

9. Differential Calculus

Definition 9.1

Let V and W be two Banach spaces, $D \subseteq V$ be open in V and let $a \in D$. A function $f: D \rightarrow W$ is called differentiable at a if there exists a continuous linear transformation $T \in \mathcal{L}(V, W)$ such that

$$(*) \quad \lim_{x \rightarrow a} \frac{f(x) - f(a) - T(x-a)}{\|x-a\|} = 0$$

Remark 9.2

In the hypothesis of the above definition, for a function $f: D \rightarrow W$ the following are equivalent:

(i) f is differentiable at a ;

(ii) there exists $T \in \mathcal{L}(V, W)$ s.t. $\lim_{x \rightarrow a} \frac{\|f(x) - f(a) - T(x-a)\|}{\|x-a\|} = 0$;

(iii) there exist $T \in \mathcal{L}(V, W)$ and $r: D \rightarrow W$ s.t.

(a) $f(x) = f(a) + T(x-a) + r(x)$ for all $x \in D$, and

(b) $\lim_{x \rightarrow a} \frac{\|r(x)\|}{\|x-a\|} = 0$;

(iv) there exist $T \in \mathcal{L}(V, W)$ and $r': D \rightarrow W$ s.t.

(a) $f(x) = f(a) + T(x-a) + \|x-a\| \cdot r'(x)$ for all $x \in D$, and

(b) $\lim_{x \rightarrow a} r'(x) = 0$.

(v) there exist $T \in \mathcal{L}(V, W)$ and a map $\varphi: U_0 \rightarrow W$, where $U_0 \subseteq V$ is a neighborhood of 0 s.t.

(a) $f(a+h) = f(a) + T(h) + \psi(h)$ for all $h \in U_0$, and

(b) $\lim_{h \rightarrow 0} \frac{\psi(h)}{\|h\|} = 0;$

(vii) there exist $T \in \mathcal{L}(V, W)$ and a map $\psi: U_0 \rightarrow W$, where U_0 is a neighborhood of 0 in V s.t.

(a) $f(a+h) = f(a) + T(h) + \|h\| \cdot \psi(h)$ for all $h \in U_0$, and

(b) $\lim_{h \rightarrow 0} \psi(h) = 0.$

Proof

Exercise. □

Proposition 9.3

If f is differentiable at a , then the continuous linear transformation satisfying (*) is uniquely determined.

Proof

Assume that $S \in \mathcal{L}(V, W)$ is another function having property (*). It follows that

$$\begin{aligned} \lim_{x \rightarrow a} \frac{T(x-a) - S(x-a)}{\|x-a\|} &= \lim_{x \rightarrow a} \frac{(f(x) - f(a) - T(x-a)) - (f(x) - f(a) - S(x-a))}{\|x-a\|} \\ &= \lim_{x \rightarrow a} \frac{f(x) - f(a) - T(x-a)}{\|x-a\|} - \lim_{x \rightarrow a} \frac{f(x) - f(a) - S(x-a)}{\|x-a\|} \\ &= 0. \end{aligned}$$

We shall prove that $T(y) = S(y)$ for all $y \in V$. If $y = 0$, then $T(0) = S(0) = 0$.

Assume now that $y \neq 0$. Since $a \in D$ and D is open in V , there exists $r > 0$ s.t. $U_r(a) \subseteq D$. Then by setting $\delta := \frac{r}{\|y\|}$ we get that for all $t \in]0, \delta[$,

$\|(a+ty) - a\| = \|ty\| = t \cdot \|y\| < \delta \cdot \|y\| = r$, so $(a+ty) \in U_r(a) \subseteq D$.

Since $\lim_{t \rightarrow 0} (a+ty) = a$, we set that

$$\begin{aligned}
0 &= \lim_{t \rightarrow 0} \frac{T((a+ty)-a) - S((a+ty)-a)}{\|(a+ty)-a\|} = \lim_{t \rightarrow 0} \frac{T(ty) - S(ty)}{t \cdot \|y\|} = \\
&= \lim_{t \rightarrow 0} \frac{t(T(y) - S(y))}{t \cdot \|y\|} = \lim_{t \rightarrow 0} \frac{T(y) - S(y)}{\|y\|} = \frac{T(y) - S(y)}{\|y\|}.
\end{aligned}$$

Hence, $T(y) = S(y)$.

□

Definition 3.4

The uniquely determined continuous linear transformation T of the Definition 3.1 is called the derivative of f at a and is denoted by $f'(a)$ or $Df(a)$.

Definition 3.5

We say that $f: D \rightarrow W$ is differentiable if f is differentiable at every point $a \in D$. In that case, the derivative f' is a map

$$f': D \rightarrow \mathcal{L}(V, W), \quad a \mapsto f'(a).$$

from D into the Banach space $(\mathcal{L}(V, W), \|\cdot\|)$, where $\|\cdot\|$ is the operator norm.

We say that f is continuously differentiable or that f is of class C^1 if f' is continuous.

Remark 3.6

If V and W are finite dimensional normed spaces (and, hence, Banach spaces by Theorem 6.43), then any linear transformation $T: V \rightarrow W$ is continuous (see Proposition 6.46).

Moreover, since any two norms on a finite dimensional normed space are equivalent, it follows that the property of a function to be differentiable does not depend on V and W .

Remark 3.7

In the case $V = W = \mathbb{K}$ we get the usual definition of differentiability in \mathbb{K} from Analysis I.

Proof

Use the fact that a function $T: \mathbb{K} \rightarrow \mathbb{K}$ is linear iff there exists $L \in \mathbb{K}$ s.t. $T(x) = Lx$ for all $x \in \mathbb{K}$.

□

Proposition 3.8

Let V and W be Banach spaces, $D \subseteq V$ be open in V , $a \in D$ and $f: D \rightarrow W$ be differentiable at a . Then there exists a constant $c > 0$ s.t. for all x from a neighborhood of a

$$\|f(x) - f(a)\| \leq c \|x - a\|.$$

In particular, f is continuous at a .

Proof

Let us use Remark 3.2 (iv). Then there exists $r: D \rightarrow W$ s.t.

(5)

$f(x) = f(a) + f'(a)(x-a) + \|x-a\| r(x)$ for all $x \in D$ and $\lim_{x \rightarrow a} r(x) = 0$.

We get that for all $x \in D$,

$$\begin{aligned} \|f(x) - f(a)\| &= \|\ f'(a) \cdot (x-a) + \|x-a\| \cdot r(x)\ \| \leq \|f'(a) \cdot (x-a)\| + \\ &\quad + \|x-a\| \cdot \|r(x)\| \leq (\|f'(a)\| + \|r(x)\|) \|x-a\|. \end{aligned}$$

Since $\lim_{x \rightarrow a} r(x) = 0$, there exists $\delta > 0$ s.t.

$$(\forall x \in D) (0 < \|x-a\| < \delta \Rightarrow \|r(x)\| < 1).$$

Let $U := U_\delta(a)$. Then for all $x \in U$,

$$\|f(x) - f(a)\| \leq (\|f'(a)\| + 1) \cdot \|x-a\| = c \|x-a\|,$$

where $c = \|f'(a)\| + 1$.

In particular, this implies that

$$\lim_{x \rightarrow a} \|f(x) - f(a)\| \leq \lim_{x \rightarrow a} c \cdot \|x-a\| = 0,$$

so $\lim_{x \rightarrow a} f(x) = f(a)$. Thus, f is continuous at a . □

Operations with differentiable functions

In this section V, W, U are Banach spaces.

Proposition 3.3

Let D be open in V , $a \in D$ and $f, g: D \rightarrow W$. Assume that f and g are differentiable at a . Then

(i) $f+g$ is differentiable at a , and

$$(f+g)'(a) = f'(a) + g'(a).$$

(6)

(ii) for all $c \in \mathbb{R}$, $c \cdot f$ is differentiable at a , and

$$(c \cdot f)'(a) = c \cdot f'(a).$$

Proof

Since f, g are differentiable at a , there are $\Gamma_1, \Gamma_2: D \rightarrow W$

s.t.

$$f(x) = f(a) + f'(a)(x-a) + \Gamma_1(x), \quad \lim_{x \rightarrow a} \frac{\Gamma_1(x)}{\|x-a\|} = 0$$

$$g(x) = g(a) + g'(a)(x-a) + \Gamma_2(x), \quad \lim_{x \rightarrow a} \frac{\Gamma_2(x)}{\|x-a\|} = 0.$$

(i) Let $\Gamma := \Gamma_1 + \Gamma_2$. then

$$(f+g)(x) = (f+g)(a) + (f'(a) + g'(a))(x-a) + \Gamma(x), \text{ and}$$

$$\lim_{x \rightarrow a} \frac{\Gamma(x)}{\|x-a\|} = \lim_{x \rightarrow a} \frac{\Gamma_1(x)}{\|x-a\|} + \lim_{x \rightarrow a} \frac{\Gamma_2(x)}{\|x-a\|} = 0.$$

Thus, $f+g$ is differentiable at a and $(f+g)'(a) = f'(a) + g'(a)$.

(ii) Let $\Gamma := c\Gamma_1$. then

$$(c \cdot f)(x) = c f(a) + (c f'(a))(x-a) + \Gamma(x), \text{ and}$$

$$\lim_{x \rightarrow a} \frac{\Gamma(x)}{\|x-a\|} = c \cdot \lim_{x \rightarrow a} \frac{\Gamma_1(x)}{\|x-a\|} = 0.$$

Proposition 3.10

Let D be open in V and E be open in W . Let $f: D \rightarrow E$ and $g: E \rightarrow U$ be two functions. Assume that f is differentiable at $a \in D$ and g is differentiable at $f(a)$. Then $g \circ f$ is differentiable at a , and

$$(g \circ f)'(a) = g'(f(a)) \circ f'(a).$$

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Before giving the proof, we make explicit the meaning of the above formula. Note that $f'(a): V \rightarrow W$ is a continuous linear transformation, and $g'(f(a)): W \rightarrow U$ is also a continuous linear transformation. These transformations can be composed to get a continuous linear transformation from V to U .

Proof

For brevity, we set $b = f(a)$, $T_1 = f'(a)$ and $T_2 = g'(f(a)) = g'(b)$.

Hence, we have to prove that $g \circ f$ is differentiable at a , and $(g \circ f)'(a) = T_2 \circ T_1$.

We use Lemma 3.2 (iii). Since f is differentiable at a and g is differentiable at b , there exist $r_1: D \rightarrow W$ and $r_2: E \rightarrow U$ s.t.

$$f(x) = f(a) + T_1(x-a) + r_1(x) \text{ for all } x \in D, \text{ and } \lim_{x \rightarrow a} \frac{r_1(x)}{\|x-a\|} = 0$$

$$g(y) = g(b) + T_2(y-b) + r_2(y) \text{ for all } y \in E, \text{ and } \lim_{y \rightarrow b} \frac{r_2(y)}{\|y-b\|} = 0.$$

$$\text{Let } r: D \rightarrow U, \quad r(x) = (g \circ f)(x) - (g \circ f)(a) - (T_2 \circ T_1)(a).$$

Thus, $(g \circ f)(x) = (g \circ f)(a) + (T_2 \circ T_1)(a) + r(x)$ for all $x \in D$. It remains

to prove that $\lim_{x \rightarrow a} \frac{r(x)}{\|x-a\|} = 0$.

We have that for all $x \in D$,

$$\begin{aligned} r(x) &= g(f(x)) - g(b) - T_2(T_1(a)) = (g(b) + T_2(f(x)-b) + r_2(f(x))) - \\ &\quad - g(b) - T_2(T_1(a)) = T_2(f(x)-b) - T_2(T_1(a)) + r_2(f(x)) = \\ &= T_2(f(x)-b-T_1(a)) + r_2(f(x)) = T_2(r_1(x)) + r_2(f(x)). \end{aligned}$$

It follows that

$$\begin{aligned} \frac{\|r(x)\|}{\|x-a\|} &= \frac{\|T_2(r_1(x)) + r_2(f(x))\|}{\|x-a\|} \leq \frac{\|T_2(r_1(x))\|}{\|x-a\|} + \frac{\|r_2(f(x))\|}{\|x-a\|} \\ &\leq \|T_2\| \cdot \frac{\|r_1(x)\|}{\|x-a\|} + \frac{\|r_2(f(x))\|}{\|x-a\|} = \|T_2\| \cdot \frac{\|r_1(x)\|}{\|x-a\|} + \\ &\quad + \frac{\|r_2(f(x))\|}{\|f(x)-f(a)\|} \cdot \frac{\|f(x)-f(a)\|}{\|x-a\|} \\ &\leq \|T_2\| \cdot \frac{\|r_1(x)\|}{\|x-a\|} + c \cdot \frac{\|r_2(f(x))\|}{\|f(x)-f(a)\|} \end{aligned}$$

for all x from a neighborhood of a , by Prop. 9.8.

Since $\lim_{x \rightarrow a} \left(\|T_2\| \cdot \frac{\|r_1(x)\|}{\|x-a\|} + c \cdot \frac{\|r_2(f(x))\|}{\|f(x)-f(a)\|} \right) = \|T_2\| \cdot 0 +$
 $+ c \cdot \lim_{x \rightarrow a} \frac{\|r_2(f(x))\|}{\|f(x)-f(a)\|} \stackrel{y:=f(x)}{=} c \cdot \lim_{y \rightarrow b} \frac{\|r_2(y)\|}{\|y-a\|} = c \cdot 0 = 0,$

it follows that $\lim_{x \rightarrow a} \frac{\|r(x)\|}{\|x-a\|} = 0$, so $\lim_{x \rightarrow a} \frac{r(x)}{\|x-a\|} = 0$.

□

Proposition 9.11

Let D be open in V and E be open in W . Let $f: D \rightarrow E$ be a bijective function and $a \in D$. If f is differentiable at a with invertible derivative $f'(a)$ and if the inverse mapping $f^{-1}: E \rightarrow D$ is continuous at $b = f(a)$, then f^{-1} is differentiable at b with derivative

$$(f^{-1})'(b) = (f'(a))^{-1} = (f'(f^{-1}(b)))^{-1}.$$

Proof

Since f is differentiable at a , by Remark 8.2 (iv), there exists

$r: D \rightarrow W$ s.t.

$$(1) \quad f(x) = f(a) + f'(a)(x-a) + \|x-a\| \cdot r(x) \quad \text{for all } x \in D, \text{ and}$$

$$\lim_{x \rightarrow a} r(x) = 0.$$

By taking $x = f^{-1}(y)$ in (1), we get that

$$(2) \quad y = b + f'(a)(f^{-1}(y) - f^{-1}(a)) + \|f^{-1}(y) - f^{-1}(a)\| \cdot r(f^{-1}(y))$$

for all $y \in E$.

For brevity, let us set $T := (f'(a))^{-1}$. By applying T to both members of (2), it follows that

$$T(y-b) = f^{-1}(y) - f^{-1}(a) + T(\|f^{-1}(y) - f^{-1}(a)\| \cdot r(f^{-1}(y))),$$

so

$$f^{-1}(y) = f^{-1}(a) + T(y-b) + \|f^{-1}(y) - f^{-1}(a)\| \cdot (-T \circ r \circ f^{-1})(y)$$

for all $y \in E$.

$$\text{Let } r': E \rightarrow W, \quad r'(y) = \frac{\|f^{-1}(y) - f^{-1}(a)\|}{\|y-a\|} \cdot (-T \circ r \circ f^{-1})(y)$$

if $y \neq a$

$$r'(a) = 0$$

Then for all $y \in E$,

$$f^{-1}(y) = f^{-1}(a) + T(y-a) + \|y-a\| \cdot r'(y).$$

Hence, it remains to prove that $\lim_{y \rightarrow a} r'(y) = 0$.

First, let us remark that, since f^{-1} is continuous at $b=f(a)$, we have that $\lim_{y \rightarrow b} f^{-1}(y) = f^{-1}(b) = a$. It follows that

$$\lim_{y \rightarrow b} \tau(f^{-1}(y)) = \lim_{x \rightarrow a} \tau(x) = 0, \text{ so } \lim_{y \rightarrow b} (\tau \circ f^{-1})(y) = \tau(a) = 0.$$

Now, we shall prove that there exists $M > 0$ s.t. $\|f^{-1}(y) - f^{-1}(b)\| \leq M \cdot \|y - b\|$ for all y from a neighborhood of b .

It follows then that $\lim_{y \rightarrow b} \tau^{-1}(y) = 0$.

We have that for all $y \in E_1$

$$\|f^{-1}(y) - f^{-1}(b)\| \leq \|\tau(y - b)\| + \|f^{-1}(y) - f^{-1}(b)\| \cdot \|-(\tau \circ f^{-1})(y)\| \leq \|\tau\| \cdot \|y - b\| + \|f^{-1}(y) - f^{-1}(b)\| \cdot \|-(\tau \circ f^{-1})(y)\|.$$

Since $\lim_{y \rightarrow b} \|-(\tau \circ f^{-1})(y)\| = 0$, we get that there exists a neighborhood G of b s.t. $\|-(\tau \circ f^{-1})(y)\| \leq \frac{1}{2}$ for all $y \in G \setminus \{b\}$.

Hence, for all $y \in G \setminus \{b\}$,

$$\|f^{-1}(y) - f^{-1}(b)\| \leq \|\tau\| \cdot \|y - b\| + \frac{1}{2} \cdot \|f^{-1}(y) - f^{-1}(b)\|,$$

so (3) $\|f^{-1}(y) - f^{-1}(b)\| \leq 2 \cdot \|\tau\| \cdot \|y - b\|$.

Inequality (3) is also true for $y = b$.



Proposition 9.12

Let D be open in V , $a \in D$ and $f, g: D \rightarrow \mathbb{R}$. Assume that f, g are differentiable at a . Then

(i) $f \cdot g: D \rightarrow \mathbb{R}$, $(f \cdot g)(x) = f(x) \cdot g(x)$ is differentiable at a , and

$$(f \cdot g)'(a) = f(a) \cdot g'(a) + g(a) \cdot f'(a).$$

(ii) if $f(a) \neq 0$, then $\frac{1}{f}$ is differentiable at a , and

$$\left(\frac{1}{f}\right)'(a) = -\frac{1}{f(a)^2} f'(a)$$

Proof

(i) Let $T := f(a) \cdot g'(a) + g(a) \cdot f'(a)$. Then for all $v \in V$, we have that

$$T(v) = f(a) \cdot g'(a)(v) + g(a) \cdot f'(a)(v).$$

We have that

$$\begin{aligned} & \lim_{x \rightarrow a} \frac{(f \cdot g)(x) - (f \cdot g)(a) - T(x-a)}{\|x-a\|} = \\ & = \lim_{x \rightarrow a} \frac{f(x)g(x) - f(a)g(a) - f(a)g'(a)(x-a) - g(a)f'(a)(x-a)}{\|x-a\|} = \\ & = \lim_{x \rightarrow a} \frac{(f(x) - f(a) - f'(a)(x-a))g(a) + f(x)(g(x) - g(a) - g'(a)(x-a))}{\|x-a\|} + \\ & \quad + \frac{(f(x) - f(a))g'(a)(x-a)}{\|x-a\|} \\ & = \lim_{x \rightarrow a} \frac{f(x) - f(a) - f'(a)(x-a)}{\|x-a\|} \cdot g(a) + \lim_{x \rightarrow a} f(x) \cdot \frac{g(x) - g(a) - g'(a)(x-a)}{\|x-a\|} + \\ & \quad + \lim_{x \rightarrow a} \frac{f(x) - f(a)}{\|x-a\|} \cdot g'(a)(x-a) = 0 \cdot g(a) + f(a) \cdot 0 + 0 = 0, \end{aligned}$$

Since f is continuous at a , so $\lim_{x \rightarrow a} f(x) = f(a)$, and

$$\frac{\|f(x) - f(a)\|}{\|x - a\|} \leq c \text{ for } x \text{ in some neighborhood of } a \text{ (see Prop. 9.8)}$$

$$\lim_{x \rightarrow a} f'(a)(x-a) = f'(a)(0) = 0.$$

(ii) Assume that $f(a) \neq 0$. Since f is continuous at a , there exists a neighborhood G of a s.t. $f(x) \neq 0$ for all $x \in G \subseteq D$.

Then $\frac{1}{f}: G \rightarrow W$, $x \mapsto \frac{1}{f(x)}$ is well defined.

Consider the differentiable real function $g: \mathbb{R} \setminus \{0\} \rightarrow \mathbb{R}$ defined

by $g(y) = \frac{1}{y}$. Then $\frac{1}{f} = g \circ f$.

We can apply the Chain Rule to get that $\frac{1}{f}$ is differentiable at a with derivative

$$\left(\frac{1}{f}\right)'(a) = g'(f(a)) \cdot f'(a) = -\frac{1}{f(a)^2} f'(a).$$

□

Differentiability in \mathbb{R}^n

In the sequel, we consider $V = \mathbb{R}^n$, $W = \mathbb{R}^m$, where $m, n \in \mathbb{N}$ and the norms are the Euclidean norms, if not otherwise stated.

A function $f: D \rightarrow \mathbb{R}^m$, where $D \subseteq \mathbb{R}^n$, can be written in the form

$$f(x) = \begin{pmatrix} f_1(x) \\ \vdots \\ f_m(x) \end{pmatrix} \text{ for all } x \in \mathbb{R}^n, \text{ where } f_j: D \rightarrow \mathbb{R}, j=1, \dots, m \text{ are}$$

the components of f . We shall write $f = \begin{pmatrix} f_1 \\ \vdots \\ f_m \end{pmatrix}$.

Example 9.14

Let $f: \mathbb{R}^3 \rightarrow \mathbb{R}^2$, $f(x, y, z) = \begin{pmatrix} x^2 - y^2 \\ 2xz + 1 \end{pmatrix}$. Then $f = \begin{pmatrix} f_1 \\ f_2 \end{pmatrix}$, where

$$f_1, f_2: \mathbb{R}^3 \rightarrow \mathbb{R}, \quad f_1(x, y, z) = x^2 - y^2, \quad f_2(x, y, z) = 2xz + 1.$$

Proposition 9.15

Let D be open in \mathbb{R}^n , $a \in D$ and $f: D \rightarrow \mathbb{R}^m$. Then

f is differentiable at $a \iff f_1, \dots, f_m$ are differentiable at a .

In this case, the derivative $f'(a) \in \mathcal{L}(\mathbb{R}^n, \mathbb{R}^m)$ is given by

$$f'(a) = \begin{pmatrix} f_1'(a) \\ \vdots \\ f_m'(a) \end{pmatrix}.$$

That is, $(f'(a))_j = f_j'(a)$ for all $j=1, \dots, m$.

Proof

We have that

f is differentiable at a with derivative $f'(a) \Leftrightarrow$

$$\Leftrightarrow \lim_{x \rightarrow a} \frac{f(x) - f(a) - f'(a)(x-a)}{\|x-a\|} = 0$$

$$\Leftrightarrow \lim_{x \rightarrow a} \left(\frac{f_1(x) - f_1(a) - (f'(a))_1(x-a)}{\|x-a\|} \dots \frac{f_m(x) - f_m(a) - (f'(a))_m(x-a)}{\|x-a\|} \right)^T = 0$$

$$\Leftrightarrow \text{for all } j=1, \dots, m, \quad \lim_{x \rightarrow a} \frac{f_j(x) - f_j(a) - (f'(a))_j(x-a)}{\|x-a\|} = 0$$

\Leftrightarrow for all $j=1, \dots, m$, f_j is differentiable at a and $f'_j(a) = (f'(a))_j$.

The last equivalence is true iff $(f'(a))_j \in \mathcal{L}(\mathbb{R}^n, \mathbb{R})$. It is easy to prove that if $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a linear transformation, $T = \begin{pmatrix} T_1 \\ \vdots \\ T_m \end{pmatrix}$, then T_j is a linear transformation for all $j=1, \dots, m$. □

Remark 8.16

As a consequence of the above proposition, we get that for a path $\gamma: I \rightarrow \mathbb{R}^n$, where I is an open interval in \mathbb{R} , γ is differentiable $\Leftrightarrow \gamma$ is differentiable in the sense of Definition 8.13.

If $f: D \subseteq \mathbb{R}^n \rightarrow \mathbb{R}^m$, where D is open, is differentiable at $a \in D$, then the derivative $f'(a)$ is a linear transformation $\mathbb{R}^n \rightarrow \mathbb{R}^m$. Then $f'(a)$ can be represented by a $m \times n$ -matrix and sometimes $f'(a)$ is identified with this matrix. If $A = (a_{ij})_{\substack{1 \leq i \leq m \\ 1 \leq j \leq n}}$ is the associated matrix and

$$h = \begin{pmatrix} h_1 \\ \vdots \\ h_n \end{pmatrix} \in \mathbb{R}^n, \text{ then } f'(a)(h) = Ah = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{pmatrix} \begin{pmatrix} h_1 \\ \vdots \\ h_n \end{pmatrix}.$$

If $f: D \subseteq \mathbb{R}^n \rightarrow \mathbb{R}$ is real-valued, then $f'(a)$ is a linear transformation $\mathbb{R}^n \rightarrow \mathbb{R}$, so it is represented by a $1 \times n$ -matrix, that is a row vector. The transpose $[f'(a)]^T$ of this $1 \times n$ -matrix is a $n \times 1$ -matrix, a column vector.

Definition 3.17

Let $f: D \subseteq \mathbb{R}^n \rightarrow \mathbb{R}$, where D is open in \mathbb{R}^n , and assume that f is differentiable at a . The gradient of f at a , denoted by $\text{grad } f(a)$ or $\nabla f(a)$, is defined as

$$\text{grad } f(a) := [f'(a)]^T.$$

Directional and partial derivatives

In the sequel, $D \subseteq \mathbb{R}^n$ is open, $a \in D$ and $f: D \rightarrow \mathbb{R}^m$.

Remark 3.18

For any vector $v \in \mathbb{R}^n$, there exists a neighborhood $U_0 \subseteq \mathbb{R}$ of 0 s.t. $a+tv \in D$ for all $t \in U_0$.

Proof

Since $a \in D$ and D is open, there exists $r > 0$ s.t. $U_r(a) \subseteq D$. Let $v \in \mathbb{R}^n$. If $v = 0$, we can take any neighborhood of 0, since $a+0 = a \in D$. Assume that $v \neq 0$, so $\|v\| \neq 0$. Then by setting $\delta := \frac{r}{\|v\|}$ we get that for all

$$t \in U_0 :=]-\delta, \delta[,$$

$$\|(a+tv) - a\| = \|tv\| = |t| \cdot \|v\| < \delta \cdot \|v\| = r,$$

$$\text{so } a+tv \in U_r(a) \subseteq D.$$

Definition 9.18

Let $v \in \mathbb{R}^n, v \neq 0$. The directional derivative of f at a in the direction v is defined as

$$D_v f(a) = \lim_{t \rightarrow 0} \frac{f(a+tv) - f(a)}{t},$$

provided the limit exists.

Proposition 9.20

Let $f = \begin{pmatrix} f_1 \\ \vdots \\ f_m \end{pmatrix}$ and $v \in \mathbb{R}^n \setminus \{0\}$. Then

$D_v f(a)$ exists $\Leftrightarrow D_v f_j(a)$ exists for all $j=1, \dots, m$.

In this case, $D_v f(a) = \begin{pmatrix} D_v f_1(a) \\ \vdots \\ D_v f_m(a) \end{pmatrix}$.

Proof

Similar to the proof of Proposition 9.15. □

Proposition 9.21

Assume that f is differentiable at a . Then for any $v \in \mathbb{R}^n, v \neq 0$, the directional derivative $D_v f(a)$ exists and

$$D_v f(a) = f'(a)(v).$$

Proof

Let $v \in \mathbb{R}^n, v \neq 0$. Since f is differentiable at a , by Remark 9.2 (vi),

there exists a map $\psi: U_0 \rightarrow \mathbb{R}^m$, where U_0 is a neighborhood of 0 in \mathbb{R}^n ,

s.t.

$$(1) \quad f(a+h) = f(a) + f'(a)(h) + \|h\| \cdot \psi(h) \quad \text{for all } h \in U_0$$

$$\text{and } \lim_{h \rightarrow 0} \psi(h) = 0.$$

As in Remark 3.18, we can find a neighborhood V_0 of 0 in \mathbb{R}^n s.t. $tv \in U_0$ for all $t \in V_0$. Then for $t \in V_0$ we can take $h := tv$ in (1) to get that

$$f(a+tv) = f(a) + f'(a)(tv) + \|tv\| \cdot \psi(tv), \text{ so}$$

$$f(a+tv) - f(a) = t \cdot f'(a)(v) + |t| \cdot \|v\| \cdot \psi(tv).$$

We get that

$$(2) \quad \frac{f(a+tv) - f(a)}{t} = f'(a)(v) + \frac{|t|}{t} \cdot \|v\| \cdot \psi(tv) \quad \text{for all } t \in V_0 \setminus \{0\}.$$

Since $\lim_{t \rightarrow 0} tv = 0$, we have that $\lim_{t \rightarrow 0} \psi(tv) = 0$ by (1). Moreover,

$$\left| \frac{|t|}{t} \cdot \|v\| \right| = \|v\|, \text{ so we can conclude that } \lim_{t \rightarrow 0} \left(\frac{|t|}{t} \cdot \|v\| \cdot \psi(tv) \right) = 0.$$

Thus, by (2), $\lim_{t \rightarrow 0} \frac{f(a+tv) - f(a)}{t} = f'(a)(v)$. That is, the

directional derivative $D_v f(a)$ exists and $D_v f(a) = f'(a)(v)$. □

Thus, differentiability at a implies the existence of all directional derivatives at a . We shall see later that the converse is not true. There exist functions having all directional derivatives at a point without being differentiable at that point.

Proposition 3.21 can be used to compute $f'(a)$ when we know that f is differentiable at a . If v_1, \dots, v_n is a basis of \mathbb{R}^n , then every vector $h \in \mathbb{R}^n$ can be uniquely represented as a linear combination

$h = \sum_{i=1}^n \alpha_i v_i$, with $\alpha_i \in \mathbb{R}$. Since $f'(a)$ is linear, we get that $f'(a)(h) = f'(a)\left(\sum_{i=1}^n \alpha_i v_i\right) = \sum_{i=1}^n \alpha_i f'(a)(v_i) = \sum_{i=1}^n \alpha_i D_{v_i} f(a)$.

Therefore $f'(a)$ is known if the directional derivatives $D_{v_i} f(a)$ for the basis vectors are known.

Let us consider the standard basis $e_1, \dots, e_n \in \mathbb{R}^n$, where

$e_i = \begin{pmatrix} 0 \\ \vdots \\ 0 \\ 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}$ ← i th position for all $i=1, \dots, n$.

Definition 3.22

Let $i=1, \dots, n$. The i -th partial derivative of f at a or the partial derivative of f at a with respect to the i -th variable is by definition the

directional derivative $D_{e_i} f(a)$ at a in the direction e_i , provided it exists.

We use the following notations for the i -th partial derivative of f at a :

$\frac{\partial f}{\partial x_i}(a), \partial_i f(a), D_i f(a)$.

If $\frac{\partial f}{\partial x_i}(a)$ exists, we say also that f is partial differentiable at a

with respect to the i -th variable. We say that f is partial differentiable

at a if $\frac{\partial f}{\partial x_1}(a), \dots, \frac{\partial f}{\partial x_n}(a)$ exists

If $\frac{\partial f}{\partial x_i}(a)$ exists for all $a \in D$ we get a function

$\frac{\partial f}{\partial x_i} : D \rightarrow \mathbb{R}^m$ whose value at any $a \in D$ is $\frac{\partial f}{\partial x_i}(a)$; $\frac{\partial f}{\partial x_i}$ is the

i -th partial derivative.

Remark 1.23

Let $i=1, \dots, n$ and $a = (a_1, \dots, a_n) \in D$.

$$(i) \quad \frac{\partial f}{\partial x_i}(a) = \lim_{x_i \rightarrow a_i} \frac{f(a_1, \dots, a_{i-1}, x_i, a_{i+1}, \dots, a_n) - f(a)}{x_i - a_i}.$$

(ii) If $f: D \subseteq \mathbb{R}^n \rightarrow \mathbb{R}$ is real-valued, then

$$\frac{\partial f}{\partial x_i}(a) = \lim_{x_i \rightarrow a_i} \frac{\varphi_i(x_i) - \varphi_i(a_i)}{x_i - a_i} = \varphi_i'(a_i),$$

where $\varphi_i: \mathbb{R} \rightarrow \mathbb{R}$, $\varphi_i(t) = f(a_1, \dots, a_{i-1}, t, a_{i+1}, \dots, a_n)$.

Proof

$$\begin{aligned} (i) \quad \frac{\partial f}{\partial x_i}(a) &= \text{Def } f(a) = \lim_{t \rightarrow 0} \frac{f(a + te_i) - f(a)}{t} = \\ &= \lim_{t \rightarrow 0} \frac{f(a_1, \dots, a_{i-1}, a_i + t, a_{i+1}, \dots, a_n) - f(a)}{t} \\ &\stackrel{\text{change of variables}}{=} \lim_{x_i \rightarrow a_i} \frac{f(a_1, \dots, a_{i-1}, x_i, a_{i+1}, \dots, a_n) - f(a)}{x_i - a_i} \end{aligned}$$

(ii) Apply (i). □

Remark 1.24

Let $f = \begin{pmatrix} f_1 \\ \vdots \\ f_m \end{pmatrix}$. Then for all $i=1, \dots, m$,

$$\frac{\partial f}{\partial x_i}(a) \text{ exists} \iff \frac{\partial f_1}{\partial x_i}(a), \dots, \frac{\partial f_m}{\partial x_i}(a) \text{ exists.}$$

In this case, $\frac{\partial f}{\partial x_i}(a) = \begin{pmatrix} \frac{\partial f_1}{\partial x_i}(a) \\ \vdots \\ \frac{\partial f_m}{\partial x_i}(a) \end{pmatrix}$.

Proof

It is a consequence of Proposition 9.20. □

Let $D \subseteq \mathbb{R}^n$ be open, $f: D \rightarrow \mathbb{R}^m$, $f = \begin{pmatrix} f_1 \\ \vdots \\ f_m \end{pmatrix}$ and $a \in D$. In order to compute a partial derivative of f at a , we compute the partial derivatives at a of the components f_1, \dots, f_m . Thus, we reduce the problem to real-valued functions.

If $f: D \subseteq \mathbb{R}^n \rightarrow \mathbb{R}$ is real-valued, then we compute the partial derivative $\frac{\partial f}{\partial x_i}(a)$ as follows: we fix all the variables except for the i -th, putting them equal to $a_1, \dots, a_{i-1}, a_{i+1}, \dots, a_n$ and we consider the real function $z \mapsto f(a_1, \dots, a_{i-1}, z, a_{i+1}, \dots, a_n)$, $z \in \mathbb{R}$; now we differentiate this function at a as in Analysis I and the result is $\frac{\partial f}{\partial x_i}(a)$.

Definition 9.25

Assume that $f: D \subseteq \mathbb{R}^n \rightarrow \mathbb{R}^m$ is partial differentiable at $a \in D$.

Then the matrix of partial derivatives

$$\begin{pmatrix} \frac{\partial f_1}{\partial x_1}(a) & \frac{\partial f_1}{\partial x_2}(a) & \dots & \frac{\partial f_1}{\partial x_n}(a) \\ \frac{\partial f_2}{\partial x_1}(a) & \frac{\partial f_2}{\partial x_2}(a) & \dots & \frac{\partial f_2}{\partial x_n}(a) \\ \dots & \dots & \dots & \dots \\ \frac{\partial f_m}{\partial x_1}(a) & \frac{\partial f_m}{\partial x_2}(a) & \dots & \frac{\partial f_m}{\partial x_n}(a) \end{pmatrix}$$

is called the Jacobi matrix of f at a and is denoted by $Jf(a)$. (21)

If $m=n$, then the matrix $Jf(a)$ is square and its determinant $\det Jf(a)$ is called the Jacobian determinant or the Jacobian of f at a .

It is frequently denoted $\frac{\partial(f_1, \dots, f_n)}{\partial(x_1, \dots, x_n)}$ or $\frac{D(f_1, \dots, f_n)}{D(x_1, \dots, x_n)}$.

Remark 9.26

If $f: \mathbb{R}^3 \rightarrow \mathbb{R}$, one also uses the notation $\frac{\partial f}{\partial x}$, $\frac{\partial f}{\partial y}$, $\frac{\partial f}{\partial z}$ instead

of $\frac{\partial f}{\partial x_1}$, $\frac{\partial f}{\partial x_2}$, $\frac{\partial f}{\partial x_3}$.

Example 9.27

(i) Let $f: \mathbb{R}^2 \rightarrow \mathbb{R}$, $f(x_1, x_2) = x_1^2 x_2 + x_2^3$.

To find $\frac{\partial f}{\partial x_1}(x_1, x_2)$ we hold x_2 constant and differentiate only with respect to x_1 ; this yields

$$\frac{\partial f}{\partial x_1}(x_1, x_2) = \frac{d(x_1^2 x_2 + x_2^3)}{dx_1} = 2x_1 x_2.$$

Similarly, to find $\frac{\partial f}{\partial x_2}(x_1, x_2)$ we hold x_1 constant and differentiate

only with respect to x_2 :

$$\frac{\partial f}{\partial x_2}(x_1, x_2) = \frac{d(x_1^2 x_2 + x_2^3)}{dx_2} = x_1^2 + 3x_2^2.$$

Thus, f is partial differentiable on \mathbb{R}^2 and for all $a = (a_1, a_2) \in \mathbb{R}^2$,

$$\begin{aligned} \frac{\partial f}{\partial x_1}(a) &= 2a_1 a_2, \quad \frac{\partial f}{\partial x_2}(a) = a_1^2 + 3a_2^2, \quad Jf(a) = \begin{pmatrix} \frac{\partial f}{\partial x_1}(a) & \frac{\partial f}{\partial x_2}(a) \end{pmatrix} \\ &= (2a_1 a_2 \quad a_1^2 + 3a_2^2). \end{aligned}$$

(ii) Let $f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$, $f(x_1, x_2) = \begin{pmatrix} x_1^2 - x_2^2 \\ 2x_1x_2 \end{pmatrix}$.

The components of f are $f_1, f_2: \mathbb{R}^2 \rightarrow \mathbb{R}$, $f_1(x_1, x_2) = x_1^2 - x_2^2$,
 $f_2(x_1, x_2) = 2x_1x_2$.

Then f is partial differentiable on \mathbb{R}^2 and for all $a = (a_1, a_2) \in \mathbb{R}^2$
 we get that

$$\begin{aligned} \mathcal{D}f(a_1, a_2) &= \begin{pmatrix} \frac{\partial f_1}{\partial x_1}(a_1, a_2) & \frac{\partial f_1}{\partial x_2}(a_1, a_2) \\ \frac{\partial f_2}{\partial x_1}(a_1, a_2) & \frac{\partial f_2}{\partial x_2}(a_1, a_2) \end{pmatrix} = \\ &= \begin{pmatrix} 2a_1 & -2a_2 \\ 2a_2 & 2a_1 \end{pmatrix}. \end{aligned}$$

(iii) Let $f: \mathbb{R}^2 \rightarrow \mathbb{R}^3$, $f(x, y) = \begin{pmatrix} x^2 - 2xy \\ x^2 + y^3 \\ \sin x \end{pmatrix}$

The components of f are $f_1, f_2, f_3: \mathbb{R}^2 \rightarrow \mathbb{R}$,

$$f_1(x, y) = x^2 - 2xy, \quad f_2(x, y) = x^2 + y^3, \quad f_3(x, y) = \sin x.$$

For all $(x, y) \in \mathbb{R}^2$, f is partial differentiable at (x, y) and

$$\mathcal{D}f(x, y) = \begin{pmatrix} \frac{\partial f_1}{\partial x}(x, y) & \frac{\partial f_1}{\partial y}(x, y) \\ \frac{\partial f_2}{\partial x}(x, y) & \frac{\partial f_2}{\partial y}(x, y) \\ \frac{\partial f_3}{\partial x}(x, y) & \frac{\partial f_3}{\partial y}(x, y) \end{pmatrix} = \begin{pmatrix} 2x - 2y & -2x \\ 2x & 3y^2 \\ \cos x & 0 \end{pmatrix}$$

In particular, $\mathcal{D}f(0, 1) = \begin{pmatrix} -2 & 0 \\ 0 & 3 \\ 1 & 0 \end{pmatrix}$.

(iv) Let $f: \mathbb{R}^2 \rightarrow \mathbb{R}$, $f(x, y) = x^{\frac{1}{3}} y^{\frac{1}{3}} = \sqrt[3]{x} \cdot \sqrt[3]{y}$.

Then for all $(x, y) \in \mathbb{R}^2 \setminus \{(0, 0)\}$,

$$\begin{aligned} \nabla f(x, y) &= \left(\frac{\partial f}{\partial x}(x, y) \quad \frac{\partial f}{\partial y}(x, y) \right) = \left(\frac{1}{3} \cdot y^{\frac{1}{3}} \cdot x^{-\frac{2}{3}}, \frac{1}{3} x^{\frac{1}{3}} y^{-\frac{2}{3}} \right) \\ &= \left(\frac{1}{3} \frac{\sqrt[3]{y}}{\sqrt[3]{x^2}} \quad \frac{1}{3} \frac{\sqrt[3]{x}}{\sqrt[3]{y^2}} \right). \end{aligned}$$

To obtain the partial derivative at $(0, 0)$ we can not simply substitute $(x, y) = (0, 0)$. In this case, we use the definition.

$$\frac{\partial f}{\partial x}(0, 0) = \lim_{x \rightarrow 0} \frac{f(x, 0) - f(0, 0)}{x - 0} = \lim_{x \rightarrow 0} \frac{0 - 0}{x} = 0.$$

$$\frac{\partial f}{\partial y}(0, 0) = \lim_{y \rightarrow 0} \frac{f(0, y) - f(0, 0)}{y - 0} = 0.$$

Thus, $\nabla f(0, 0) = (0 \ 0)$.

Proposition 9.28

Let $D \subseteq \mathbb{R}^n$ be open, $a \in D$ and $f: D \rightarrow \mathbb{R}^m$. If f is differentiable at a , then f is partial differentiable at a and for all $h \in \mathbb{R}^n$

$$f'(a)(h) = \nabla f(a) \cdot h.$$

Thus, the matrix associated to $f'(a)$ is the Jacobi matrix of f at a .

Proof

By Proposition 9.21, f is partial differentiable at a and for all $i = 1, \dots, n$

$$\frac{\partial f}{\partial x_i}(a) = \text{Dei } f(a) = f'(a)(e_i).$$

Let $h = \begin{pmatrix} h_1 \\ \vdots \\ h_n \end{pmatrix} \in \mathbb{R}^n$. Then $h = \sum_{i=1}^n h_i e_i$, so

$$\begin{aligned}
f'(a)(h) &= f'(a) \left(\sum_{i=1}^n h_i e_i \right) = \sum_{i=1}^n h_i f'(a)(e_i) = \sum_{i=1}^n h_i \frac{\partial f}{\partial x_i}(a) \\
&= \sum_{i=1}^n h_i \cdot \begin{pmatrix} \frac{\partial f_1}{\partial x_i}(a) \\ \vdots \\ \frac{\partial f_m}{\partial x_i}(a) \end{pmatrix}, \text{ by Remark 9.24} \\
&= \begin{pmatrix} \sum_{i=1}^n h_i \cdot \frac{\partial f_1}{\partial x_i}(a) \\ \vdots \\ \sum_{i=1}^n h_i \cdot \frac{\partial f_m}{\partial x_i}(a) \end{pmatrix} = \begin{pmatrix} \frac{\partial f_1}{\partial x_1}(a) & \dots & \frac{\partial f_1}{\partial x_n}(a) \\ \vdots & & \vdots \\ \frac{\partial f_m}{\partial x_1}(a) & \dots & \frac{\partial f_m}{\partial x_n}(a) \end{pmatrix} \cdot \begin{pmatrix} h_1 \\ \vdots \\ h_n \end{pmatrix} \\
&= J_f(a) \cdot h.
\end{aligned}$$

Remark 9.28

It is possible that all partial derivatives exist at a without f being differentiable at a . Then the Jacobi matrix can be formed, but it does not represent the derivative $f'(a)$, which does not exist.

Remark 9.30

To check whether f is differentiable at a , one first verifies that f is partial differentiable at a . This is a necessary condition for the existence of $f'(a)$, by Proposition 9.28. Then one forms the Jacobi matrix $J_f(a)$ and considers the associated linear transformation $T \in \mathcal{L}(\mathbb{R}^n, \mathbb{R}^m)$, $T(h) = J_f(a)h$. Finally, one tests if $\lim_{x \rightarrow a} \frac{f(x) - f(a) - T(x-a)}{\|x-a\|} = 0$ holds. If this holds, then f is differentiable at a with derivative $f'(a) = T$.

The following example shows that a function can have all directional derivatives at a without being differentiable at a.

Example 8.31

Let $f: \mathbb{R}^2 \rightarrow \mathbb{R}$ be defined by

$$f(x_1, x_2) = \begin{cases} 0 & \text{for } (x_1, x_2) = (0, 0) \\ \frac{|x_1| \cdot x_2}{\sqrt{x_1^2 + x_2^2}} & \text{for } (x_1, x_2) \neq (0, 0). \end{cases}$$

Then f has all directional derivatives at $(0, 0)$, but f is not differentiable at $(0, 0)$.

Proof

Let $v = (v_1, v_2) \in \mathbb{R}^2 \setminus \{(0, 0)\}$. Then

$$\begin{aligned} D_v f(0, 0) &= \lim_{t \rightarrow 0} \frac{f((0, 0) + tv) - f(0, 0)}{t} = \lim_{t \rightarrow 0} \frac{f(tv) - f(0, 0)}{t} = \lim_{t \rightarrow 0} \frac{f(tv)}{t} \\ &= \lim_{t \rightarrow 0} \frac{1}{t} \cdot \frac{|tv_1| \cdot tv_2}{\sqrt{t^2 v_1^2 + t^2 v_2^2}} = \lim_{t \rightarrow 0} \frac{|v_1| \cdot v_2}{|t| \cdot \sqrt{v_1^2 + v_2^2}} \\ &= \lim_{t \rightarrow 0} \frac{|v_1| \cdot v_2}{\sqrt{v_1^2 + v_2^2}} = \frac{|v_1| \cdot v_2}{\sqrt{v_1^2 + v_2^2}}. \end{aligned}$$

It follows that $\frac{\partial f}{\partial x_1}(0, 0) = D_{e_1} f(0, 0) = \frac{|1| \cdot 0}{\sqrt{1+0}} = 0$ and

$\frac{\partial f}{\partial x_2}(0, 0) = D_{e_2} f(0, 0) = 0$. Thus, $\nabla f(0, 0) = (0 \ 0)$.

Assume now that f is differentiable at $(0, 0)$. By Proposition 8.28, we must have for all $v = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} \in \mathbb{R}^2$:

$$f'(0, 0)(v) = \nabla f(0, 0) \cdot v = (0 \ 0) \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = 0.$$

Thus, $D_v f(0,0) = f'(0,0)(v) = 0$. Yet, the preceding computations yield for $v = (1,1)$ that $D_v f(0,0) = \frac{1}{\sqrt{2}}$.

We have got a contradiction. Thus, f is not differentiable at $(0,0)$. □

Proposition 9.32

Let D be open in \mathbb{R}^n , $a \in D$ and $f: D \rightarrow \mathbb{R}^m$. Assume that f is partial differentiable on D and that the partial derivatives $\frac{\partial f}{\partial x_1}, \dots, \frac{\partial f}{\partial x_n}$ are continuous at a .

Then f is differentiable at a and $f'(a)$ has as associate matrix the Jacobi matrix $J_f(a)$ of f at a .

Proof

By Propositions 9.15 and Remark 9.24, it follows that it is enough to consider the case $m=1$. We have to prove that $f: D \rightarrow \mathbb{R}$ is differentiable at a and that for all $h = \begin{pmatrix} h_1 \\ \vdots \\ h_n \end{pmatrix} \in \mathbb{R}^n$,

$$f'(a)(h) = J_f(a) \cdot h = \begin{pmatrix} \frac{\partial f}{\partial x_1}(a) & \dots & \frac{\partial f}{\partial x_n}(a) \end{pmatrix} \begin{pmatrix} h_1 \\ \vdots \\ h_n \end{pmatrix} = \sum_{i=1}^n \frac{\partial f}{\partial x_i}(a) \cdot h_i.$$

Let $T \in \mathcal{L}(\mathbb{R}^n, \mathbb{R})$ be defined by $T(h) = \sum_{i=1}^n \frac{\partial f}{\partial x_i}(a) h_i$.

Let $\epsilon > 0$. Since for any $i=1, \dots, n$, the function $\frac{\partial f}{\partial x_i}: D \rightarrow \mathbb{R}$ is continuous at a , there exists $r_i > 0$ s.t. $U_{r_i}(a) \subseteq D$ and

$$(\forall x \in D) \left(x \in U_{r_i}(a) \implies \left| \frac{\partial f}{\partial x_i}(x) - \frac{\partial f}{\partial x_i}(a) \right| < \frac{\epsilon}{n} \right).$$

Let $r := \min_{i=1, \dots, n} r_i$. Then $U_r(a) \subseteq U_{r_i}(a) \subseteq D$ and

$$(1) (\forall i=1, \dots, n) (\forall \epsilon > 0) (x \in U_r(a) \Rightarrow \left| \frac{\partial f}{\partial x_i}(x) - \frac{\partial f}{\partial x_i}(a) \right| < \frac{\epsilon}{n}).$$

Let $x \in U_r(a)$. Then

$$\begin{aligned} f(x) - f(a) - T(x-a) &= f(x_1, x_2, \dots, x_n) - f(a_1, a_2, \dots, a_n) - \sum_{i=1}^n \frac{\partial f}{\partial x_i}(a)(x_i - a_i) \\ &= \left[f(x_1, x_2, \dots, x_n) - f(a_1, x_2, \dots, x_n) - \frac{\partial f}{\partial x_1}(a)(x_1 - a_1) \right] + \\ &\quad + \left[f(a_1, x_2, \dots, x_n) - f(a_1, a_2, x_3, \dots, x_n) - \frac{\partial f}{\partial x_2}(a)(x_2 - a_2) \right] + \\ &\quad + \dots + \\ &\quad + \left[f(a_1, a_2, \dots, a_{n-1}, x_n) - f(a_1, a_2, \dots, a_n) - \frac{\partial f}{\partial x_n}(a)(x_n - a_n) \right]. \end{aligned}$$

For any $i=1, \dots, n$ let us define the real function

$$\varphi_i: [a_i, x_i] \rightarrow \mathbb{R}, \quad \varphi_i(t) = f(a_1, \dots, a_{i-1}, t, x_{i+1}, \dots, x_n) - \frac{\partial f}{\partial x_i}(a) \cdot t,$$

where we have assumed without loss of generality that $a_i \leq x_i$; the same reasoning applies when $x_i \leq a_i$.

Then for any $t \in [a_i, x_i]$ we have that $(a_1, \dots, a_{i-1}, t, x_{i+1}, \dots, x_n) \in D$

$$\text{since } \|(a_1, \dots, a_{i-1}, t, x_{i+1}, \dots, x_n) - (a_1, \dots, a_n)\| = \|(0, \dots, 0, t - a_i, \dots, x_n - a_n)\|$$

$$\| = \sqrt{(t - a_i)^2 + \sum_{k=i+1}^n (x_k - a_k)^2} \leq \sqrt{(x_i - a_i)^2 + \sum_{k=i+1}^n (x_k - a_k)^2} \leq$$

$$\leq \|x - a\| < r, \text{ so } (a_1, \dots, a_{i-1}, t, x_{i+1}, \dots, x_n) \in U_r(a) \subseteq D.$$

$$\text{It follows that } \varphi_i'(t) = \lim_{y \rightarrow t} \frac{\varphi_i(y) - \varphi_i(t)}{y - t}$$

$$= \lim_{y \rightarrow t} \frac{f(a_1, \dots, a_{i-1}, y, x_{i+1}, \dots, x_n) - f(a_1, \dots, a_{i-1}, t, x_{i+1}, \dots, x_n)}{y - t}$$

$$-\frac{\partial f}{\partial x_i}(a) = \frac{\partial f}{\partial x_i}(a_1, \dots, a_{i-1}, x_{i+1}, \dots, x_n) - \frac{\partial f}{\partial x_i}(a)$$

Hence, φ_i is differentiable on $[a_i, x_i]$ so we can apply the Mean Value Theorem from Analysis I to get the existence of $\zeta_i \in]a_i, x_i[$ s.t.

$$\varphi_i(x_i) - \varphi_i(a) = \varphi_i'(\zeta_i)(x_i - a_i).$$

That is,

$$\begin{aligned} & f(a_1, \dots, a_{i-1}, x_i, x_{i+1}, \dots, x_n) - f(a_1, \dots, a_{i-1}, a_i, x_{i+1}, \dots, x_n) - \frac{\partial f}{\partial x_i}(a)(x_i - a_i) = \\ & = \left(\frac{\partial f}{\partial x_i}(a_1, \dots, a_{i-1}, \zeta_i, x_{i+1}, \dots, x_n) - \frac{\partial f}{\partial x_i}(a) \right) \cdot (x_i - a_i). \end{aligned}$$

Hence,

$$\begin{aligned} |f(x) - f(a) - T(x-a)| &\leq \sum_{i=1}^n \left| f(a_1, \dots, a_{i-1}, x_i, x_{i+1}, \dots, x_n) - f(a_1, \dots, a_{i-1}, a_i, x_{i+1}, \dots, x_n) - \frac{\partial f}{\partial x_i}(a)(x_i - a_i) \right| \\ &= \sum_{i=1}^n |\varphi_i(x_i) - \varphi_i(a_i)| = \sum_{i=1}^n \left| \frac{\partial f}{\partial x_i}(a_1, \dots, a_{i-1}, \zeta_i, x_{i+1}, \dots, x_n) - \frac{\partial f}{\partial x_i}(a) \right| \cdot |x_i - a_i| \\ &\stackrel{(1)}{<} \frac{\varepsilon}{n} \cdot \sum_{i=1}^n |x_i - a_i| \leq \frac{\varepsilon}{n} \cdot \sum_{i=1}^n \|x - a\| = \\ &= \frac{\varepsilon}{n} \cdot n \cdot \|x - a\| = \varepsilon \cdot \|x - a\|. \end{aligned}$$

Thus, we have got that

$$(\forall \varepsilon > 0) \left(x \in U_\varepsilon(a) \implies \frac{|f(x) - f(a) - T(x-a)|}{\|x-a\|} < \varepsilon \right)$$

This shows that $\lim_{x \rightarrow a} \frac{|f(x) - f(a) - T(x-a)|}{\|x-a\|} = 0$, that is f is differentiable and $f'(a) = T$.