REGULARITY OF WEAK SOLUTIONS TO THE NAVIER-STOKES EQUATIONS IN EXTERIOR DOMAINS

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ABSTRACT. Let u be a weak solution of the Navier-Stokes equations in an exterior domain $\Omega \subset \mathbb{R}^3$ and a time interval $[0, T[, 0 < T \le \infty, \text{with}$ initial value u_0 , external force $f = \operatorname{div} F$, and satisfying the strong energy inequality. It is well known that global regularity for u is an unsolved problem unless we state additional conditions on the data u_0 and f or on the solution u itself such as Serrin's condition $||u||_{L^s(0,T;L^q(\Omega))} < \infty$ with $2 < s < \infty, \frac{2}{s} + \frac{3}{q} = 1$. In this paper, we generalize results on local in time regularity for bounded domains, see [2], [5], [6], to exterior domains. If e.g. u fulfills Serrin's condition in a left-side neighborhood of t or if the norm $||u||_{L^{s'}(t-\delta,t;L^q(\Omega))}$ converges to 0 sufficiently fast as $\delta \to 0+$, where $\frac{2}{s'} + \frac{3}{q} > 1$, then u is regular at t. The same conclusion holds when the kinetic energy $\frac{1}{2}||u(t)||_2^2$ is locally Hölder continuous with exponent $\alpha > \frac{1}{2}$.

1. INTRODUCTION AND MAIN RESULTS

In this paper, $\Omega \subset \mathbb{R}^3$ is an exterior domain, i.e. an open, connected subset having a nonempty, compact complement in \mathbb{R}^3 , with smooth boundary $\partial \Omega \in C^{2,1}$, and $[0, T[, 0 < T \leq \infty, \text{ denotes the time interval. In } [0, T[\times \Omega \text{ we$ consider the instationary Navier-Stokes equations

$$u_t - \nu \Delta u + u \cdot \nabla u + \nabla p = f \quad \text{in }]0, T[\times \Omega]$$

div $u = 0 \quad \text{in }]0, T[\times \Omega]$
 $u = 0 \quad \text{on }]0, T[\times \partial \Omega]$
 $u = u_0 \quad \text{at } t = 0$
(1.1)

with constant viscosity $\nu > 0$ (fixed throughout this paper), external force $f = \operatorname{div} F = (\sum_{i=1}^{3} \partial_i F_{i,j})_{j=1}^{3}$ and initial value u_0 . First we recall the definition of weak and strong solutions. The space of test functions is defined to be

 $C_0^{\infty}([0,T[;C_{0,\sigma}^{\infty}(\Omega))) := \{ u |_{[0,T[\times\Omega]}; u \in C_0^{\infty}(]-1, T[\times\Omega) ; \text{div} \, u = 0 \}.$

Definition 1.1. Let $\Omega \subset \mathbb{R}^3$ be an exterior domain and let $u_0 \in L^2_{\sigma}(\Omega)$, $f = \operatorname{div} F$ with $F \in L^1_{\operatorname{loc}}([0, T]; L^2(\Omega))$ where $0 < T \leq \infty$. Then a vector field $u \in LH_T$, where LH_T denotes the Leray-Hopf class

$$LH_T := L^{\infty}_{\text{loc}}([0, T[; L^2_{\sigma}(\Omega)) \cap L^2_{\text{loc}}([0, T[; W^{1,2}_{0,\sigma}(\Omega))), \qquad (1.2)$$

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is called *weak solution* (in the sense of *Leray-Hopf*) of the instationary Navier-Stokes system (1.1) with data f, u_0 , if the following identity is satisfied for all test functions $w \in C_0^{\infty}([0, T]; C_{0,\sigma}^{\infty}(\Omega))$:

$$\int_{0}^{T} \left(-\langle u, w_{t} \rangle_{\Omega} + \nu \langle \nabla u, \nabla w \rangle_{\Omega} + \langle u \cdot \nabla u, w \rangle_{\Omega} \right) dt$$

= $\langle u_{0}, w(0) \rangle_{\Omega} - \int_{0}^{T} \langle F, \nabla w \rangle_{\Omega} dt.$ (1.3)

As a consequence of (1.2), (1.3), $u : [0, T[\rightarrow L^2_{\sigma}(\Omega)]$ is - after a possible redefinition on a set of Lebesgue measure 0 - weakly continuous and the initial value u_0 is attained in the sense

$$\langle u(t), \phi \rangle \to \langle u_0, \phi \rangle, \quad t \to 0 + \quad \forall \phi \in L^2_{\sigma}(\Omega).$$

Moreover, there exists a distribution p, called an associated pressure, such that the equality

$$u_t - \nu \Delta u + u \cdot \nabla u + \nabla p = f$$

holds in the sense of distributions on $[0, T] \times \Omega$, see [14, V.1.7].

A weak solution of (1.1) is called a *strong solution* if there exist exponents s, q with $2 < s < \infty$, $3 < q < \infty$, $\frac{2}{s} + \frac{3}{q} = 1$ such that additionally *Serrin's condition*

$$u \in L^s(0, T; L^q(\Omega)) \tag{1.4}$$

is satisfied. By Hölder's inequality, such a strong solution u satisfies $u \otimes u \in L^2_{loc}([0, T[; L^2(\Omega)))$. Moreover, by Serrin's Uniqueness Theorem [14, V. Theorems 1.5.1, 1.4.1], a weak solution with (1.4) is unique within the class of weak solutions satisfying the energy inequality, i.e., fulfilling (1.5) below with s = 0. Finally, $u : [0, T[\to L^2_{\sigma}(\Omega)]$ is strongly continuous and satisfies the energy identity (1.15) below.

For sufficiently smooth Ω, f, u_0 a strong solution u has the regularity property

$$u \in C^{\infty}(]0, T[\times \overline{\Omega}), \quad p \in C^{\infty}(]0, T[\times \overline{\Omega}),$$

see [14, Theorem V.1.8.2], and therefore a strong solution is also called a *regular solution*. We call a weak solution u of (1.1) *regular at* t, if there exists a $\delta = \delta(t) > 0$ with $u \in L^s(t - \delta, t + \delta; L^q(\Omega))$ where s, q satisfy $\frac{2}{s} + \frac{3}{q} = 1$.

Now let $\Omega \subset \mathbb{R}^3$ be an exterior domain with smooth boundary. We know, see [13], that there exists at least one weak solution u of (1.1) satisfying the strong energy inequality

$$\frac{1}{2} \|u(t)\|_{2}^{2} + \nu \int_{s}^{t} \|\nabla u\|_{2}^{2} d\tau \leq \frac{1}{2} \|u(s)\|_{2}^{2} - \int_{s}^{t} \langle F, \nabla u \rangle_{\Omega} d\tau \qquad (1.5)$$

for almost all $s \in [0, T[$ and all $t \in [s, T[$.

Our first main theorem states that if u fulfills the Serrin condition in a left-side neighborhood of t then u is regular at t. Furthermore, it gives conditions depending on $||u||_{L^{s'}(0,T;L^q(\Omega))}$ with $\frac{2}{s'} + \frac{3}{q} > 1$ to imply regularity of u at t; note that in this case, the integrability of u is weaker than in Serrin's condition. **Theorem 1.2.** Let $\Omega \subset \mathbb{R}^3$ be an exterior domain with $\partial \Omega \in C^{2,1}$, let $2 < s < \infty$, $\frac{2}{s} + \frac{3}{q} = 1$, $\frac{1}{3} + \frac{1}{q} = \frac{1}{r}$ and let $1 \leq s' < s$. Assume that $f = \operatorname{div} F$ with $F \in L^s(0,T; L^r(\Omega)) \cap L^4(0,T; L^2(\Omega))$, $u_0 \in L^2_{\sigma}(\Omega)$, $0 < T < \infty$, and let $u \in LH_T$ be a weak solution of the Navier-Stokes equations (1.1) satisfying the strong energy inequality (1.5). Then we have:

(1) Left-side $L^{s}(L^{q})$ -condition. If for $t \in]0, T[$

$$u \in L^{s}(t - \delta, t; L^{q}_{\sigma}(\Omega)) \quad for \ some \ 0 < \delta = \delta(t) < t \,, \tag{1.6}$$

then u is regular at t.

(2) Left-side $L^{s'}(L^q)$ -condition. The condition

$$\liminf_{\delta \to 0+} \frac{1}{\delta^{1-\frac{s'}{s}}} \int_{t-\delta}^{t} \|u(\tau)\|_{q}^{s'} d\tau = 0$$
(1.7)

is necessary and sufficient for regularity of u at t.

(3) Global $L^{s'}(L^q)$ -condition. There exists a constant $\epsilon_* = \epsilon_*(q, s', \Omega) > 0$, independent of f, u_0, T with the following property: If $u_0 \in L^2_{\sigma}(\Omega) \cap L^q_{\sigma}(\Omega)$, $u \in L^{s'}(0, T; L^q_{\sigma}(\Omega))$ and the conditions

$$\int_{0}^{T} \|F(\tau)\|_{r}^{s} d\tau \leq \epsilon_{*} \nu^{2s-1} \quad and \quad \int_{0}^{T} \|u(\tau)\|_{q}^{s'} d\tau \leq \epsilon_{*} \frac{\nu^{s-1}}{\|u_{0}\|_{q}^{s-s'}}$$
(1.8)

are satisfied, then $u \in L^s(0,T;L^q(\Omega))$.

The following theorem states that Hölder continuity of the kinetic energy with exponent $\alpha \in]\frac{1}{2}, 1[$ implies regularity of u at t. In the case $\alpha = \frac{1}{2}$ we need a smallness condition for the corresponding Hölder term under which we can prove regularity of u at t.

Theorem 1.3. Let $\Omega \subset \mathbb{R}^3$ be an exterior domain with boundary $\partial \Omega \in C^{2,1}$, let $0 < T < \infty$ and let u be a weak solution of the Navier-Stokes equations (1.1) satisfying the strong energy inequality (1.5) with initial value $u_0 \in L^2_{\sigma}(\Omega)$ and external force $f = \operatorname{div} F$ which will be specified below. Furthermore, we assume that the kinetic energy $E(t) := \frac{1}{2} ||u(t)||_2^2$ is a continuous function of $t \in [0, T[$. Then we have:

(1) Let $\alpha \in]\frac{1}{2}, 1[, 2 < s' < 4\alpha, 3 < q < 6, \frac{2}{s'} + \frac{3}{q} = \frac{3}{2}, \frac{2}{s} + \frac{3}{q} = 1,$ $f \in L^{\frac{s}{s'}}(0, T; L^2(\Omega))$ and $F \in L^4(0, T; L^2(\Omega)) \cap L^s(0, T; L^r(\Omega)),$ where $\frac{1}{3} + \frac{1}{q} = \frac{1}{r}$, and let u satisfy at $t \in]0, T[$ the left-side condition

$$\sup_{\mu < t' < t} \frac{|E(t) - E(t')|}{|t - t'|^{\alpha}} < \infty$$
(1.9)

with a $\mu > 0$. Then u is regular at t.

t-

(2) (The case $\alpha = \frac{1}{2}$) Let $f \in L^2(0,T;L^2(\Omega))$, $F \in L^4(0,T;L^2(\Omega))$. Then there exists a constant $\gamma_* = \gamma_*(\Omega)$ such that the left-side condition

$$\sup_{t-\mu < t' < t} \frac{|E(t) - E(t')|}{|t - t'|^{\frac{1}{2}}} \le \gamma_* \nu^{\frac{5}{2}}$$
(1.10)

with a $\mu > 0$ implies regularity of u at t.

Remark. (1) The proof of Theorem 1.3, in particular see (4.8), will yield the following regularity criteria using the dissipation energy: If

$$\alpha \in \left]\frac{1}{2}, 1\right[\quad \text{and} \quad \liminf_{\delta \to 0+} \frac{1}{\delta^{\alpha}} \int_{t-\delta}^{t} \|\nabla u(\tau)\|_{2}^{2} d\tau < \infty, \qquad (1.11)$$

or

$$\liminf_{\delta \to 0+} \frac{1}{\delta^{\frac{1}{2}}} \int_{t-\delta}^{t} \|\nabla u(\tau)\|_{2}^{2} d\tau \leq \gamma_{*} \nu^{\frac{3}{2}}$$
(1.12)

then u is regular at t.

(2) In the case $\alpha = \frac{1}{2}$ a smallness condition as in (1.10) and (1.12) is necessary. Indeed, if f = 0 and]0, t[is a maximal regularity interval of u, then

$$\|\nabla u(\tau)\|_2 \ge \frac{c_0}{(t-\tau)^{\frac{1}{4}}}, \quad 0 < \tau < t,$$

where $c_0 = c_0(\Omega) > 0$, see [8]. Hence

$$\liminf_{\delta \to 0+} \frac{1}{\delta^{\frac{1}{2}}} \int_{t-\delta}^{t} \|\nabla u(\tau)\|_{2}^{2} d\tau \ge 2c_{0}^{2} > 0 \,,$$

and due to the strong energy inequality (1.5) it holds for all $\mu > 0$

$$\sup_{t-\mu < t' < t} \frac{|E(t) - E(t')|}{|t - t'|^{\frac{1}{2}}} \ge 2\nu c_0^2 > 0.$$

The proofs of the regularity criteria formulated in this paper are based on a local or global identification of a weak solution with a very weak solution, a concept described in Definition 2.3 below. The following key result, Theorem 1.4, gives conditions under which a given very weak solution is also a weak solution in the sense of Leray-Hopf and, therefore, yields under certain smallness conditions on the data f and u_0 the existence of a unique strong solution of (1.1) on $[0, T] \times \Omega$.

Theorem 1.4. Let $\Omega \subset \mathbb{R}^3$ be an exterior domain with $\partial \Omega \in C^{2,1}$, let $2 < s < \infty$, $\frac{2}{s} + \frac{3}{q} = 1$ and let $\frac{1}{3} + \frac{1}{q} = \frac{1}{q*}$. Then there exists a constant $\epsilon_* = \epsilon_*(q, \Omega) > 0$ with the following property: Given $0 < T < \infty$ and data $u_0 \in L^2_{\sigma}(\Omega) \cap L^q_{\sigma}(\Omega)$ and $f = \operatorname{div} F$ with $F \in L^s(0, T; L^{q*}(\Omega)) \cap L^4(0, T; L^2(\Omega))$ satisfying the following two conditions:

$$\int_{0}^{T} \|F(\tau)\|_{q_{*}}^{s} d\tau \leq \epsilon_{*} \nu^{2s-1}, \qquad (1.13)$$

$$\int_{0}^{T} \|e^{-\nu\tau A_{q}} u_{0}\|_{q}^{s} d\tau \leq \epsilon_{*} \nu^{s-1}.$$
(1.14)

In this case, there exists a unique weak solution $u \in LH_T$ of (1.1) satisfying the Serrin condition $u \in L^s(0,T; L^q(\Omega))$. After a possible redefinition on a set of Lebesgue measure 0, we get that $u : [0,T[\rightarrow L^2_{\sigma}(\Omega)]$ is strongly continuous and it holds the energy identity

$$\frac{1}{2} \|u(t)\|_{2}^{2} + \nu \int_{0}^{t} \|\nabla u\|_{2}^{2} d\tau = \frac{1}{2} \|u_{0}\|_{2}^{2} - \int_{0}^{t} \langle F, \nabla u \rangle_{\Omega} d\tau$$
(1.15)

for all $t \in [0, T[.$

The proof of this crucial result is the content of Section 3 and differs from the case of bounded domains, see [4], [6], where the trivial inclusion $L^q(\Omega) \subset$ $L^r(\Omega), q > r$, yielding also better embedding properties of fractional powers of the Stokes operator, was used several times. The main idea of the proof is to construct a very weak solution $v \in L^s(0, T; L^q_{\sigma}(\Omega))$ for the given data u_0, f and to identify u and v by Serrin's Uniqueness Theorem; for this reason, we have to show that v lies in the Leray-Hopf class LH_T .

After some preliminaries to be discussed in Section 2 we prove Theorem 1.4 in Section 3. Finally, Section 4 deals with the proofs of the main results Theorem 1.2 and 1.3.

2. Preliminaries

Given $1 \leq q \leq \infty, k \in \mathbb{N}$ we need the usual Lebesgue and Sobolev spaces, $L^q(\Omega), W^{k,q}(\Omega)$ with norm $\|\cdot\|_{L^q(\Omega)} = \|\cdot\|_q$ and $\|\cdot\|_{W^{k,q}(\Omega)} = \|\cdot\|_{k,q}$, respectively. For two measurable functions f, g with the property $f \cdot g \in L^1(\Omega)$, where $f \cdot g$ means the usual scalar product of vector or matrix fields, we set

$$\langle f,g \rangle_{\Omega} := \int_{\Omega} f(x) \cdot g(x) \, dx.$$

Note that the same symbol $L^q(\Omega)$ etc. will be used for spaces of scalar-, vector or matrix-valued functions. Let $C^m(\Omega)$, $m = 0, 1, \ldots, \infty$, denote the usual space of functions for which all partial derivatives of order $|\alpha| \leq m$ exist and are continuous. As usual, $C_0^m(\Omega)$ is the set of all functions from $C^m(\Omega)$ with compact support in Ω . Further we need the space of smooth solenoidal vector fields

$$C^{\infty}_{0,\sigma}(\Omega) := \{ v \in C^{\infty}_0(\Omega)^3; \operatorname{div} v = 0 \}$$

and define the spaces

$$L^{q}_{\sigma}(\Omega) := \overline{C^{\infty}_{0,\sigma}(\Omega)}^{\|\cdot\|_{q}}, \quad W^{1,2}_{0,\sigma}(\Omega) := \overline{C^{\infty}_{0,\sigma}(\Omega)}^{\|\cdot\|_{W^{1,2}}}.$$

For $1 \leq q \leq \infty$ let $q' \in [1, \infty]$ denote its dual exponent. It is well known that $L^q_{\sigma}(\Omega)' = L^{q'}_{\sigma}(\Omega)$ using the standard pairing $\langle \cdot, \cdot \rangle_{\Omega}$. Moreover, let us write $[d, v]_{\Omega}$ for the application of a distribution $d \in C_0^{\infty}(\Omega)'$ on a test function $v \in C_0^{\infty}(\Omega)$.

Given a Banach space X and an interval [0,T], $0 < T \leq \infty$, we denote by $L^p(0,T;X)$, $1 \leq p \leq \infty$, the space of all equivalence classes of strongly measurable functions $f:[0,T) \to X$ such that

$$\|f\|_p := \left(\int_0^T \|f(t)\|_X^p \, dt\right)^{\frac{1}{p}} < \infty$$

if $p < \infty$, and $||f||_{\infty} := \operatorname{ess\,sup}_{[0,T[} ||f(\cdot)||_X)$, if $p = \infty$. Moreover, we define the set of *locally integrable* L^p -functions on [0,T[as

$$L^{p}_{loc}([0, T[; X) := \{ u : [0, T[\to X \text{ strongly measurable}, u \in L^{p}(0, T'; X) \text{ for all } 0 < T' < T \}.$$

When $X = L^q(\Omega)$, $1 \le q \le \infty$, we denote the norm in $L^p(0,T; L^q(\Omega))$ by $\|\cdot\|_{q,p,\Omega;T}$. For $1 < p, q < \infty$ it holds

$$L^{p}(0,T;L^{q}(\Omega))' = L^{p'}(0,T;L^{q'}(\Omega))$$

and we define

$$\langle f, g \rangle_{\Omega,T} := \int_0^T \int_\Omega f(t, x) \cdot g(t, x) \, dx \, dt$$

for $f \in L^{p}(0,T; L^{q}(\Omega)), g \in L^{p'}(0,T; L^{q'}(\Omega)).$

Given an exterior domain $\Omega \subset \mathbb{R}^3$ with $\partial \Omega \in C^{2,1}$ and $1 < q < \infty$, there exists a bounded, linear projection $P_q : L^q(\Omega) \to L^q_\sigma(\Omega)$ with range $\mathcal{R}(P_q) = L^q_\sigma(\Omega)$ and nullspace $N(P_q) = \{\nabla p \in L^q(\Omega) ; p \in L^q_{loc}(\overline{\Omega})\}$. The operator P_q is called *Helmholtz projection* and is *consistent* in the sense that

$$P_q f = P_r f \qquad \forall f \in L^q(\Omega) \cap L^r(\Omega).$$
(2.1)

Furthermore, we get $P'_q = P_{q'}$ for the dual operator, i.e.,

$$\langle P_q f, g \rangle_{\Omega} = \langle f, P_{q'} g \rangle_{\Omega} \quad \forall f \in L^q(\Omega) \quad \forall g \in L^{q'}(\Omega).$$
 (2.2)

For $1 < q < \infty$ we define the *Stokes operator* A_q on $L^q_{\sigma}(\Omega)$ by

$$\mathcal{D}(A_q) = L^q_{\sigma}(\Omega) \cap W^{1,q}_0(\Omega) \cap W^{2,q}(\Omega), \qquad (2.3)$$

$$A_q u := -P_q \Delta u, \quad u \in \mathcal{D}(A_q). \tag{2.4}$$

The Stokes operator is *consistent* in the sense that for $1 < q, r < \infty$ it holds

$$A_q u = A_r u \quad \forall u \in \mathcal{D}(A_q) \cap \mathcal{D}(A_r).$$
(2.5)

In general, $\mathcal{D}(A_q)$ will be equipped with the graph norm $||u||_{\mathcal{D}(A_q)} := ||u||_q + ||A_q||_q$ for $u \in D(A_q)$ which makes $\mathcal{D}(A_q)$ to a Banach space since the Stokes operator is closed. For simplicity, we use the notation $A = A_2$.

For $\alpha \in [-1, 1]$ the fractional power $A_q^{\alpha} : \mathcal{D}(A_q^{\alpha}) \to L_{\sigma}^q(\Omega)$ with dense domain $\mathcal{D}(A_q^{\alpha}) \subseteq L_{\sigma}^q(\Omega)$) is a well defined, injective, closed operator such that

$$(A_q^{\alpha})^{-1} = A_q^{-\alpha}, \quad \mathcal{R}(A_q^{\alpha}) = \mathcal{D}(A_q^{-\alpha}) \text{ and } \quad (A_q^{\alpha})' = A_{q'}^{\alpha}.$$

It holds $\mathcal{D}(A_q^{1/2}) = W_0^{1,q}(\Omega) \cap L_{\sigma}^q(\Omega)$ for 1 < q < 3, and the estimate

$$\|\nabla u\|_{q,\Omega} \le c \|A_q^{1/2}u\|_{q,\Omega} \quad \text{for } 1 < q < 3, \ u \in \mathcal{D}(A_q^{1/2}),$$
(2.6)

with a constant $c = c(\Omega, q) > 0$. Moreover,

$$\|u\|_{\gamma,\Omega} \le c \|A_q^{\alpha}u\|_{q,\Omega} \quad \text{where } 0 \le \alpha \le \frac{1}{2}, 1 < q < 3, 2\alpha + \frac{3}{\gamma} = \frac{3}{q}, \quad (2.7)$$

for all $u \in \mathcal{D}(A_q^{\alpha})$ with a constant $c = c(\Omega, q, \gamma) > 0$. It is well known that $-A_q$ generates a uniformly bounded analytic semigroup $\{e^{-tA_q} : t \ge 0\}$ on $L_{\sigma}^q(\Omega)$ satisfying the decay estimate

$$\|A_q^{\alpha} e^{-tA_q}\|_q \le ct^{-\alpha} \quad \forall t > 0, \qquad (2.8)$$

where $\alpha \ge 0, 1 < q < \infty$ and $c = c(\Omega, q, \alpha) > 0$.

Lemma 2.1. Let $d \in C_0^{\infty}(\Omega)'$ be a distribution, well defined for all $v \in \mathcal{D}(A_{q'}^{\alpha})$ where $1 < q < \infty, 0 < \alpha \leq 1$. We assume that there exists a constant $c \geq 0$, independent of $v \in \mathcal{D}(A_{q'}^{\alpha})$, such that

$$|[d, v]_{\Omega}| \le c \|A_{q'}^{\alpha}v\|_{q',\Omega} \quad \forall v \in \mathcal{D}(A_{q'}^{\alpha}).$$

$$(2.9)$$

Then there exists a unique element $d \in L^q_{\sigma}(\Omega)$, to be denoted by $A^{-\alpha}_q P_q d$, with the properties

$$\langle A_q^{-\alpha} P_q d, A_{q'}^{\alpha} v \rangle_{\Omega} = [d, v]_{\Omega} \quad \forall v \in \mathcal{D}(A_{q'}^{\alpha}) \quad and \ \|A_q^{-\alpha} P_q d\|_q \le c \quad (2.10)$$

with the constant c from (2.9). In particular, if $F \in L^q(\Omega)$, and $\frac{3}{2} < q < \infty$, then $A_q^{-\frac{1}{2}} P_q \operatorname{div} F \in L^q_{\sigma}(\Omega)$ and

$$\|A_q^{-\frac{1}{2}}P_q \operatorname{div} F\|_q \le c \|F\|_q.$$
(2.11)

Proof. We define for $w \in \mathcal{R}(A_{q'}^{\alpha})$

$$[\widetilde{d}, w]_{\Omega} := [d, v]_{\Omega}, \quad \text{where } w = A_{q'}^{\alpha} v, v \in \mathcal{D}(A_{q'}^{\alpha}).$$

By the density of $\mathcal{R}(A_{q'}^{\alpha})$ in $L_{\sigma}^{q'}(\Omega)$, we extend \tilde{d} to a functional defined on $L_{\sigma}^{q'}(\Omega)$. We use $L_{\sigma}^{q'}(\Omega)' = L_{\sigma}^{q}(\Omega)$ to obtain a unique element $A_{q}^{-\alpha}P_{q}d \in L_{\sigma}^{q}(\Omega)$ satisfying the identity in (2.10). For the proof of (2.11) we exploit (2.6) with q replaced by $q' \in]1,3[$.

Theorem 2.2. Let $\Omega \subset \mathbb{R}^3$ be an exterior domain with $\partial \Omega \in C^{2,1}$, let $1 < q, s < \infty$ and $0 < T < \infty$. Furthermore, let $f \in L^s(0,T; L^q_{\sigma}(\Omega))$ and $u_0 \in L^q_{\sigma}(\Omega)$ such that $\int_0^\infty \|A_q e^{-tA_q} u_0\|_{q,\Omega}^s dt < \infty$. Then the instationary Stokes system

$$u_t + \nu A_q u = f$$
 in $(0, T)$
 $u(0) = u_0$ (2.12)

has a unique strong solution $u \in L^s(0,T; D(A_q))$ with $u_t \in L^s(0,T; L^q_{\sigma}(\Omega))$ and $u \in C([0,T[; L^q_{\sigma}(\Omega)))$. Moreover, u satisfies the maximal regularity estimate

$$\|u_t\|_{q,s,\Omega;T} + \|\nu A_q u\|_{q,s,\Omega;T} \le c \left(\left(\int_0^T \|\nu A_q e^{-\nu t A_q} u_0\|_{q,\Omega}^s dt \right)^{\frac{1}{s}} + \|f\|_{q,s,\Omega;T} \right)$$
(2.13)

with a constant $c = c(\Omega, q, s)$ independent of T und ν . It holds the representation

$$u(t) = e^{-\nu t A_q} u_0 + \int_0^t e^{-\nu (t-\tau)A_q} f(\tau) \, d\tau \tag{2.14}$$

for all $t \in [0, T[$. In the case $T = \infty$ we get a unique strong solution $u \in L^s_{loc}(0, \infty; D(A_q))$ of (2.12) satisfying $u_t \in L^s(0, \infty; L^q_{\sigma}(\Omega))$ and $u \in C([0, \infty]; L^q_{\sigma}(\Omega))$ and it holds the estimate (2.13) and the representation (2.14) for all $t \in [0, \infty]$.

Proof. See [10, Theorem 4.2].

A major tool for the proof of Theorem 1.4 is the theory of very weak solutions. In this context we refer to [3] for exterior domains and to [4] for bounded domains. In the following definition let

$$C_0^1([0,T[;C_{0,\sigma}^2(\bar{\Omega}))) := \{ w \mid_{[0,T[\times\bar{\Omega}]} \text{ with } w \in C_0^{1,2}(-]1, T[\times\mathbb{R}^3); \qquad (2.15)$$

liv
$$w = 0, w|_{\partial\Omega} = 0$$
 for all $t \in [0, T[]$ (2.16)

denote the space of test functions and let

$$\mathcal{J}^{q,s}(\Omega) := \{ u_0 \in C_0^\infty(\Omega)';$$
(2.17)

$$A_{q}^{-1}P_{q}u_{0} \in L_{\sigma}^{q}(\Omega), \int_{0}^{\infty} \|A_{q}e^{-tA_{q}}(A_{q}^{-1}P_{q}u_{0})\|_{q,\Omega}^{s} dt < \infty \}$$
(2.18)

denote the space of initial values.

Definition 2.3. Let $\Omega \subset \mathbb{R}^3$ be an exterior domain, let $F \in L^s(0,T; L^r(\Omega))$ and $u_0 \in \mathcal{J}^{q,s}(\Omega)$ where $2 < s < \infty$, $\frac{2}{s} + \frac{3}{q} = 1$, $\frac{1}{3} + \frac{1}{q} = \frac{1}{r}$. Then $u \in L^s(0,T; L^q_{\sigma}(\Omega))$ is called *very weak solution* of the instationary Navier-Stokes equations (1.1) if

$$\int_0^T \langle -u, w_t \rangle_{\Omega} - \nu \langle u, \Delta w \rangle_{\Omega} - \langle u \otimes u, \nabla w \rangle_{\Omega} \, dt = [u_0, w(0)]_{\Omega} - \int_0^T \langle F, \nabla w \rangle_{\Omega} \, dt$$
(2.19)

holds for all test functions $w \in C_0^1([0,T[;C_{0,\sigma}^2(\bar{\Omega})))$.

In the corresponding definition of very weak solutions to the linear, instationary Stokes system where the nonlinear term $u \cdot \nabla u$ is absent, we may omit in Definition 2.3 the restriction $\frac{2}{s} + \frac{3}{q} = 1$, and in (2.19) the term $\langle u \otimes u, \nabla w \rangle_{\Omega,T}$ is absent. A proof of the following Theorem can be found in [3], [12].

Theorem 2.4. Let $\Omega \subset \mathbb{R}^3$ be an exterior domain with $\partial \Omega \in C^{2,1}$ and let $2 < s < \infty$, $\frac{2}{s} + \frac{3}{q} = 1$, $\frac{1}{3} + \frac{1}{q} = \frac{1}{r}$. Then there exists a constant $c = c(q, \Omega) > 0$ with the following property: For data $f = \operatorname{div} F$ with $F \in L^s(0, T; L^r(\Omega))$ and $u_0 \in \mathcal{J}^{q,s}(\Omega)$, satisfying the condition

$$\left(\int_{0}^{T} \|\nu A_{q} e^{-\nu t A_{q}} (A_{q}^{-1} P_{q} u_{0})\|_{q,\Omega}^{s} dt\right)^{\frac{1}{s}} + \|F\|_{r,s,\Omega;T} \le c\nu^{1+\alpha}$$
(2.20)

with $\alpha := \frac{3}{2q} + \frac{1}{2} = 1 - \frac{1}{s}$, there exists a unique very weak solution $u \in L^s(0,T; L^{\sigma}_{\sigma}(\Omega))$ of the instationary Navier-Stokes system (1.1). Moreover, u has the representation $u = E + \tilde{u}$, where $E \in L^s(0,T; L^{q}_{\sigma}(\Omega))$ is the unique very weak solution of the linear Stokes system with data f, u_0 and \tilde{u} is the unique solution in $L^s(0,T; L^{q}_{\sigma}(\Omega))$ of the nonlinear fixed point equation

$$\tilde{u}(t) = -\int_0^t A_q^{\alpha} e^{-\nu(t-\tau)A_q} A_q^{-\alpha} P_q \operatorname{div}\left(\left(\tilde{u}(\tau) + E(\tau)\right) \otimes \left(\tilde{u}(\tau) + E(\tau)\right)\right) d\tau$$
(2.21)

for almost all $t \in [0, T[$.

Finally we recall the Hardy-Littlewood inequality [14, II Lemma 3.3.2]. Let $0 < \alpha < 1, 1 < r < q < \infty$ with $\alpha + \frac{1}{q} = \frac{1}{r}$ and let $f \in L^r(\mathbb{R})$. Then the integral

$$u(t) := \int_{\mathbb{R}} |t - \tau|^{\alpha - 1} f(\tau) \, d\tau$$

converges absolutely for almost all $t \in \mathbb{R}$ and it holds

$$||u||_{L^q(\mathbb{R})} \le c||f||_{L^r(\mathbb{R})}$$
 (2.22)

with a constant $c = c(\alpha, q) > 0$.

3. Proof of Theorem 1.4

Before proving Theorem 1.4 we discuss the nonlinear term arising in the nonlinear fixed point problem (2.21). We denote by $\operatorname{div}(u \otimes u)$ the functional defined for suitable vector fields w by

$$[\operatorname{div}(u\otimes u),w]_{\Omega}:=-\langle u\otimes u,\nabla w\rangle_{\Omega}.$$

The following lemma is technical but essential for Lemma 3.2 below.

Lemma 3.1. Let $\Omega \subset \mathbb{R}^3$ be an exterior domain with boundary $\partial \Omega \in C^{2,1}$, let $3 < q < \infty, r \in [\frac{q}{2}, q]$ and $\beta := \frac{3}{q} - \frac{3}{2r} + \frac{1}{2}$.

(1) There exists a constant $c = c(\Omega, q, r) > 0$ such that for all $u \in L^q_{\sigma}(\Omega)$

$$\|A_r^{-\beta}P_r\operatorname{div}(u\otimes u)\|_{r,\Omega} \le c\|u\|_{q,\Omega}^2.$$
(3.1)

(2) For $2 < s < \infty$, $3 < q < \infty$, $0 < T \le \infty$ there exists a constant $c = c(\Omega, q, r) > 0$ such that for all $u \in L^s(0, T; L^q_{\sigma}(\Omega))$

$$\|A_r^{-\beta}P_r\operatorname{div}(u\otimes u)\|_{r,\frac{s}{2},\Omega;T} \le c\|u\|_{q,s,\Omega;T}^2.$$
(3.2)

Proof. The assumptions of the lemma imply

$$2(\beta - \frac{1}{2}) + \frac{3}{\left(\frac{q}{2}\right)'} = \frac{3}{r'} \quad \text{with } 1 < r' < 3, \frac{1}{2} \le \beta < 1.$$
(3.3)

Then we get for arbitrary $w \in \mathcal{D}(A_{r'}^{\beta})$ by (2.6) using $1 < \left(\frac{q}{2}\right)' < 3$, (2.7) and (2.5) (applied to $A^{1/2}$ instead of A)

$$\begin{split} |[\operatorname{div}(u \otimes u), w]| &= | - \langle u \otimes u, \nabla w \rangle | \\ &\leq \| u \otimes u \|_{\frac{q}{2}} \| \nabla w \|_{\left(\frac{q}{2}\right)'} \\ &\leq c \| u \|_{q}^{2} \| A_{(q/2)'}^{1/2} w \|_{\left(\frac{q}{2}\right)'} \\ &\leq c \| u \|_{q}^{2} \| A_{r'}^{(\beta - \frac{1}{2})} (A_{(q/2)'}^{1/2} w) \|_{r} \\ &\leq c \| u \|_{q}^{2} \| A_{r'}^{\beta} w \|_{r'}. \end{split}$$

It is possible to choose the constant c > 0 in the above estimate depending only on Ω , q and r. For the second assertion we use (3.1), which holds for almost all $t \in [0, T[$, and integrate over [0, T].

Lemma 3.2. Let $\Omega \subset \mathbb{R}^3$ be an exterior domain with $\partial \Omega \in C^{2,1}$, let $0 < T \leq \infty, 2 < s < \infty, \frac{2}{s} + \frac{3}{q} = 1$ and let $u \in L^s(0,T;L^q(\Omega))$. We define for $r \in [\frac{q}{2},q]$ and $\beta := \frac{3}{q} - \frac{3}{2r} + \frac{1}{2}$ the term $\Lambda^r(u)$ by

$$\Lambda^r u(t) := -\int_0^t A_r^\beta e^{-\nu(t-\tau)A_r} A_r^{-\beta} P_r \operatorname{div}(u(\tau) \otimes u(\tau)) \, d\tau \,. \tag{3.4}$$

Then the following statements are satisfied.

(1) For almost all $t \in [0, T[$ we get

$$\int_0^t \|A_r^\beta e^{-\nu(t-\tau)A_r} A_r^{-\beta} P_r \operatorname{div}(u(\tau) \otimes u(\tau))\|_r \, d\tau < \infty$$
(3.5)

and

$$-A_r^{\beta} \int_0^t e^{-\nu(t-\tau)A_r} A_r^{-\beta} P_r \operatorname{div}(u(\tau) \otimes u(\tau)) d\tau$$

= $-\int_0^t A_r^{\beta} e^{-\nu(t-\tau)A_r} A_r^{-\beta} P_r \operatorname{div}(u(\tau) \otimes u(\tau)) d\tau.$ (3.6)

(2) For all $r_1, r_2 \in [\frac{q}{2}, q]$ with $\beta_1 := \frac{3}{q} - \frac{3}{2r_1} + \frac{1}{2}$, $\beta_2 := \frac{3}{q} - \frac{3}{2r_2} + \frac{1}{2}$ it holds

$$\Lambda^{r_1}u(t) = \Lambda^{r_2}u(t) \qquad \text{for almost all } t \in [0, T[. \tag{3.7})$$

Therefore, we can denote the expression in (3.4), independently of $r \in [\frac{q}{2}, q]$, by $\Lambda(u)$.

(3) For all $q_1 \in [\frac{q}{2}, q]$ with $3 < q_1 < \infty$ and $s_1 > 2$ defined by $\frac{2}{s_1} + \frac{3}{q_1} = 1$ we have

$$\Lambda u \in L^{s_1}(0, T; L^{q_1}(\Omega)).$$
(3.8)

(4) If $q \in]3, 6[$ then

$$\Lambda u \in L^{\frac{s}{2}}(0,T;L^{q_2}(\Omega)) \tag{3.9}$$

where $q_2 > 3$ satisfies $\frac{1}{3} + \frac{1}{q_2} = \frac{1}{\left(\frac{q}{2}\right)}$ and consequently $\frac{2}{\left(\frac{s}{2}\right)} + \frac{3}{q_2} = 1$.

Proof. (1) By (2.8) and (3.1) we know that for all $t \in [0, T[$

$$\int_{0}^{t} \|A_{r}^{\beta} e^{-\nu(t-\tau)A_{r}} A_{r}^{-\beta} P_{r} \operatorname{div} (u(\tau) \otimes u(\tau))\|_{r} d\tau \\
\leq c(\Omega, q, r) \nu^{-\beta} \int_{0}^{T} |t-\tau|^{-\beta} \|u(\tau)\|_{q}^{2} d\tau.$$
(3.10)

Moreover, as for almost all $t \in [0, T[$ the integral in (3.10) is finite (see the application of the Hardy-Littlewood inequality (2.22) in the proof of part (3) below) and

$$\int_0^t \|e^{-\nu(t-\tau)A_r}A_r^{-\beta}P_r\operatorname{div}(u\otimes u)\|_r\,d\tau \le c\int_0^t \|A_r^{-\beta}P_r\operatorname{div}(u\otimes u)\|_r\,d\tau < \infty\,,$$

the closedness of the operator A_r^{β} yields the identity (3.6).

(2) To prove (3.7) for $t \in (0, T[$ as in (1) let

$$\begin{split} f_t^r(\tau) &:= A_r^\beta e^{-\nu(t-\tau)A_r} A_r^{-\beta} P_r \text{div}(u(\tau) \otimes u(\tau)) \quad \text{for almost all } \tau \in]0, t[\,, \\ \text{where } \beta &= \beta(r) = \frac{3}{q} - \frac{3}{2r} + \frac{1}{2}. \text{ Since for all } \phi \in C_{0,\sigma}^{\infty}(\Omega) \end{split}$$

$$\int_0^t \langle f_t^{r_1}(\tau), \phi \rangle_\Omega \, d\tau = -\int_0^t \langle u(\tau) \otimes u(\tau), \nabla e^{-\nu(t-\tau)A_{r'}} \phi \rangle_\Omega \, d\tau \,,$$

we see that

$$\int_0^t \langle f_t^{r_1}(\tau), \phi \rangle_\Omega \, d\tau = \int_0^t \langle f_t^{r_2}(\tau), \phi \rangle_\Omega \, d\tau = \int_0^t \langle f_t^{r$$

for details of the proof we refer to [12]. A density argument finishes the proof of (3.7).

(3) We consider (3.10) and use the Hardy-Littlewood inequality (2.22) with $(1 - \beta) + \frac{1}{s_1} = \frac{1}{(\frac{s}{2})}$ to conclude with $\Lambda^{q_1} u = \Lambda u$ and (3.2) that

 $\|\Lambda u\|_{q_1,s_1,\Omega;T}$

$$\leq \left(\int_{0}^{T} \left(c\nu^{-\beta} \int_{0}^{T} |t - \tau|^{-\beta} \|A_{q_{1}}^{-\beta} P_{q_{1}} \operatorname{div}(u(\tau) \otimes u(\tau))\|_{q_{1}} d\tau \right)^{s_{1}} dt \right)^{\frac{1}{s_{1}}} \\ \leq c\nu^{-\beta} \|A_{q_{1}}^{-\beta} P_{q_{1}} \operatorname{div}(u(\tau) \otimes u(\tau))\|_{q_{1},\frac{s}{2},\Omega;T} \\ \leq c(q,q_{1},\Omega)\nu^{-\beta} \|u\|_{q,s,\Omega;T}^{2} < \infty.$$

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(4) From $2\frac{1}{2} + \frac{3}{q_2} = \frac{3}{\left(\frac{q}{2}\right)}$ and (2.7) it follows with (3.6) and $\beta = \frac{1}{2}, r = \frac{q}{2}$, for almost all $t \in [0, T[$

$$\begin{aligned} \|\Lambda^{q_2} u(t)\|_{q_2} &\leq \|A_{\frac{q}{2}}^{1/2} \Lambda u(t)\|_{\frac{q}{2}} \\ &= \|A_{\frac{q}{2}} \int_0^t e^{-\nu(t-\tau)A_{\frac{q}{2}}} A_{\frac{q}{2}}^{-1/2} P_{\frac{q}{2}} \mathrm{div}(u(\tau) \otimes u(\tau)) \, d\tau\|_{\frac{q}{2}}. \end{aligned}$$
(3.11)

Since by (3.2)

$$A_{\frac{q}{2}}^{-1/2} P_{\frac{q}{2}} \operatorname{div}(u \otimes u) \in L^{\frac{s}{2}}(0, T; L^{\frac{q}{2}}(\Omega)), \qquad (3.12)$$

the maximal regularity estimate (2.13) yields the last statement of the lemma. $\hfill\square$

Proof of Theorem 1.4. Given the smallness conditions (1.13) and (1.14), Theorem 2.4 implies the existence of a unique very weak solution $u \in L^s(0,T; L^q_{\sigma}(\Omega))$ of (1.1). Moreover, we know the representation $u = E + \tilde{u}$, where the linear part E satisfies

$$E(t) = e^{-\nu t A_q} u_0 + A_q \int_0^t e^{-\nu (t-\tau)A_q} (A_q^{-1} P_q \operatorname{div} F(\tau)) \, d\tau$$
(3.13)

in [0, T[and the nonlinear part $\tilde{u} \in L^s(0, T; L^q_{\sigma}(\Omega))$ solves the fixed point equation

$$\tilde{u}(t) = -\int_0^t A_q^{\alpha} e^{-\nu(t-\tau)A_q} A_q^{-\alpha} P_q \operatorname{div}\left(\left(\tilde{u}(\tau) + E(\tau)\right) \otimes \left(\tilde{u}(\tau) + E(\tau)\right)\right) d\tau$$
(3.14)

(3.14) with $\alpha := \frac{3}{2q} + \frac{1}{2}$ for almost all $t \in [0, T[$. Since $F \in L^2(0, T; L^2(\Omega))$ and $u_0 \in L^2_{\sigma}(\Omega)$ it follows with (2.5) that

$$E(t) = E_1(t) + E_2(t) := e^{-\nu tA} u_0 + A^{1/2} \int_0^t e^{-\nu(t-\tau)A} A^{-1/2} P \operatorname{div} F(\tau) d\tau$$
(3.15)

almost everywhere. We use [14, IV Theorems 2.3.1, 2.4.1] to obtain that E lies in the Leray-Hopf class (1.2) and is a weak solution of the linear stationary Stokes system with data f, u_0 . To finish the proof, we want to show that

$$u \in L^8(0, T; L^4(\Omega)).$$
 (3.16)

The validity of the above property implies

$$u \otimes u \in L^2(0,T;L^2(\Omega)).$$
(3.17)

As a consequence of (3.14) and (3.17) we conclude that \tilde{u} lies in the Leray-Hopf class (1.2) and \tilde{u} is the unique weak solution of the linear, stationary Stokes system with the external force div $(u \otimes u)$ and vanishing initial value, see [14, IV Theorems 2.3.1, 2.4.1]. Furthermore, from these two Theorems and $\langle u \otimes u, \nabla u \rangle(\tau) = 0$ almost everywhere, it follows that u is, after a possible redefinition on a set of Lebesgue measure 0, strongly continuous and satisfies the energy equality (1.15).

Since in the case q = 4 (and s = 8) there is nothing left to be proved, we may assume in the proof of (3.16) that $q \neq 4$.

Assertion 1: $E = E_1 + E_2 \in L^8(0, T; L^4(\Omega)).$

Proof. In the case $4 < q < \infty$ it is easily seen since $L^2_{\sigma}(\Omega) \cap L^q_{\sigma}(\Omega) \subset L^4_{\sigma}(\Omega)$ that $E_1(t) = e^{-\nu tA}u_0 = e^{-\nu tA_q}u_0 \in L^8(0,T;L^4(\Omega))$. If 3 < q < 4 we use [11, Theorem 1.2 (ii)] to find a constant c > 0, independent of t, such that

$$\|e^{-\nu t A_4} u_0\|_4 \le c t^{-\frac{3}{2}(\frac{1}{q} - \frac{1}{4})} \|u_0\|_q$$

for all t > 0. The estimate

$$\int_0^T \|e^{-\nu t A_4} u_0\|_4^8 \, dt \le c \|u_0\|_q^8 \int_0^T t^{-12(\frac{1}{q} - \frac{1}{4})} \, dt < \infty$$

implies $E_1 \in L^8(0,T; L^4(\Omega))$. To get the property $E_2 \in L^8(0,T; L^4(\Omega))$ we estimate for almost all $t \in [0,T[$, using (2.7), (2.8) and (2.11), that

$$\begin{aligned} \|E_{2}(t)\|_{4} &\leq c \|A^{3/8} E_{2}(t)\|_{2} \\ &= c \left\| \int_{0}^{t} A^{7/8} e^{-\nu(t-\tau)A} A^{-1/2} P \operatorname{div} F(\tau) \, d\tau \right\|_{2} \\ &\leq c \nu^{-7/8} \int_{0}^{T} |t-\tau|^{-7/8} \|F(\tau)\|_{2} \, d\tau \,. \end{aligned}$$
(3.18)

Then an application of the Hardy-Littlewood inequality (2.22) yields

$$||E_2||_{4,8,\Omega;T} \le c\nu^{-\frac{1}{8}} ||F||_{2,4,\Omega;T} < \infty.$$

Assertion 2: Let 3 < q < 4. Then $\tilde{u} \in L^8(0,T; L^4(\Omega))$.

Proof. We use an iterative argument to improve the regularity in space step by step. Assume that for almost all $t \in [0, T[$ with certain parameters s_k, r_k, β_k

$$\tilde{u}(t) = -\int_{0}^{t} A_{r_{k}}^{\beta_{k}} e^{-\nu(t-\tau)A_{r_{k}}} A_{r_{k}}^{-\beta_{k}} P_{r_{k}} \operatorname{div}((\tilde{u}+E) \otimes (\tilde{u}+E)) d\tau, \qquad (3.19)$$

$$\tilde{u}, E \in L^{s_k}(0, T; L^{r_k}(\Omega)) \text{ with } 3 < r_k < 4, \frac{2}{s_k} + \frac{3}{r_k} = 1, \beta_k \in [\frac{1}{2}, 1].$$
 (3.20)

For k = 1 the iteration starts with $s_1 := s$, $r_1 := q$ and $\beta_1 := \frac{3}{2q} + \frac{1}{2} = \alpha$, see (3.14). We denote by $r_{k+1} > r_k$ the unique element satisfying $\frac{1}{3} + \frac{1}{r_{k+1}} = \frac{1}{r_k/2}$ and set $s_{k+1} := \frac{s_k}{2}$. Then (3.9) implies that

$$\tilde{u} \in L^{s_{k+1}}(0,T;L^{r_{k+1}}(\Omega)).$$
 (3.21)

We define $\beta_{k+1} := \frac{3}{r_{k+1}} - \frac{3}{2r_{k+1}} + \frac{1}{2} = \frac{3}{2r_{k+1}} + \frac{1}{2}$ and get with (3.7)

$$\tilde{u}(t) = -\int_0^t A_{r_{k+1}}^{\beta_{k+1}} e^{-\nu(t-\tau)A_{r_{k+1}}} A_{r_{k+1}}^{-\beta_{k+1}} P_{r_{k+1}} \operatorname{div}((\tilde{u}+E)\otimes(\tilde{u}+E)) \, d\tau.$$
(3.22)

From the first step of the proof we know that $E \in L^8(0, T; L^4(\Omega))$. There can occur two different possibilities. If $4 \leq r_{k+1} < \infty$ we get by an interpolation argument $\tilde{u}, E \in L^8(0, T; L^4(\Omega))$. Otherwise, if $3 < r_{k+1} < 4$, an interpolation argument yields $E \in L^{s_{k+1}}(0, T; L^{r_{k+1}}(\Omega))$. Looking at (3.21), (3.22), we see that (3.19) and (3.20) are satisfied with the parameters $s_{k+1}, r_{k+1}, \beta_{k+1}$. Therefore, we can start a new step of this iterative argument. Repeating this step finitely many times, we get $\tilde{u} \in L^8(0, T; L^4(\Omega))$ which finishes the proof of Assertion 2. Assertion 3: Let $4 < q < \infty$. Then $\tilde{u} \in L^8(0, T; L^4(\Omega))$. *Proof.* Assume that we have for almost all $t \in [0, T[$ with certain parameters s_k, r_k, β_k

$$\tilde{u}(t) = -\int_{0}^{t} A_{r_{k}}^{\beta_{k}} e^{-\nu(t-\tau)A_{r_{k}}} A_{r_{k}}^{-\beta_{k}} P_{r_{k}} \operatorname{div}((\tilde{u}+E) \otimes (\tilde{u}+E)) d\tau, \quad (3.23)$$

$$\tilde{u}, E \in L^{s_k}(0, T; L^{r_k}(\Omega)) \text{ with } 4 < r_k < \infty, \frac{2}{s_k} + \frac{3}{r_k} = 1, \beta_k \in [\frac{1}{2}, 1].$$
(3.24)

Again, for k = 1, the iteration starts with $s_1 := s$, $r_1 := q$ and $\beta_1 := \frac{3}{2q} + \frac{1}{2} = \alpha$, see (3.14). We set $r_{k+1} := \frac{3}{4}r_k$ and $\beta_{k+1} := \frac{3}{r_k} - \frac{3}{2r_{k+1}} + \frac{1}{2} = \frac{1}{r_k} + \frac{1}{2}$. Let $s_{k+1} > 2$ be the unique element which satisfies the relation $\frac{2}{s_{k+1}} + \frac{3}{r_{k+1}} = 1$. Then (3.7) implies that \tilde{u} has the representation (3.22) with the new parameters $s_{k+1}, r_{k+1}, \beta_{k+1}$. From (3.22) we conclude with (3.8) that

$$\tilde{u} \in L^{s_{k+1}}(0,T;L^{r_{k+1}}(\Omega)).$$
 (3.25)

From the first step of the proof we know that $E \in L^8(0,T;L^4(\Omega))$. There can occur two different possibilities. If $3 < r_{k+1} \leq 4$ we get by an interpolation argument $\tilde{u}, E \in L^8(0,T;L^4(\Omega))$. Otherwise, if $4 < r_{k+1} < \infty$, we use an interpolation argument to get $E \in L^{s_{k+1}}(0,T;L^{r_{k+1}}(\Omega))$. If we look at (3.22), (3.25) we see that the equations (3.23) and (3.24) are satisfied with the parameters $s_{k+1}, r_{k+1}, \beta_{k+1}$. Therefore, we can start a new step of this iterative argument. Repeating this step finitely many times, we get $\tilde{u} \in L^8(0,T;L^4(\Omega))$ which finishes the proof of Assertion 3.

Now the claim (3.16) for $u = \tilde{u} + E$ follows, and the proof of this theorem is complete.

4. PROOF OF REGULARITY RESULTS

Before proving Theorems 1.2 and 1.3 we need a useful, but technical lemma. In this lemma we assume that u satisfies the strong energy inequality (1.5) to consider the term u(t) for almost all $t \in [0, T]$ as initial value of a local strong solution which can be identified locally with u. Therefore, the proof will be based on Theorem 1.4. We will use the notation

$$\int_{a}^{b} f(x) \, dx := \frac{1}{b-a} \int_{a}^{b} f(x) \, dx$$

for the mean value of an integral.

Lemma 4.1. Let Ω , q, s, f, u_0 , T satisfy the assumptions of Theorem 1.4, let $1 \leq s' \leq s$, and let u be a weak solution of (1.1) satisfying the strong energy inequality (1.5). Then there exists a constant $\epsilon_* = \epsilon_*(q, s', \Omega) > 0$ with the following property: If $0 < t_0 < t \leq t_1 \leq T$, and if

$$\int_{t_0}^{t_1} \|F(\tau)\|_{q*}^s \, d\tau \le \epsilon_* \nu^{2s-1} \,, \tag{4.1}$$

$$\int_{t_0}^t (t_1 - \tau)^{\frac{s'}{s}} \|u(\tau)\|_q^{s'} d\tau \le \epsilon_* \nu^{s' - \frac{s'}{s}}, \qquad (4.2)$$

then there exists a $\delta = \delta(t) > 0$ such that $u \in L^s(t - \delta, t_1; L^q(\Omega))$. In particular, if $t_1 > t$, then t is a regular point of u.

Proof. We may assume that $u(\tau) \in L^2(\Omega)$ for all $\tau \in [0, T[$. From (4.2) and the fact that u satisfies the strong energy inequality we find a null set $N \subset [t_0, t[$ such that for $\tau_0 \in]t_0, t[\setminus N$ it holds $u(\tau_0) \in L^q_{\sigma}(\Omega)$ and

$$\frac{1}{2} \|u(\tau_1)\|_2^2 + \nu \int_{\tau_0}^{\tau_1} \|\nabla u\|_2^2 d\tau \le \frac{1}{2} \|u(\tau_0)\|_2^2 - \int_{\tau_0}^{\tau_1} \langle F, \nabla u \rangle_\Omega d\tau$$
(4.3)

for all τ_1 mit $\tau_0 \leq \tau_1 < T$. Moreover, the condition (4.2) yields the existence of $\tau_0 \in]t_0, t[\setminus N$ which fulfills the inequality

$$(t_1 - \tau_0)^{\frac{s'}{s}} \|u(\tau_0)\|_q^{s'} \le \int_{t_0}^t (t_1 - \tau)^{\frac{s'}{s}} \|u(\tau)\|_q^{s'} d\tau \le \epsilon_* \nu^{s' - \frac{s'}{s}}.$$

It follows with a constant $c = c(\Omega, q) > 0$ that

$$\int_{0}^{t_{1}-\tau_{0}} \|e^{-\nu\tau A_{q}}u(\tau_{0})\|_{q}^{s} d\tau \leq \int_{0}^{t_{1}-\tau_{0}} c\|u(\tau_{0})\|_{q}^{s} d\tau$$
$$= c(t_{1}-\tau_{0})\|u(\tau_{0})\|_{q}^{s} \leq c \epsilon_{*}^{\frac{s}{s'}} \nu^{s-1}$$

Hence with a new constant $\tilde{\epsilon_*} := \left(\frac{\epsilon_*}{c}\right)^{\frac{s'}{s}}$, where ϵ_* is the constant from Theorem 1.4, the conditions of Theorem 1.4 are satisfied. We get the existence of a unique weak solution $v \in L^s([\tau_0, t_1]; L^q_{\sigma}(\Omega))$ to the Navier-Stokes system (1.1) with initial value $v(\tau_0) = u(\tau_0)$. Considering u as a weak solution to the Navier-Stokes system with initial value $u(\tau_0)$ on $[0, t_1 - \tau_0]$, we use Serrin's Uniqueness Theorem to get that $u = v \in L^s(\tau_0, t_1; L^q_{\sigma}(\Omega))$. The proof is complete.

Proof of Theorem 1.2. (1) Let $s := s', t_0 := t - \delta, t_1 := t + \delta$ where $\delta > 0$ is chosen so small that, see (1.6),

$$\begin{aligned} \int_{t-\delta}^t (t_1 - \tau) \|u(\tau)\|_q^s \, d\tau &\leq 2 \int_{t-\delta}^t \|u(\tau)\|_q^s \, d\tau \leq \epsilon_* \nu^{s-1} \\ \int_{t-\delta}^{t+\delta} \|F(\tau)\|_r^s \, d\tau \leq \epsilon_* \nu^{2s-1}. \end{aligned}$$

The assertion follows with Lemma 4.1.

(2) Because of (1.7) it is possible to choose a $\delta > 0$ such that with $t_0 := t - \delta$, $t_1 := t + \delta$ the estimate

$$\begin{aligned} \int_{t-\delta}^{t} (t_1 - \tau)^{\frac{s'}{s}} \|u(\tau)\|_q^{s'} d\tau &\leq \frac{1}{\delta} \int_{t-\delta}^{t} (2\delta)^{\frac{s'}{s}} \|u(\tau)\|_q^{s'} d\tau \\ &= \frac{2^{\frac{s'}{s}}}{\delta^{1-\frac{s'}{s}}} \int_{t-\delta}^{t} \|u(\tau)\|_q^{s'} d\tau \leq \epsilon_* \nu^{s'-\frac{s'}{s}} \end{aligned}$$

holds. This shows (4.2). Furthermore, condition (4.1) on F can be fulfilled as well. Then Lemma 4.1 proves the sufficiency of (1.7) to imply regularity of u at t. Since by Hölder's inequality

$$\frac{1}{\delta^{1-\frac{s'}{s}}} \int_{t-\delta}^{t} \|u(\tau)\|_{q}^{s'} d\tau \le \left(\int_{t-\delta}^{t} \|u(\tau)\|_{q}^{s} d\tau\right)^{\frac{s'}{s}}$$

we get that the condition (1.7) is also necessary for regularity of u at t.

(3) The constant $\epsilon_* = \epsilon_*(q, \Omega) > 0$ will be determined in the proof; therefore, we begin with considering ϵ_* as an arbitrary, fixed positive number. Let $\varepsilon_1 = \varepsilon_1(q, \Omega) > 0$ denote the constant from Theorem 1.4 which in (1.13), (1.14) is called ϵ_* , and let $\epsilon_2 = \epsilon_2(s', \Omega)$ be the constant in Lemma 1.5 called ϵ_* in (4.1), (4.2). We assume $\epsilon_* \leq \varepsilon_1$ and $u_0 \neq 0$. It holds

$$\int_0^{\delta_1} \|e^{-\nu\tau A_q} u_0\|_q^s \, d\tau \le c\delta_1 \|u_0\|_q^s, \quad c = c(\Omega, q) > 0.$$

We define

$$\delta_1 := \min\left(\frac{\varepsilon_1 \nu^{s-1}}{c \|u_0\|_q^s}, T\right). \tag{4.4}$$

If $\delta_1 = T$, we already know that $u \in L^s(0,T;L^q(\Omega))$. So let us assume that $\delta_1 = \frac{\varepsilon_1 \nu^{s-1}}{c \|u_0\|_q^s}$. With this choice of δ_1 , Theorem 1.4 yields the existence of a unique weak solution $v \in L^s(0, \delta_1; L^q(\Omega))$ of (1.1), which coincides by Serrin's Uniqueness with u on $[0, \delta_1[$. For an arbitrary $t \in [\frac{\delta_1}{2}, T - \frac{\delta_1}{2}]$, we get with $t_0 := t - \frac{\delta_1}{2}$, $t_1 := t + \frac{\delta_1}{2}$

$$\begin{aligned} \oint_{t_0}^t (t_1 - \tau)^{\frac{s'}{s}} \|u(\tau)\|_q^{s'} d\tau &\leq \frac{2}{\delta_1^{1 - \frac{s'}{s}}} \int_0^T \|u(\tau)\|_q^{s'} d\tau \\ &\leq 2 \left(\frac{\varepsilon_1 \nu^{s-1}}{c \|u_0\|_q^s}\right)^{\frac{s'}{s} - 1} \epsilon_* \frac{\nu^{s-1}}{\|u_0\|_q^{s-s'}} \\ &= 2 \left(\frac{\varepsilon_1}{c}\right)^{\frac{s'}{s} - 1} \epsilon_* \nu^{s' - \frac{s'}{s}}. \end{aligned}$$
(4.5)

From this estimate it follows that we may define

$$\epsilon_* := \min\left(\frac{\varepsilon_2}{2} \left(\frac{\varepsilon_1}{c}\right)^{1-\frac{s'}{s}}, \varepsilon_1, \varepsilon_2\right).$$
(4.6)

We see that ϵ_* depends only on Ω, q, s' . Using Lemma 4.1 we find a $\delta = \delta(t) > 0$ such that

$$u \in L^{s}(t - \delta(t), t + \frac{\delta_{1}}{2}; L^{q}(\Omega)).$$

$$(4.7)$$

With (4.7) and $u \in L^s(0, \delta_1; L^q(\Omega))$ we obtain due to the compactness of the interval [0, T] that $u \in L^s(0, T; L^q(\Omega))$.

Now the theorem is completely proved.

Proof of Theorem 1.3. By interpolation, in both cases the weak solution u satisfies $u \in L^{s'}(0, T; L^q(\Omega))$. The idea of the proof is to use Lemma 4.1. To control the term in (4.2) we use the interpolation inequality, see [1, Theorem 4.3.1],

$$\|v\|_q \le c \|v\|_2^{1-\frac{2}{s'}} \|\nabla v\|_2^{\frac{2}{s'}}, \quad v \in H^1_0(\Omega),$$

where $c = c(\Omega, q) > 0$. For $\delta \in]0, \delta_0[$ with a small $\delta_0 > 0$ we get with $t_0 := t - \delta$, $t_1 := t + \delta$ the estimate

$$I(\delta) := \int_{t-\delta}^{t} (t_1 - \tau)^{\frac{s'}{s}} \|u(\tau)\|_q^{s'} d\tau$$

$$\leq c\delta^{\frac{s'}{s} - 1} \int_{t-\delta}^{t} \left(\|u(\tau)\|_2^{1-\frac{2}{s'}} \|\nabla u(\tau)\|_2^{\frac{2}{s'}} \right)^{s'} d\tau \qquad (4.8)$$

$$\leq c\delta^{\frac{s'}{s} - 1} \|u\|_{2,\infty;T}^{s'-2} \int_{t-\delta}^{t} \|\nabla u(\tau)\|_2^2 d\tau$$

with a constant $c = c(\Omega, q) > 0$. Since u is supposed to satisfy the strong energy inequality (1.5), we may proceed for almost all $\delta \in [0, \delta_0]$ as follows:

$$I(\delta) \le \frac{c}{\nu} \,\delta^{\frac{s'}{s} - 1} \left(|E(t - \delta) - E(t)| + \left| \int_{t - \delta}^{t} \langle f, u \rangle \, d\tau \right| \right) \tag{4.9}$$

where the constant c depends on $||u||_{2,\infty;T}$ in the case $\alpha > \frac{1}{2}$ and $c = c(\Omega)$ if $\alpha = \frac{1}{2}$. By Hölder's inequality we get that

$$\left|\frac{1}{\delta^{\frac{s'}{4}}} \int_{t-\delta}^{t} \langle f(\tau), u(\tau) \rangle \, d\tau \right| \leq \|u\|_{2,\infty;T} \left(\int_{t-\delta}^{t} \|f\|_{2}^{\frac{4}{4-s'}} \, d\tau \right)^{\frac{4-s'}{4}}.$$
 (4.10)

As $\frac{s}{s'} = \frac{4}{4-s'}$ and consequently $f \in L^{\frac{4}{4-s'}}(0,T;L^2(\Omega))$, the left-hand side in the previous inequality converges to 0 as $\delta \to 0+$. First consider the case $\alpha > \frac{1}{2}$ and choose $\epsilon > 0$ with $s' = 4\alpha - \epsilon$. Due to the assumption (1.9) we get with $1 - \frac{s'}{s} = \frac{s'}{4} = \alpha - \frac{\epsilon}{4}$

$$\lim_{\delta \to 0+} \frac{c}{\nu} \,\delta^{-\frac{s'}{4}} \left| E(t-\delta) - E(t) \right| = \lim_{\delta \to 0+} \frac{c}{\nu} \,\delta^{\frac{\epsilon}{4}} \,\frac{\left| E(t-\delta) - E(t) \right|}{\delta^{\alpha}} = 0.$$
(4.11)

Consequently the right hand side of (4.9) converges to 0 as $\delta \to 0+$. Hence we can fulfill (4.2) and, due to the assumption $F \in L^{s}(0,T;L^{r}(\Omega))$, it is also possible to satisfy (4.1). Altogether, Lemma 4.1 yields regularity of u at t.

Secondly, consider the case $\alpha = \frac{1}{2}$ in which s' = 2, s = 4. We will choose the constant $\gamma_* = \gamma_*(\Omega) > 0$ below. Let $\epsilon_* = \epsilon_*(q) > 0$ denote the constant from Lemma 4.1. The assumption (1.10) implies that for all $0 < \delta < \mu$

$$\frac{1}{\nu} \frac{|E(t-\delta) - E(t)|}{\delta^{\frac{1}{2}}} \le \gamma_* \nu^{\frac{3}{2}}.$$
(4.12)

Then by (4.9), (4.10) and (4.12) we get with a constant $c = c(\Omega) > 0$ for almost all $\delta \in]0, \delta_0[$ that

$$I(\delta) \le c\gamma_*\nu^{\frac{3}{2}} + \frac{c}{\nu} \|u\|_{2,\infty;T} \left(\int_{t-\delta}^t \|f\|_2^2 \, d\tau\right)^{\frac{1}{2}}$$

Now with $\gamma_* := \frac{\epsilon_*}{2c}$ we find $0 < \delta < \mu$ such that $I(\delta) \leq \epsilon_* \nu^{\frac{3}{2}}$, cf. (4.2), and that (4.1) is satisfied. Hence Lemma 4.1 implies regularity of u at t. \Box

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