}(\partial_\theta u - e_3 \wedge u) = F := f - \nabla p \quad \text{in } \mathbb{R}^3, \quad (2.6)$$

or—in Fourier space—

$$(\nu s^2 + ik\xi_3)\widehat{u} - \tilde{\omega}(\partial_\varphi \widehat{u} - e_3 \wedge \widehat{u}) = \widehat{F}.$$

As shown in [Fa2] this inhomogeneous linear differential equation of first order with respect to φ has the unique 2π -periodic solution

$$\begin{aligned} \widehat{u}(\xi) &= \frac{1}{1 - e^{-2\pi(\nu|\xi|^2 + ik\xi_3)/\tilde{\omega}}} \int_0^{2\pi/\tilde{\omega}} e^{-(\nu|\xi|^2 + ik\xi_3)t} O_\omega^T(t) \mathcal{F}F(O_\omega(t)\xi) dt, \\ &= \int_0^\infty e^{-\nu|\xi|^2 t} O_\omega^T(t) (\mathcal{F}F(O_\omega(t) \cdot -kte_3))(\xi) dt. \end{aligned} \quad (2.7)$$

Finally note that $e^{-\nu|\xi|^2 t}$ is the Fourier transform of the heat kernel $E_t(x) = (4\pi\nu t)^{-3/2} e^{-|x|^2/4\nu t}$ yielding

$$u(x) = \int_0^\infty E_t * O_\omega^T(t) F(O_\omega(t) \cdot -kte_3)(x) dt. \quad (2.8)$$

Since $F = f - \nabla p$ is solenoidal, the identity $i\xi \cdot \widehat{F} = 0$ easily implies that also u is solenoidal.

The main ingredients of the proof of Theorem 1.4 are a weighted version of Littlewood-Paley theory and a decomposition of the integral operator

$$\begin{aligned} Tf(x) &= \int_0^\infty \widehat{\psi}_{\nu t}(\xi) O_\omega^T(t) \mathcal{F}f(O_\omega(t) \cdot -kte_3)(\xi) \frac{dt}{t} \\ &= \int_0^\infty \widehat{\psi}_t(\xi) O_{\omega/\nu}^T(t) \mathcal{F}f\left(O_{\omega/\nu}(t) \cdot -\frac{k}{\nu}te_3\right)(\xi) \frac{dt}{t}, \end{aligned} \quad (2.9)$$

where

$$\widehat{\psi}(\xi) = \frac{1}{(2\pi)^{3/2}} |\xi|^2 e^{-|\xi|^2} \quad \text{and} \quad \widehat{\psi}_t(\xi) = \widehat{\psi}(\sqrt{t}\xi), \quad t > 0, \quad (2.10)$$

are the Fourier transforms of the function $\psi = -\Delta E_1 \in \mathcal{S}(\mathbb{R}^3)$ and of $\psi_t(x) = t^{-3/2}\psi(x/\sqrt{t})$, $t > 0$, resp. Note that due to Theorem 1.4 it suffices to find an estimate of $\|\Delta u\|_{q,w}$ in order to estimate all second order derivatives $\partial_j \partial_k u$ of u .

To decompose $\widehat{\psi}_t$ choose $\widetilde{\chi} \in C_0^\infty(\frac{1}{2}, 2)$ satisfying $0 \leq \widetilde{\chi} \leq 1$ and $\sum_{j=-\infty}^\infty \widetilde{\chi}(2^{-j}s) = 1$ for all $s > 0$. Then define χ_j , $j \in \mathbb{Z}$, by its Fourier transform

$$\widehat{\chi}_j(\xi) = \widetilde{\chi}(2^{-j}|\xi|), \quad \xi \in \mathbb{R}^n,$$

yielding $\sum_{j=-\infty}^\infty \widehat{\chi}_j = 1$ on $\mathbb{R}^n \setminus \{0\}$ and

$$\text{supp } \widehat{\chi}_j \subset A(2^{j-1}, 2^{j+1}) := \{\xi \in \mathbb{R}^3 : 2^{j-1} \leq |\xi| \leq 2^{j+1}\}. \quad (2.11)$$

Using χ_j , we define for $j \in \mathbb{Z}$

$$\psi^j = \frac{1}{(2\pi)^{3/2}} \chi_j * \psi \quad (\widehat{\psi} = \widehat{\chi}_j \cdot \widehat{\psi}). \quad (2.12)$$

Obviously, $\sum_{j=-\infty}^\infty \psi^j = \psi$ on \mathbb{R}^3 . Finally, in view of (2.9), (2.12), we define the linear operators

$$\begin{aligned} T_j f(x) &= \int_0^\infty \widehat{\psi}_{\nu t}^j(\xi) O_\omega^T(t) \mathcal{F}f(O_\omega(t) \cdot -kte_3)(\xi) \frac{dt}{t} \\ &= \int_0^\infty \widehat{\psi}_t^j(\xi) O_{\omega/\nu}^T(t) \mathcal{F}f\left(O_{\omega/\nu}(t) \cdot -\frac{k}{\nu}te_3\right)(\xi) \frac{dt}{t}. \end{aligned} \quad (2.13)$$

Since formally $T = \sum_{j=-\infty}^\infty T_j$, we have to prove that this infinite series converges even in the operator norm on L_w^q .

For later use we cite the following lemma, see [6].

Lemma 2.5. *The functions ψ^j , ψ_t^j , $j \in \mathbb{Z}$, $t > 0$, have the following properties:*

(i) $\text{supp } \widehat{\psi}_t^j \subset A\left(\frac{2^{j-1}}{\sqrt{t}}, \frac{2^{j+1}}{\sqrt{t}}\right)$.

(ii) For $m > \frac{3}{2}$ let $h(x) = (1 + |x|^2)^{-m}$ and $h_t(x) = t^{-3/2}h(\frac{x}{\sqrt{t}})$, $t > 0$.

Then there exists a constant $c > 0$ independent of $j \in \mathbb{Z}$ such that

$$\begin{aligned} |\psi^j(x)| &\leq c 2^{-2|j|} h_{2^{-2j}}(x), \quad x \in \mathbb{R}^3, \\ \|\psi^j\|_1 &\leq c 2^{-2|j|}. \end{aligned} \quad (2.14)$$

To introduce a weighted Littlewood-Paley decomposition of L_w^q choose $\tilde{\varphi} \in C_0^\infty(\frac{1}{2}, 2)$ such that $0 \leq \tilde{\varphi} \leq 1$ and $\int_0^\infty \tilde{\varphi}(s)^2 \frac{ds}{s} = \frac{1}{2}$. Then define $\varphi \in \mathcal{S}(\mathbb{R}^3)$ by its Fourier transform $\widehat{\varphi}(\xi) = \tilde{\varphi}(|\xi|)$ yielding for every $s > 0$

$$\widehat{\varphi}_s(\xi) = \tilde{\varphi}(\sqrt{s}|\xi|), \quad \text{supp } \widehat{\varphi}_s \subset A\left(\frac{1}{2\sqrt{2}}, \frac{2}{\sqrt{2}}\right) \quad (2.15)$$

and the normalization $\int_0^\infty \widehat{\varphi}_s(\xi)^2 \frac{ds}{s} = 1$ for all $\xi \in \mathbb{R}^n \setminus \{0\}$.

Theorem 2.6. *Let $1 < q < \infty$ and $w \in A_q(\mathbb{R}^3)$. Then there are constants $c_1, c_2 > 0$ depending on q, w and φ such that for all $f \in L_w^q$*

$$c_1 \|f\|_{q,w} \leq \left\| \left(\int_0^\infty |\varphi_s * f(\cdot)|^2 \frac{ds}{s} \right)^{1/2} \right\|_{q,w} \leq c_2 \|f\|_{q,w} \quad (2.16)$$

where $\varphi_s \in \mathcal{S}(\mathbb{R}^n)$ is defined by (2.15).

Proof. See [22, Proposition 1.9, Theorem 1.10], and also [17], [24]. ■

3 Proofs

As a preliminary version of Theorem 1.4 we prove the following proposition. The extension to more general weights based on complex interpolation of L_w^q -spaces will be postponed to the end of Section 3.

Proposition 3.1. *Let the weight $w \in L_{\text{loc}}^1(\mathbb{R}^3)$ be independent of the angle θ and define $w_r(x_3) := w(x_1, x_2, x_3)$ for fixed $r = |(x_1, x_2)| > 0$. Assume that*

$$\begin{aligned} w &\in \widetilde{A}_{q/2}^- && \text{if } q > 2, \\ w &\in \widetilde{A}_1^- \text{ or } \frac{1}{w} \in \widetilde{A}_1^+ && \text{if } q = 2, \\ w^{2/(2-q)} &\in \widetilde{A}_{q/(2-q)}^- && \text{if } 1 < q < 2. \end{aligned} \quad (3.1)$$

Then the linear operator T defined by (2.9) satisfies the estimate

$$\|Tf\|_{q,w} \leq c \|f\|_{q,w} \quad \text{for all } f \in L_w^q \quad (3.2)$$

with a constant $c = c(q, w) > 0$ independent of f .

Proof. Step 1. First we consider the case $q > 2$, $w \in \tilde{A}_{q/2}^- \subset A_q$, and define the sublinear operator \mathcal{M}^j , a modified maximal operator, by

$$\mathcal{M}^j g(x) = \sup_{s>0} \int_{A_s} (|\psi_t^j| * |g|) \left(O_{\omega/\nu}^T(t)x + \frac{k}{\nu} t e_3 \right) \frac{dt}{t}, \quad (3.3)$$

where $A_s = [\frac{s}{16}, 16s]$. Then we will prove the preliminary estimate

$$\|T_j f\|_{q,w} \leq c \|\psi^j\|_1^{1/2} \|\mathcal{M}^j\|_{L_v^{(q/2)'}}^{1/2} \|f\|_{q,w}, \quad j \in \mathbb{Z}, \quad (3.4)$$

where v denotes the θ -independent weight

$$v = w^{-\left(\frac{q}{2}\right)' / \left(\frac{q}{2}\right)} = w^{-\frac{2}{q-2}} \in \tilde{A}_{(q/2)'}^+ = \tilde{A}_{q/(q-2)}^+. \quad (3.5)$$

To prove (3.4) we use the Littlewood-Paley decomposition of L_w^q , see (2.16), applied to $T_j f$. By a duality argument we find some function $0 \leq g \in L_v^{(q/2)'} = (L_w^{(q/2)})^*$ with $\|g\|_{(q/2)',v} = 1$ such that

$$\left\| \int_0^\infty |\varphi_s * T_j f(\cdot)|^2 \frac{ds}{s} \right\|_{q/2,w} = \int_0^\infty \int_{\mathbb{R}^3} |\varphi_s * T_j f(x)|^2 g(x) dx \frac{ds}{s}. \quad (3.6)$$

To estimate the right-hand side of (3.6) note that

$$\varphi_s * T_j f(x) = \int_0^\infty O_{\omega/\nu}^T(t) (\varphi_s * \psi_t^j * f) \left(O_{\omega/\nu}(t)x - \frac{k}{\nu} t e_3 \right) \frac{dt}{t},$$

where $\varphi_s * \psi_t^j = 0$ unless $t \in A(s, j) := [2^{2j-4}s, 2^{2j+4}s]$. Since $\int_{t \in A(s,j)} \frac{dt}{t} = \log 2^8$ for every $j \in \mathbb{Z}$, $s > 0$, we get by the inequality of Cauchy-Schwarz and the associativity of convolutions that

$$\begin{aligned} |\varphi_s * T_j f(x)|^2 &\leq c \int_{A(s,j)} \left| (\psi_t^j * (\varphi_s * f)) \left(O_{\omega/\nu}(t)x - \frac{k}{\nu} t e_3 \right) \right|^2 \frac{dt}{t} \\ &\leq c \|\psi^j\|_1 \int_{A(s,j)} (|\psi_t^j| * |\varphi_s * f|^2) \left(O_{\omega/\nu}(t)x - \frac{k}{\nu} t e_3 \right) \frac{dt}{t}; \end{aligned}$$

here we used the estimate $|(\psi_t^j * (\varphi_s * f))(y)|^2 \leq \|\psi_t^j\|_1 (|\psi_t^j| * |\varphi_s * f|^2)(y)$

and the identity $\|\psi_t^j\|_1 = \|\psi^j\|_1$, see (2.14). Thus

$$\begin{aligned}
& \|T_j f\|_{q,w}^2 \\
& \leq c \|\psi^j\|_1 \int_0^\infty \int_{A(s,j)} \int_{\mathbb{R}^3} (|\psi_t^j| * |\varphi_s * f|^2) \left(O_{\omega/\nu}(t)x - \frac{k}{\nu} t e_3 \right) g(x) dx \frac{dt}{t} \frac{ds}{s} \\
& \leq c \|\psi^j\|_1 \int_0^\infty \int_{A(s,j)} \int_{\mathbb{R}^3} (|\psi_t^j| * |\varphi_s * f|^2)(x) g \left(O_{\omega/\nu}^T(t)x + \frac{k}{\nu} t e_3 \right) dx \frac{dt}{t} \frac{ds}{s} \\
& \leq c \|\psi^j\|_1 \int_{\mathbb{R}^3} \int_0^\infty |\varphi_s * f|^2(x) \int_{A(s,j)} (|\psi_t^j| * g) \left(O_{\omega/\nu}^T(t)x + \frac{k}{\nu} t e_3 \right) \frac{dt}{t} \frac{ds}{s} dx,
\end{aligned} \tag{3.7}$$

since ψ_t^j is radially symmetric. By definition of \mathcal{M}^j the innermost integral is bounded by $\mathcal{M}^j g(x)$ uniformly in $s > 0$. Hence we may proceed in (3.7) using Hölder's inequality as follows:

$$\begin{aligned}
\|T_j f\|_{q,w}^2 & \leq c \|\psi^j\|_1 \int_{\mathbb{R}^3} \left(\int_0^\infty |\varphi_s * f|^2(x) \frac{ds}{s} \right) \mathcal{M}^j g(x) dx \\
& \leq c \|\psi^j\|_1 \left\| \int_0^\infty |\varphi_s * f|^2(x) \frac{ds}{s} \right\|_{q/2,w} \|\mathcal{M}^j g\|_{(q/2)',v}.
\end{aligned} \tag{3.8}$$

Now (2.16) and the normalization $\|g\|_{(q/2)',v} = 1$ complete the proof of (3.4).

Step 2. We estimate $\|\mathcal{M}^j g\|_{(q/2)',v}$. For functions γ depending on θ, x_3 only let \mathcal{M}_{hel} denote the ‘‘helical’’ maximal operator

$$\mathcal{M}_{\text{hel}} \gamma(\theta, x_3) = \sup_{s>0} \frac{1}{s} \int_{A_s} |\gamma| \left(\theta - \frac{\omega}{\nu} t, x_3 + \frac{k}{\nu} t \right) dt,$$

where $A_s = [\frac{s}{16}, 16s]$. Then, writing $p := (\frac{q}{2})'$, we claim that

$$\mathcal{M}^j g(x) \leq c 2^{-2|j|} \mathcal{M}(\mathcal{M}_{\text{hel}} g)(x) \quad \text{for a.a. } x \in \mathbb{R}^n, \tag{3.9}$$

$$\|\mathcal{M}^j g\|_{p,v} \leq c 2^{-2|j|} \|g\|_{p,v}, \tag{3.10}$$

where in (3.9) $\mathcal{M}_{\text{hel}} g$ is considered as $\mathcal{M}_{\text{hel}} g(r, \cdot, \cdot)$ for almost all $r > 0$.

To prove (3.9) we use the pointwise estimate $|\psi_t^j(x)| \leq c 2^{-2|j|} h_{t2^{-2j}}(x)$, see Lemma 2.5 (ii). Hence

$$\mathcal{M}^j g(x) \leq c 2^{-2|j|} \sup_{s>0} \int_{A_s} (h_{t2^{-2j}} * |g|) \left(O_{\omega/\nu}^T(t)x + \frac{k}{\nu} t e_3 \right) \frac{dt}{t}.$$

Moreover, there exists a constant $c > 0$ independent of $s > 0$, $j \in \mathbb{Z}$, such that $h_{t2^{-2j}} \leq ch_{s2^{-2j}}$ for all $t \in A_s$. Consequently,

$$\begin{aligned} \mathcal{M}^j g(x) &\leq c2^{-2|j|} \sup_{s>0} h_{s2^{-2j}} * \int_{A_s} |g| \left(O_{\omega/\nu}^T(t)x + \frac{k}{\nu}te_3 \right) \frac{dt}{t} \\ &\leq c2^{-2|j|} \sup_{t>0} h_t * \mathcal{M}_{\text{hel}}g(x). \end{aligned}$$

Since h is nonnegative, radially decreasing, and $\|h_t\|_1 = \|h\|_1 = c_0 > 0$ for all $t > 0$, a well-known convolution estimate, see [25], II §2.1, yields the pointwise estimate (3.9).

Step 3. Note that up to now we have not yet used any specific properties of the weight $v \in A_p$. To estimate $\mathcal{M}_{\text{hel}}g$ we shall work with a suitable one-sided maximal operator since our weight belongs to a Muckenhoupt class in \mathbb{R}^3 but a problem occurs when the weight is considered with respect to x_3 only. This naturally corresponds to the physical circumstances of the problem, where in the Oseen case the wake should appear. To estimate $\mathcal{M}_{\text{hel}}g$ we write $g_r(\theta, x_3) = g(r, \theta, x_3) = g(x)$ and $v_r(x_3) = v(x)$, $r = |(x_1, x_2)| > 0$, for the θ -independent weight v . Then by the 2π -periodicity of g_r and v_r with respect to θ we get for almost all $r > 0$

$$\begin{aligned} &\int_{\mathbb{R}} \int_0^{2\pi} \mathcal{M}_{\text{hel}}g_r(\theta, x_3)^p v_r(x_3) d\theta dx_3 \\ &\leq \int_{\mathbb{R}} \int_0^{2\pi} \left| \sup_{s>0} \frac{1}{s} \int_0^{16s} |g_r| \left(\theta - \frac{\omega}{k} \left(x_3 + \frac{k}{\nu}t \right), x_3 + \frac{k}{\nu}t \right) dt \right|^p v_r(x_3) d\theta dx_3 \\ &= \int_{\mathbb{R}} \int_0^{2\pi} \left| \sup_{s>0} \frac{1}{s} \int_0^{16s} \gamma_{r,\theta} \left(x_3 + \frac{k}{\nu}t \right) dt \right|^p d\theta v_r(x_3) dx_3 \\ &= 16 \int_0^{2\pi} \int_{\mathbb{R}} |M^+ \gamma_{r,\theta}(x_3)|^p v_r(x_3) dx_3 d\theta \end{aligned}$$

where $\gamma_{r,\theta}(y_3) = |g_r|(\theta - \frac{\omega}{k}y_3, y_3)$ and M^+ denotes the one-sided maximal operator, see Definition 1.2. Since $w_r \in A_{q/2}^-$, by (3.5) and Theorem 2.3 (i) $v_r = w_r^{-(q/2)'/(q/2)} \in A_{(q/2)'}^+ = A_p^+$ with an A_p^+ -constant uniformly bounded in $r > 0$. Then Theorem 2.3 (ii) yields the estimate

$$\begin{aligned} &\int_{\mathbb{R}} \int_0^{2\pi} \mathcal{M}_{\text{hel}}g_r(\theta, x_3)^p v_r(x_3) d\theta dx_3 \\ &\leq c \int_0^{2\pi} \int_{\mathbb{R}} |\gamma_{r,\theta}(x_3)|^p v_r(x_3) dx_3 d\theta = c \|g_r\|_{L^p(\mathbb{R} \times (0, 2\pi), v_r(x_3))}^p, \end{aligned}$$

where $c > 0$ is independent of k, ν . Integrating with respect to $r dr$, $r \in (0, \infty)$, Fubini's theorem allows to consider an extension of \mathcal{M}_{hel} to a bounded operator from $L_v^p(\mathbb{R}^3)$ to itself with an operator norm bounded uniformly in k, ν . Moreover, $\mathcal{M} : L_v^p(\mathbb{R}^3) \rightarrow L_v^p(\mathbb{R}^3)$ is bounded by Theorem 2.3 (ii). Hence, (3.9) implies (3.10), and by (3.4) as well as Lemma 2.5 (ii) we get the estimate

$$\|T_j f\|_{q,w} \leq c 2^{-2|j|} \|f\|_{q,w}$$

for all $f \in L_w^q(\mathbb{R}^3)$ with a constant $c > 0$ independent of $j \in \mathbb{Z}$. Summarizing the previous inequalities we proved (3.2) for $q > 2$.

Step 4. Now let $q = 2$, $w \in \tilde{A}_1^-$. In this case the Littlewood-Paley decomposition of $T_j f$ in L_w^2 implies that

$$\|T_j f\|_{2,w}^2 \leq c \int_0^\infty \int_{\mathbb{R}^n} |\varphi_s * T_j f|^2(x) g(x) dx \frac{ds}{s},$$

where

$$g \in L_v^\infty, v = \frac{1}{w} \quad \text{and} \quad \|g\|_{\infty,v} = \text{ess sup}_{\mathbb{R}^3} |g v| = 1.$$

By the same reasoning as before we arrive at (3.4), i.e.,

$$\|T_j f\|_{2,w} \leq c 2^{-|j|} \|\mathcal{M}^j g\|_{\infty,v}^{1/2} \|f\|_{2,w}, \quad (3.11)$$

and at (3.9). Concerning \mathcal{M}_{hel} we use the pointwise estimate $g_r(\theta, x_3) \leq w_r(x_3)$ for a.a. $\theta \in (0, 2\pi)$, $x_3 \in \mathbb{R}$, and get that

$$\mathcal{M}_{\text{hel}} g_r(\theta, x_3) \leq \sup_{s>0} \frac{1}{s} \int_0^{16s} w_r(x_3 + \frac{k}{\nu} t) dt \leq 16 M^+ w_r(x_3) \leq c w_r(x_3)$$

with a constant $c > 0$ independent of $r > 0$. Since w is an $A_1(\mathbb{R}^3)$ -weight, (3.9) implies that

$$\mathcal{M}^j g(x) \leq c 2^{-2|j|} \mathcal{M} w(x) \leq c 2^{-2|j|} w(x)$$

and consequently that $\|\mathcal{M}^j g\|_{\infty,v} \leq c 2^{-2|j|}$ with a constant $c > 0$ independent of $j \in \mathbb{Z}$. Hence $\|T_j f\|_{2,w} \leq c 2^{-2|j|}$ proving (3.2) when $q = 2$.

Step 5. The remaining estimates are proved by duality arguments. Obviously the dual operator to T is defined by

$$T^* f(x) = \int_0^\infty (-\Delta) O_\omega(t) E_t * f(O_\omega^T(t)x + k t e_3) dt,$$

which has the same structure as K , but with an "opposite orientation". Hence T^* is bounded on L_w^q for $q \geq 2$ and all weights $w \in \tilde{A}_{q/2}^+$. Now let $1 < q < 2$ and $w^{2/(2-q)} \in \tilde{A}_{q/(2-q)}^- = \tilde{A}_{(q'/2)}^-$. Then by simple duality arguments $w' = w^{-q'/q} \in \tilde{A}_{(q'/2)}^+$ and

$$|\langle Tf, g \rangle| = |\langle f, T^*g \rangle| \leq \|f\|_{q,w} \|T^*g\|_{q',w'} \leq c \|f\|_{q,w} \|g\|_{q',w'}.$$

Finally let $q = 2$ and $\frac{1}{w} \in \tilde{A}_1^+$. As before,

$$|\langle Tf, g \rangle| \leq \|f\|_{2,w} \|T^*g\|_{2,1/w} \leq c \|f\|_{2,w} \|g\|_{2,1/w}.$$

Now Proposition 3.1 is completely proved. \blacksquare

Lemma 3.2 ([1]). *Let $1 \leq p_1, p_2 < \infty$, let $0 < w_1, w_2$ be weight functions, $\delta \in (0, 1)$, and*

$$\frac{1}{p} = \frac{1-\delta}{p_1} + \frac{\delta}{p_2}, \quad w^{\frac{1}{p}} = w_1^{\frac{1-\delta}{p_1}} \cdot w_2^{\frac{\delta}{p_2}}.$$

Then

$$[L_{w_1}^{p_1}, L_{w_2}^{p_2}]_\delta = L_w^p$$

in the sense of complex interpolation.

In the following we shall derive an anisotropic variant of Jones's factorization theorem tailored to our situation, when we need to work with one-sided Muckenhoupt weights with respect to x_3 , satisfying the usual Muckenhoupt condition in three dimensions.

Lemma 3.3 (Anisotropic Version of Jones' Factorization Theorem).

Suppose that $w \in \tilde{A}_q^-$. Then there exist weights $w_1 \in \tilde{A}_1^-$ and $w_2 \in \tilde{A}_1^+$ such that

$$w = \frac{w_1}{w_2^{q-1}}.$$

Here \tilde{A}_1^+ is defined by analogy with \tilde{A}_1^- , cf. Definition 1.2, by assuming for $w_2 \in \tilde{A}_1^+$ that $(w_2)_r \in A_1^+$ with A_1^+ -constant uniformly bounded in $r > 0$. An analogous result holds for $w \in \tilde{A}_q^+$.

Proof. Let $q \geq 2$. Given $w \in \tilde{A}_q^-$ we consider the operator T defined by

$$\begin{aligned} Tf &= (w^{-1/q} \mathcal{M}(f^{q/q'} w^{1/q}))^{q'/q} + w^{1/q} \mathcal{M}(f w^{-1/q}) \\ &\quad + (w^{-1/q} M_1^+(f_r^{q/q'} w_r^{1/q}))^{q'/q} + w^{1/q} M_1^-(f_r w_r^{-1/q}) \end{aligned}$$

where $r = |(x_1, x_2)|$. Then for all $f \in L^q(\mathbb{R}^3)$

$$\begin{aligned} \|Tf\|_q^q &\leq c \left\{ \int_{\mathbb{R}^3} w^{-q'/q} (\mathcal{M}(f^{q/q'} w^{1/q}))^{q'} dx + \int_{\mathbb{R}^3} w (\mathcal{M}(f w^{-1/q}))^q dx \right. \\ &\quad + \int_{\mathbb{R}^2} \left(\int_{\mathbb{R}} w_r^{-q'/q} (M_1^+(f_r^{q/q'} w_r^{1/q}))^{q'} dx_3 \right) d(x_1, x_2) \\ &\quad \left. + \int_{\mathbb{R}^2} \left(\int_{\mathbb{R}} w_r (M_1^+(f_r w_r^{-1/q}))^q dx_3 \right) d(x_1, x_2) \right\} \\ &\leq A^q \|f\|_q^q, \end{aligned}$$

with a constant $A = A(q, w) > 0$.

Let us fix a nonnegative θ -independent function $f \in L^q(\mathbb{R}^3)$ with $\|f\|_q = 1$ and define

$$\eta = \sum_{k=1}^{\infty} (2A)^{-k} T^k(f),$$

where $T^k(f) = T(T^{k-1}(f))$. Obviously Tf and therefore also η are θ -independent. Moreover, $\eta \in L^q(\mathbb{R}^3)$ and $\|\eta\|_q \leq \sum_{k=1}^{\infty} 2^{-k} = 1$. In particular, $\eta(x) < \infty$ for a.a. $x \in \mathbb{R}^3$, $\eta_r(\cdot) \in L^q(\mathbb{R})$ for a.a. $(x_1, x_2) \in \mathbb{R}^2$ and $\eta_r(x_3) < \infty$ for a.a. $x_3 \in \mathbb{R}$. Since T is subadditive and positivity-preserving, we get the pointwise inequality

$$T\eta \leq \sum_{k=1}^{\infty} (2A)^{-k} T^{k+1}(f) = \sum_{k=2}^{\infty} (2A)^{1-k} T^k(f) \leq (2A)\eta.$$

Now let $w_1 := w^{1/q} \eta^{q/q'}$ and $w_2 := w^{-1/q} \eta$ such that $w = w_1/w_2^{q-1}$. Then

$$\begin{aligned} \mathcal{M}(w_1) &\leq w^{1/q} (T\eta)^{q/q'} \leq w^{1/q} \eta^{q/q'} (2A)^{q/q'} = (2A)^{q/q'} w_1 \\ M_1^+((w_1)_r) &\leq w^{1/q} (T\eta)^{q/q'} \leq w^{1/q} \eta^{q/q'} (2A)^{q/q'} = (2A)^{q/q'} (w_1)_r \\ \mathcal{M}(w_2) &\leq w^{-1/q} T(\eta) \leq w^{-1/q} \eta 2A = 2A w_2 \\ M_1^-((w_2)_r) &\leq w^{-1/q} T(\eta) \leq w^{-1/q} \eta 2A = 2A (w_2)_r \end{aligned}$$

proving that $w_1 \in \tilde{A}_1^-$, $w_2 \in \tilde{A}_1^+$.

The case $1 \leq q < 2$ follows by a simple duality argument, since $w \in \tilde{A}_q^-$ is equivalent to $w^{-q'/q} \in \tilde{A}_{q'}^+$. \blacksquare

Proof of Theorem 1.4 (i). Let $q \in (1, \infty)$ and $w \in A_q$ such that the L_w^q -estimate of ∇p holds, see (2.5). Hence it suffices to consider u defined by (2.7)–(2.8). We consider arbitrary $q_1, q_2 \in (1, \infty)$ and $\delta \in (0, 1)$ with

$$1 < q_1 < q < q_2 < \infty, \quad q_1 \leq 2 \leq q_2 \quad \text{and} \quad \frac{1}{q} = \frac{1-\delta}{q_1} + \frac{\delta}{q_2}, \quad (3.12)$$

and assume that $w^\tau \in \tilde{A}_{\tau q/2}^-$ with $\tau = \frac{2}{2-q(1-\delta)} \in [1, \infty)$. By Lemma 3.3 there exist weights $u \in \tilde{A}_1^-, v \in \tilde{A}_1^+$ such that

$$w^\tau = \frac{u}{v^{\tau q/2-1}} = \frac{u}{v^{\frac{q}{2-q(1-\delta)}-1}}.$$

Then we define the weights w_1, w_2 by

$$w_1^{2/(2-q_1)} = \frac{u}{v^{\frac{2(q_1-1)}{2-q_1}}} \quad \text{and} \quad w_2 = \frac{u}{v^{\frac{q_2-2}{2}}}$$

yielding

$$w_1^{2/(2-q_1)} \in \tilde{A}_{q_1/(2-q_1)}^-, \quad w_2 \in \tilde{A}_{q_2/2}^-.$$

Since, due to an elementary calculation, $w = w_1^{\frac{q(1-\delta)/q_1}{2-q(1-\delta)}} w_2^{\frac{q\delta/q_2}{2-q(1-\delta)}}$, Lemma 3.3 and Proposition 3.1 prove that T is bounded on $L_w^q(\mathbb{R}^3)$. Since $u_1 \in \tilde{A}_1^-, v_1 \in \tilde{A}_1^+$ are arbitrary, we proved the boundedness of T on L_w^q for arbitrary w if

$$w^\tau \in \tilde{A}_{\tau q/2}^-, \quad \tau = \frac{2}{2-q(1-\delta)} \in [1, \infty).$$

Now we have to find all admissible τ subject to the restrictions given by (3.12). For this reason consider the easier term

$$s = 2 \left(1 - \frac{1}{\tau} \right) = q(1-\delta) = q \frac{\frac{1}{q} - \frac{1}{q_2}}{\frac{1}{q_1} - \frac{1}{q_2}}.$$

First Case $1 < q < 2$, in which $1 < q_1 < q$ and $q_2 \geq 2$. Due to monotonicity properties of s as a function of $\frac{1}{q_1}$ and of $\frac{1}{q_2}$ it suffices to check s at the corners of the rectangle $(\frac{1}{q}, 1) \times (0, \frac{1}{2}]$. The corresponding function values are $q, 1$ and $2-q$. Hence the range of s equals the interval $(2-q, q)$ yielding for $\tau = \frac{2}{2-s}$ the condition

$$\frac{2}{q} < \tau < \frac{2}{2-q}.$$

Note that the limiting value $\tau = \frac{2}{2-q}$ is allowed due to Proposition 3.1. Finally the condition $w^\tau \in \widetilde{A}_{\tau q/2}^-, \frac{2}{q} < \tau \leq \frac{2}{2-q}$, easily implies that $w \in A_q$: By Lemma 3.3 there exist $u_1 \in \widetilde{A}_1^-, v_1 \in \widetilde{A}_1^+$ such that

$$w = \frac{u_1^{\frac{1}{\tau}}}{v_1^{\frac{q}{2} - \frac{1}{\tau}}}, \quad (3.13)$$

where $u_1^{\frac{1}{\tau}} \in \widetilde{A}_1^-$ and $\frac{q}{2} - \frac{1}{\tau} \leq q - 1$ yielding $v_1^{(\frac{q}{2} - \frac{1}{\tau})/(q-1)} \in \widetilde{A}_1^+$.

Second Case $q > 2$, in which $1 < q_1 \leq 2$ and $q_2 > q$. In this case the values of s at the corners of the rectangle $[\frac{1}{2}, 1) \times (0, \frac{1}{q})$ in the $(\frac{1}{q_1}, \frac{1}{q_2})$ -plane are 0, 1 and 2. Hence

$$1 < \tau < \infty,$$

and we observe that $\tau = 1$ is admissible due to Proposition 3.1. Finally note that the condition $w^\tau \in A_{\tau q/2}$ implies also $w \in \widetilde{A}_q^-$: There exist $u_1 \in \widetilde{A}_1^-, v_1 \in \widetilde{A}_1^+$ such that w satisfies (3.13), where again $\frac{q}{2} - \frac{1}{\tau} + 1 \leq q$ for all $\tau \in (1, \infty)$.

Third Case $q = 2$. In this case it suffices to interpolate between $L_{w_1}^2$ and $L_{w_2}^2$, where $w_1 \in \widetilde{A}_1^-$ and $\frac{1}{w_2} \in \widetilde{A}_1^+$, see Proposition 3.1. Then T is bounded on L_w^2 for all

$$w = \frac{w_1^{1-\delta}}{w_2^\delta}, \quad 0 < \delta < 1.$$

Then $w^{1/(1-\delta)} = w_1/w_2^{\delta/(1-\delta)}$, or with $\tau = \frac{1}{1-\delta} \in (1, \infty)$,

$$w^\tau = \frac{w_1}{w_2^{\tau-1}} \in \widetilde{A}_\tau^- = \widetilde{A}_{\tau q/2}^-.$$

(ii) Note that $L_{w_i}^{q_i}(\mathbb{R}^n) \subset S'(\mathbb{R}^n)$, $i = 1, 2$; indeed, $w_i \in L_{\text{loc}}^1(\mathbb{R}^n)$ and $\int_{|x| \geq 1} w_i(x) |x|^{-nq_i} dx < \infty$, see [10, IV.3 (3.2)]. Since the equation (1.5) is linear, it suffices to consider $f = 0$ and a solution $u \in S'(\mathbb{R}^n)^n$ of (1.8). In the proof of [6], Theorem 1.1 (2), (3), it was shown that under these assumptions u is a polynomial and that $u(x) = \alpha\omega + \beta\omega \wedge x + \gamma(x_1, x_2, -2x_3)^T$, $\alpha, \beta, \gamma \in \mathbb{R}$ ($u(x) = \beta(-x_2, x_1)$ if $n = 2$). \blacksquare

Proof of Corollary 1.5. Considering *a priori* estimates for $\frac{\partial u}{\partial x_3}$ we use the representation (2.7) of u . In order to analyze the dependence of the following estimates on the parameters k, ν and $\tilde{\omega}$ let

$$k' = k/\tilde{\omega}, \nu' = \nu/\tilde{\omega} \quad \text{and} \quad D(\xi) = 1 - e^{-2\pi(\nu'|\xi|^2 + ik'\xi_3)}.$$

Then for $f \in \mathcal{S}(\mathbb{R}^3)^3$ we get the identity

$$\widehat{k\partial_3 u}(\xi) = \frac{ik'\xi_3}{D(\xi)} \int_0^{2\pi} e^{-(\nu'|\xi|^2 + ik'\xi_3)t} O_{e_3}^T(t) \widehat{F}(O_{e_3}(t)\xi) dt, \quad (3.14)$$

where $F = f - \nabla p$, see (2.6). Choose a cut-off function $\eta \in C_0^\infty(B_1(0))$ with $\eta(\xi) = 1$ for $\xi \in B_{1/2}(0)$ and define the multiplier functions

$$m_0(\xi) = \frac{ik'\xi_3\eta_{\nu'}(\xi)}{D(\xi)}, \quad m_1(\xi) = \frac{k'}{\sqrt{\nu'}} \frac{1 - \eta_{\nu'}(\xi)}{D(\xi)},$$

where $\eta_{\nu'}(\xi) = \eta(\sqrt{\nu'}\xi)$, as well as

$$\mu_{0,t}(\xi) = e^{-(\nu'|\xi|^2 + ik'\xi_3)t}, \quad \mu_{1,t}(\xi) = i\xi_3\sqrt{\nu'}e^{-(\nu'|\xi|^2 + ik'\xi_3)t}, \quad t \in (0, 2\pi).$$

Then we get

$$\widehat{k\partial_3 u}(\xi) = m_0(\xi)\widehat{I}_0(\xi) + m_1(\xi)\widehat{I}_1(\xi),$$

where $I_0(x), I_1(x)$ are defined by their Fourier transforms

$$\begin{aligned} \widehat{I}_0(\xi) &= \int_0^{2\pi} \mu_{0,t}(\xi) O_{e_3}^T(t) \widehat{F}(O_{e_3}(t)\cdot)(\xi) dt, \\ \widehat{I}_1(\xi) &= \int_0^{2\pi} \mu_{1,t}(\xi) O_{e_3}^T(t) \widehat{F}(O_{e_3}(t)\cdot)(\xi) dt. \end{aligned}$$

Concerning the multiplier function $\mu_{0,t}$ we note that e.g.

$$\begin{aligned} \left| \xi_3 \frac{\partial \mu_{0,t}}{\partial \xi_3} \right| &= |(-2\nu't\xi_3^2 - ik't\xi_3)e^{-(\nu'|\xi|^2 + ik'\xi_3)t}| \\ &\leq C(\nu't|\xi|^2 + \frac{k'}{\sqrt{\nu'}}\sqrt{\nu't}|\xi_3|)e^{-\nu'|\xi|^2t} \\ &\leq C\left(1 + \frac{k'}{\sqrt{\nu'}}\right) \end{aligned}$$

with a constant $C > 0$ independent of $\xi \neq 0$, $t \in (0, 2\pi)$, $k' > 0$ and $\nu' > 0$. Then it is easily seen that $\mu_{0,t}, \mu_{1,t}$ satisfy the pointwise multiplier estimates

$$\sup_{t \in (0, 2\pi)} \max_{\alpha} \sup_{\xi \neq 0} (|\xi^\alpha D_\xi^\alpha \mu_{0,t}(\xi)| + \sqrt{t}|\xi^\alpha D_\xi^\alpha \mu_{1,t}(\xi)|) \leq C\left(1 + \frac{k}{\sqrt{\nu|\omega|}}\right)$$

uniformly in $k' > 0$ and $\nu' > 0$, where $\alpha \in \mathbb{N}_0^3$ runs through the set of all multi-indices $\alpha \in \{0, 1\}^3$. Hence Theorem 2.2 (iii) and (2.5) show that

$$\begin{aligned}\|I_0\|_{q,w} &\leq c \left(1 + \frac{k}{\sqrt{\nu|\omega|}}\right) \int_0^{2\pi} \|F(O_{e_3}(t)\cdot)\|_{q,w} dt \leq c \left(1 + \frac{k}{\sqrt{\nu|\omega|}}\right) \|f\|_{q,w}, \\ \|I_1\|_{q,w} &\leq c \left(1 + \frac{k}{\sqrt{\nu|\omega|}}\right) \int_0^{2\pi} \frac{1}{\sqrt{t}} \|F(O_{e_3}(t)\cdot)\|_{q,w} dt \leq c \left(1 + \frac{k}{\sqrt{\nu|\omega|}}\right) \|f\|_{q,w},\end{aligned}$$

where $c > 0$ is independent of k, ω and ν . Moreover, a lengthy, but elementary calculation proves that m_0, m_1 satisfy the pointwise estimates

$$\max_{j=0,1} \max_{\alpha} \sup_{\xi \neq 0} |\xi^\alpha D_\xi^\alpha m_j(\xi)| \leq C \left(1 + \frac{k^4}{\nu^2|\omega|^2}\right)$$

with $c > 0$ independent of ν, ω, k ; for details see [3]. Now another application of Theorem 2.2 (iii) yields the estimate

$$\|k\partial_3 u\|_{q,w} \leq c \left(1 + \frac{k^5}{\nu^{5/2}|\omega|^{5/2}}\right) \|f\|_{q,w}$$

for $f \in S(\mathbb{R}^3)^3$, with a constant $c > 0$ independent of f, k, ν and ω . Since $S(\mathbb{R}^3)$ is dense in $L_w^q(\mathbb{R}^3)$, this result extends to all $f \in L_w^q$; for its proof we refer to [3]. However, note that we did not estimate $\widehat{F}(O_\omega(t) \cdot -kte_3)\xi$ in $L^q(\Omega)$ as in [3]; instead we have to deal with $\widehat{F}(O_{e_3}(t)\cdot)$, and the shift operator is estimated with the help of multipliers.

Now Corollary 1.5 is completely proved. \blacksquare

Proof of Corollary 1.6. We have to check for which α, β the weight $w(x) = \eta_\beta^\alpha(x) = (1 + |x|)^\alpha (1 + s(x))^\beta$ satisfies the conditions needed in Theorem 1.4. From [2] and [16, Theorem 5.2] we know that $w = \eta_\beta^\alpha \in A_p$, $1 < p < \infty$, if and only if $-1 < \beta < p - 1$ and $-3 < \alpha + \beta < 3(p - 1)$; moreover, by Lemma 2.4 (iii) we have to satisfy the conditions $\alpha < p - 1$, $\beta \geq 0$, $\alpha + \beta > -1$ to get that $w_r(\cdot) \in A_p^-$.

Let $q > 2$. Then in view of (1.8) and (2.3) we have to analyze the convex set

$$\begin{aligned}\mathcal{C} &= \left\{(\alpha, \beta); \alpha < \frac{q}{2} - \frac{1}{\tau}, \beta \geq 0, \alpha + \beta > -\frac{1}{\tau}, -\frac{1}{\tau} < \beta < \frac{q}{2} - \frac{1}{\tau}, \right. \\ &\quad \left. -\frac{3}{\tau} < \alpha + \beta < \frac{3q}{2} - \frac{3}{\tau} \text{ for some } \tau \in [1, \infty)\right\}.\end{aligned}$$

Obviously the conditions $\beta > -\frac{1}{\tau}$ and $-\frac{3}{\tau} < \alpha + \beta < \frac{3q}{2} - \frac{3}{\tau}$ are redundant since $\frac{q}{2} - \frac{1}{\tau}$ is positive; moreover, the conditions $\alpha + \beta > -\frac{1}{\tau}$ and $\beta < \frac{q}{2} - \frac{1}{\tau}$ yield $\alpha > -\frac{q}{2}$. We will see that

$$\mathcal{C} = \{(\alpha, \beta); -\frac{q}{2} < \alpha < \frac{q}{2}, 0 \leq \beta < \frac{q}{2}, \alpha + \beta > -1\}.$$

Indeed, it suffices to consider pairs (α, β) with $\alpha < 0$. If moreover $\alpha + \beta < 0$, we find $\tau_0 > 1$ such that $\alpha + \beta = -\frac{1}{\tau_0}$. Then $\beta = -\frac{1}{\tau_0} - \alpha < -\frac{1}{\tau_0} + \frac{q}{2}$ and $\alpha < 0 < \frac{q}{2} - \frac{1}{\tau_0}$; consequently $(\alpha, \beta) \in \mathcal{C}$. If $\alpha + \beta \geq 0$, we may choose τ sufficiently large to show that $(\alpha, \beta) \in \mathcal{C}$.

Now consider the case $1 < q < 2$. As in the previous case we have to analyze the set \mathcal{C} where now τ runs in the interval $(\frac{2}{q}, \frac{2}{2-q}]$. Since $\tau > \frac{2}{q}$, the same conditions as before are redundant; moreover, $\alpha > -\frac{q}{2}$. Then we will show that

$$\mathcal{C} = \{(\alpha, \beta); -\frac{q}{2} < \alpha < q - 1, 0 \leq \beta < q - 1, \alpha + \beta > -\frac{q}{2}\}.$$

Indeed, if e.g. $\alpha < 0$ and $\alpha + \beta \leq \frac{q}{2} - 1 < 0$, then there exists $\tau_0 \in (\frac{2}{q}, \frac{2}{2-q}]$ such that $\alpha + \beta = -\frac{1}{\tau_0}$, $\beta = -\frac{1}{\tau_0} - \alpha < -\frac{1}{\tau_0} + \frac{q}{2}$ and $\alpha < 0 < \frac{q}{2} - \frac{1}{\tau_0}$; however, when $\alpha + \beta > \frac{q}{2} - 1$, we may choose $\tau = \frac{2}{2-q}$ to see that $(\alpha, \beta) \in \mathcal{C}$. ■

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